

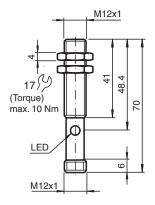
# Ultrasonic sensor UB120-12GM-I-V1

- Extremely narrow projection cone
- Analog output 4 mA ... 20 mA
- Very small unusable area
- Measuring window adjustable
- Short response time

### Single head system



## **Dimensions**



## **Technical Data**

**General specifications** 

Sensing range		15 120 mm
Adjustment range		20 120 mm
Dead band		0 15 mm
Standard target plate		10 mm x 10 mm
Transducer frequency		approx. 850 kHz
Response delay		approx. 27 ms
Indicators/operating means		
LED yellow		solid yellow: object in the evaluation range yellow, flashing: program function, object detected
LED red		solid red: Error red, flashing: program function, object not detected
Electrical specifications		
Operating voltage	$U_B$	10 30 V DC , ripple 10 % <sub>SS</sub>
No-load supply current	$I_0$	≤ 30 mA
Input		
Input type		1 program input lower evaluation limit A1: -U <sub>B</sub> +1 V, upper evaluation limit A2: +4 V +U <sub>B</sub> input impedance: > 4.7 k $\Omega$ , pulse duration: $\geq$ 1 s
Output		
Output type		1 analog output 4 20 mA

Resolution	0.17 mm
Deviation of the characteristic curve	± 1 % of full-scale value
Repeat accuracy	± 0.5 % of full-scale value
Load impedance	0 300 Ohm
Temperature influence	± 1.5 % of full-scale value
Compliance with standards and directives	
Standard conformity	
Standards	EN IEC 60947-5-2:2020 IEC 60947-5-2:2019 EN 60947-5-7:2003 IEC 60947-5-7:2003
Approvals and certificates	
UL approval	cULus Listed, Class 2 Power Source
CCC approval	CCC approval / marking not required for products rated ≤36 V
Ambient conditions	
Ambient temperature	-25 70 °C (-13 158 °F)
Storage temperature	-40 85 °C (-40 185 °F)
Mechanical specifications	
Connection type	Connector plug M12 x 1 , 4-pin
Degree of protection	IP67
Material	
Housing	brass, nickel-plated
Transducer	epoxy resin/hollow glass sphere mixture; foam polyurethane, cover PBT
Mass	25 g
Dimensions	
Length	70 mm
Diameter	12 mm

## **Connection Assignment**

Standard symbol/Connections: (version I)

1 (BN) + U<sub>B</sub>
2 (WH) Teach input
4 (BK) Analogue output
3 (BU) - U<sub>B</sub>

Core colours in accordance with EN 60947-5-2.

## **Connection Assignment**



Ultrasonic sensor UB120-12GM-I-V1

## **Connection Assignment**

Wire colors in accordance with EN 60947-5-2

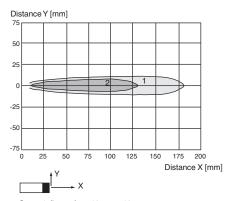
1 BN (brown)
2 WH (white)
3 BU (blue)
4 BK (black)

#### **Installation Conditions**

If the sensor is installed at places where the environment temperature can fall below 0 °C, for the sensors fixation, one of the mounting flanges BF 12, BF 12-F or BF 5-30 must be used. In case of direct mounting of the sensor in a through hole, it has to be fixed at the middle of the housing thread

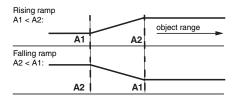
#### **Characteristic Curve**

#### Characteristic response curve



Curve 1: flat surface 10 mm x 10 mm

#### Programming the analog output mode



### **Programming**

The sensor features a programmable analog output with two programmable evaluation boundaries. Programming the evaluation boundaries and the operating mode is done by applying the supply voltage  $-U_B$  or  $+U_B$  to the Teach-In input. The supply voltage must be applied to the Teach-In input for at least 1 s. LEDs indicate whether the sensor has recognized the target during the programming procedure.

#### Note:

Evaluation boundaries may only be specified directly after Power on. A time lock secures the adjusted switching points against unintended modification 5 minutes after Power on. To modify the evaluation boundaries later, the user may specify the desired values only after a new Power On.

#### Note:

If a programming adapter UB-PROG2 is used for the programming procedure, button A1 is assigned to -U<sub>B</sub> and button A2 is assigned to +U<sub>B</sub>.

# Programming the analog output Rising ramp

- Place the target at the near end of the desired evaluation range
- 2. Program the evaluation boundary by applying  $-U_B$  to the Teach-In input (yellow LED flashes)

- 3. Disconnect the Teach-In input from -U<sub>B</sub> to save the evaluation boundary
- 4. Place the target at the far end of the desired evaluation range
- 5. Program the evaluation boundary by applying +U<sub>B</sub> to the Teach-In input (yellow LED flashes)
- 6. Disconnect the Teach-In input from +U<sub>B</sub> to save the evaluation boundary

- Falling ramp

  1. Place the target at the far end of the desired evaluation range
- 2. Program the evaluation boundary by applying -U<sub>B</sub> to the Teach-In input (yellow LED flashes)
- 3. Disconnect the Teach-In input from - $U_B$  to save the evaluation boundary
- 4. Place the target at the near end of the desired evaluation range
- 5. Program the evaluation boundary by applying  $+U_B$  to the Teach-In input (yellow LED flashes)
- 6. Disconnect the Teach-In input from +U<sub>B</sub> to save the evaluation boundary