

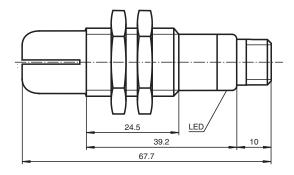
Ultrasonic sensor UB300-18GM40A-U-V1

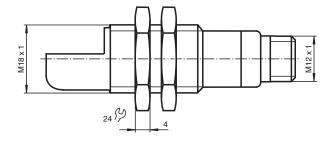
- Short design, 40 mm
- Function indicators visible from all directions
- Analog output 0 ... 10 V
- Measuring window adjustable
- Program input
- Temperature compensation

Single head system



Dimensions





Technical Data

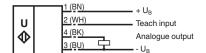
| General specifications | |
|----------------------------|--|
| Sensing range | 35 300 mm |
| Adjustment range | 50 300 mm |
| Dead band | 0 35 mm |
| Standard target plate | 100 mm x 100 mm |
| Transducer frequency | approx. 390 kHz |
| Response delay | approx. 50 ms |
| Indicators/operating means | |
| LED green | Power on |
| LED yellow | solid yellow: object in the evaluation range yellow, flashing: program function, object detected |
| LED red | solid red: Error red, flashing: program function, object not detected |

Technical Data

| Electrical specifications | | |
|--|-------|---|
| Operating voltage | U_B | 15 30 V DC , ripple 10 %ss |
| No-load supply current | I_0 | ≤ 20 mA |
| Input | | |
| Input type | | 1 program input lower evaluation limit A1: -U _B +1 V, upper evaluation limit A2: +4 V +U _B input impedance: > 4.7 k Ω , pulse duration: \geq 1 s |
| Output | | |
| Output type | | 1 analog output 0 10 V |
| Default setting | | evaluation limit A1: 50 mm evaluation limit A2: 300 mm |
| Resolution | | 0.4 mm at max. sensing range |
| Deviation of the characteristic curve | | ± 1 % of full-scale value |
| Repeat accuracy | | ± 0.5 % of full-scale value |
| Load impedance | | > 1 kOhm |
| Temperature influence | | ± 1.5 % of full-scale value |
| Compliance with standards and directives | | |
| Standard conformity | | |
| Standards | | EN IEC 60947-5-2:2020 IEC 60947-5-2:2019 EN 60947-5-7:2003 IEC 60947-5-7:2003 |
| Approvals and certificates | | |
| UL approval | | cULus Listed, Class 2 Power Source |
| CCC approval | | CCC approval / marking not required for products rated ≤36 V |
| Ambient conditions | | |
| Ambient temperature | | -25 70 °C (-13 158 °F) |
| Storage temperature | | -40 85 °C (-40 185 °F) |
| Mechanical specifications | | |
| Connection type | | Connector plug M12 x 1 , 4-pin |
| Degree of protection | | IP67 |
| Material | | |
| Housing | | brass, nickel-plated |
| Transducer | | epoxy resin/hollow glass sphere mixture; foam polyurethane, cover PBT |
| Mass | | 25 g |
| Dimensions | | |
| Length | | 40 mm |
| Diameter | | 18 mm |

Connection Assignment

Standard symbol/Connections: (version U)



Core colours in accordance with EN 60947-5-2.

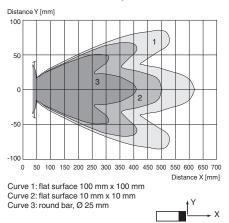


Wire colors in accordance with EN 60947-5-2

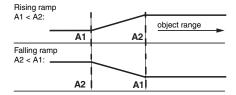
| 1 | BN | (brown) |
|---|----|---------|
| 2 | WH | (white) |
| 3 | BU | (blue) |
| 4 | BK | (black) |

Characteristic Curve

Characteristic response curve



Programming the analog output mode



Programming

The sensor features a programmable analog output with two programmable evaluation boundaries. Programming the evaluation boundaries and the operating mode is done by applying the supply voltage $-U_B$ to the Teach-In input. The supply voltage must be applied to the Teach-In input for at least 1 s. LEDs indicate whether the sensor has recognized the target during the programming procedure.

Note:

Release date: 2025-05-16 Date of issue: 2025-05-16 Filename: 220355_eng.pdf

Evaluation boundaries may only be specified directly after Power on. A time lock secures the adjusted switching points against unintended modification 5 minutes after Power on. To modify the evaluation boundaries later, the user may specify the desired values only after a new Power On.

Note:

If a programming adapter UB-PROG2 is used for the programming procedure, button A1 is assigned to -U_B and button A2 is assigned to +U_B.

Programming

Programming the analog output

Rising ramp

- 1. Place the target at the near end of the desired evaluation range
- 2. Program the evaluation boundary by applying -U_B to the Teach-In input (yellow LED flashes)
- 3. Disconnect the Teach-In input from -U_B to save the evaluation boundary
- 4. Place the target at the far end of the desired evaluation range
- 5. Program the evaluation boundary by applying +U_B to the Teach-In input (yellow LED flashes)
- 6. Disconnect the Teach-In input from $+U_B$ to save the evaluation boundary

Falling ramp

- 1. Place the target at the far end of the desired evaluation range
- 2. Program the evaluation boundary by applying -U_B to the Teach-In input (yellow LED flashes)
- 3. Disconnect the Teach-In input from -U_B to save the evaluation boundary
- 4. Place the target at the near end of the desired evaluation range
- 5. Program the evaluation boundary by applying $+U_B$ to the Teach-In input (yellow LED flashes)
- 6. Disconnect the Teach-In input from +U_B to save the evaluation boundary