

# **Insulation Resistance Monitoring Device**

# **K7GE-MG**

# Reliable, Safe and Accurate Automatic Insulation Resistance Measurements

- Measures insulation resistance automatically when a trigger signal is input
- Identifies the trend in insulation deterioration from the measurement data collected via communications
- Conducts measurements safely with a Megger voltage of 50 VDC
- · Able to measure up to eight points simultaneously
- Constantly monitors the voltage applied to the device targeted for measurement, and automatically stops measurement if the target device power is turned ON after measurement has started





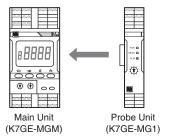
Refer to your OMRON website for the most recent information on applicable safety standards.

#### **Overview**

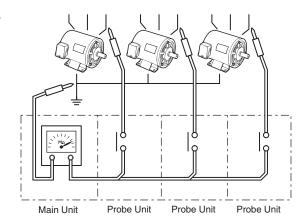
The K7GE-MG is a device that automatically measures the insulation resistance of a load and supports trend monitoring. Periodic inspections by manpower may cause a unexpected machine stoppage due to a decrease in insulation resistance of equipment before the next inspection. The K7GE-MG provides automatic monitoring of the insulation resistance of each load and allows planned maintenance.

The K7GE-MG measures the insulation resistance by the same detection principle (Megger method) as a Megohmmeter.

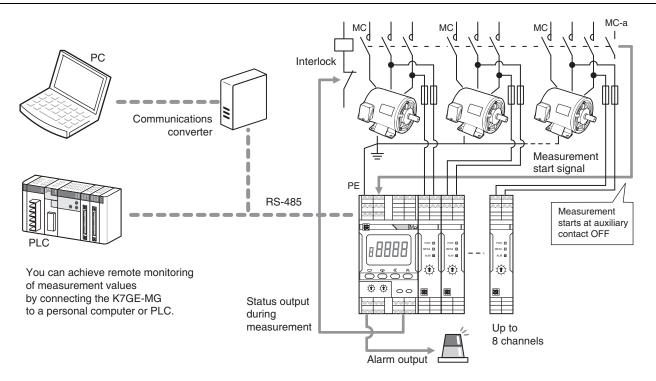
To measure the insulation resistance using the K7GE-MG, it is necessary to combine one Main Unit with at least one Probe Unit.



The functions of the Main Unit and Probe Unit are shown in the figure on the right. The Main Unit correspond to a Megohmmeter, and the Probe Unit correspond to a measurement probe with internal contacts. The Main Unit turns ON these contacts in sequence and measure multiple loads individually. Up to eight Probe Units can be connected to one Main Unit.



# **System Configuration**

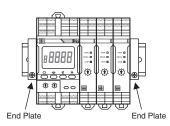


# **Ordering Information**

	Unit	Power supply voltage	Model
Main Unit		100 to 240 VAC	K7GE-MGMA
	T 999	24 VAC/VDC	K7GE-MGMD
Probe Unit			K7GE-MG1

### **Accessories (Order Separately)**

DIN Tracks	Model
	PFP-100N
	PFP-50N
End Plate	Model
5	PFP-M



End Plates must be mounted at both ends to prevent contact failure between the Units due to vibration and shock.

# **Ratings and Specifications**

Item		Specifications		
Power supply voltage and frequency		K7GE-MGMA: 100 to 240 VAC, 50/60 Hz K7GE-MGMD: 24 VAC, 50/60 Hz, 24 VDC		
Operating voltage range		85% to 110% of the rated voltage		
Operating frequency range		45 to 65 Hz		
Power consumption		Maximum Unit configuration: one Main Unit and eight Probe Units 12.9 VA max. (100 to 240 VAC)/7.8 VA max. (24 VAC)/4.7 W max. (24 VDC) Minimum Unit configuration: one Main Unit and one Probe Unit 8.4 VA max. (100 to 240 VAC)/4.6 VA max. (24 VAC)/2.5 W max. (24 VDC)		
Ambient	operating temperature	-10 to 55°C (with no condensation or icing)		
Ambient	operating humidity	25% to 85% (with no condensation)		
Storage	temperature	-20 to 65°C		
Altitude	·	2,000 m max.		
Recomm	nended fuse	T2A, time delay, high-breaking capacity (for Main Unit operating power supply) Tripping current: 7 A max., fast-blow (for Probe Unit voltage input)		
Insulation resistance		20 $M\Omega$ min.  Between all external terminals and the case, between all power supply terminals and all other terminals, between PE terminal, and trigger input terminal, all communications terminals and all transistor output terminals  1,000 $M\Omega$ min.  Between Probe Unit voltage monitoring terminal and PE terminal		
Dielectric strength		2,000 VAC for 1 minute Between all external terminals and the case, between all power supply terminals and all other terminals, between PE terminal, and trigger input terminal, all communications terminals and all transistor output terminals 1,000 VDC for 1 minute Between Probe Unit voltage monitoring terminal and PE terminal		
Vibration	resistance	Frequency: 10 to 55 Hz, 0.35-mm single amplitude, acceleration 50 m/s², 10 sweeps of 5 min each in X, Y, and Z directions		
Shock re	esistance	100 m/s², 3 times each in X, Y, and Z axes, 6 directions		
Degree o	of protection	IP20		
Terminal	block type	Push-In Plus		
Exterior	color	Black (Munsell N 1.5)		
Mounting	3	DIN Track mounting		
Weight		Main Unit: Approx. 156 g Probe Unit: Approx. 63 g		
Installation environment		Operation power supply: EN/IEC 61010-1 Over-voltage category II Pollution degree 2 Measurement circuit: EN/IEC 61010-2-030 Pollution degree 2 For details about the measurement category, refer to Conformance to Safety Standards on page 17		
Electromagnetic environment		EN/IEC 61326-1 Industrial electromagnetic environment		
Safety standards		UL 61010-1, CAN/CSA-C22.2 No.61010-1 Korean Radio Waves Act (KN 61000-6-2 and KN 11) RCM		
Wiring material	Wire type	Solid wire or stranded wire		
	Wiring material	Copper		
	Recommended wire	0.25 to 1.5 mm <sup>2</sup> AWG 24 to AWG 16		
	Stripping length Without ferrules	8 mm		

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### **K7GE-MG**

# **Measurement Specifications**

Item	Specifications		
Measurement range	0.1 to 99.9 M $\Omega$ (0.0 M $\Omega$ for less than 0.1 M $\Omega$ )		
Measuring accuracy	±5% rdg. ±1 digit (at ambient temperature -10 to 55°C and ambient humidity 25% to 65%)		
Megger voltage	50 VDC		
Measurement operation	eration Perform one measurement operation for each trigger. One-shot trigger.		
Average count	Disabled (1 time)/Enabled (8 times)		
Measurement target	Single-phase/3-phase AC induction motors An inverter-driven motor requires a contactor on the secondary coil of the inverter. Similarly, a servo motor requires a contactor on the secondary coil of the Servo Drive. A motor with a star delta starter requires a delta connection or a star connection for measurement. Also able to measure DC motors.		

# **Input Specifications of Trigger Input Terminals**

Item	Specifications	
Input type	No-voltage contact and open collector are possible.	
Residual voltage at short circuit	1.5 V max.	
Open leakage current	0.1 mA max.	
ON current at short circuit	Approx. 7 mA	
Minimum detection time	Received as a valid continuous input for at least 50 ms for both ON and OFF.	

# **Output Specifications of Transistor Output Terminals**

Item	Specifications		
Contact form	NPN open collector		
Rated voltage	24 VDC (maximum voltage: 26.4 VDC)		
Maximum current	50 mA		
Leakage current when power turning OFF	0.1 mA max.		
Residual voltage	1.5 V max.		

# **Input Specifications of Voltage Input Terminals**

Item	Specifications	
System voltage (All are specified as line voltage)	AC waveform: <single-phase, 2-wire,="" ground="" n-phase=""> Sine waveform: 100 to 600 VAC, -15% to 10%, 50/60±5 Hz Thyristor waveform: 100 to 600 VAC, -15% to 10%, 50/60±5 Hz (0° to 150° dia.) Inverter waveform: 100 to 600 VAC, -15% to 10%, 20 to 85 Hz &lt;3-phase, 3-wire, S-phase ground&gt; Sine waveform: 100 to 480 VAC, -15% to 10%, 50/60±5 Hz Thyristor waveform: 100 to 480 VAC, -15% to 10%, 50/60±5 Hz (0° to 150° dia.) Inverter waveform: 100 to 480 VAC, -15% to 10%, 20 to 85 Hz &lt;3-phase, 4-wire, N-phase ground&gt; Sine waveform: 100 to 600 VAC, -15% to 10%, 50/60±5 Hz (0° to 150° dia.) Inverter waveform: 100 to 600 VAC, -15% to 10%, 50/60±5 Hz (0° to 150° dia.) Inverter waveform: 100 to 600 VAC, -15% to 10%, 20 to 85 Hz  DC waveform: 24 to 480 VDC, -15% to 10%</single-phase,>	

# **Communications Specifications**

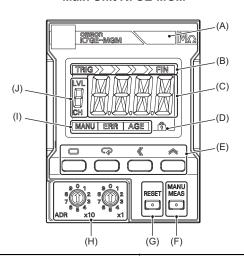
Item	Specifications	
Physical layer	RS-485	
Transmission path connection method	RS-485: Multidrop	
Communications method	RS-485 (2-wire, half duplex)	
Synchronization method	Asynchronous	
Connection configurations	Master and Slave configurations are 1:1 or 1:N connections.	
Maximum number of Units	32 (including one host system)	
Cable length	Total 500 m max. (twisted-pair cable)	
Baud rate	9.6, 19.2, 38.4 or 57.6 kbps	
Data length	7/8 bits	
Stop bits	1/2 bits	
Error detection	Vertical parity (none/even/odd) BCC (with CompoWay/F selected), CRC-16 (with Modbus RTU selected)	
Flow control	None	
Retry function	None	
Buffer	97 bytes	
Send wait time	0 to 99 ms	
Protocol	CompoWay/F and Modbus RTU	

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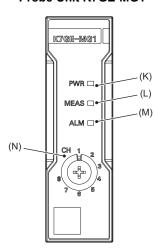
### **Nomenclature**

### **Front Section**

#### Main Unit K7GE-MGM



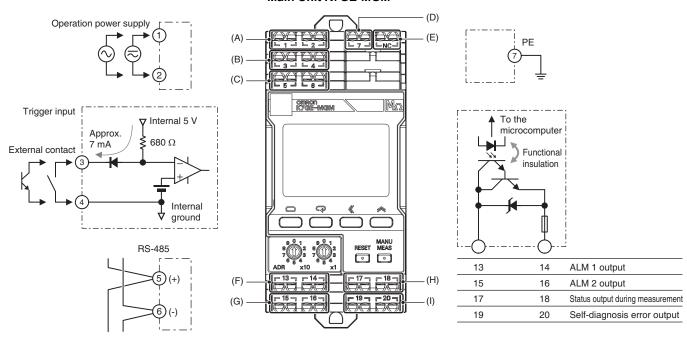
#### Probe Unit K7GE-MG1



Symbol	Name	Operation		
(A)	Alarm output indicator	Displays the alarm judgment results of automatic measurement in three colors.  Green: Normal, Yellow: Warning (Alarm 1 occurrence), Red: Critical (Alarm 2 occurrence)  If the status is different across multiple channels, the display color is decided in the priority order of red (critical) > yellow (warning) > green (normal).		
(B)	Measurement step indicator	The automatic measurement operation consists of several steps. This indicator shows the progress of the step from the start to the end of the measurement.		
(C)	Main display	The following contents are displayed in the operating status of the Main Unit.  Measuring operation:  The remaining seconds until the measurement completes are counted down  After measurement completed:  The insulation resistance measurement value, or characters indicating measurement failure  Setting level: The setting parameter name, or setting value  Error occurs: The characters indicating the error status		
(D)	Protect indicator	Indicates that the protect function of the setting parameter is set.		
		Level Key ( ): Selects the setting level.		
(E)	Operation keys	Mode Key ( ): Selects the setting parameter of the Initial Setting Level and Communications Setting Level.  Displays the measurement value of each channel at the Operation Level. Also used to select between enabling/disabling of measurement value display automatic scroll.		
		Shift Key ( <b>《</b> ): Sets the parameter value to a changeable state. Used for digit shift in the changeable state.		
		Up Key (♠): Increments the value when the parameter is in a changeable state.		
(F)	Manual Measurement Key	Selects to start or end manual measurement. Manual measurement is used to check the operation when the system is started up. Automatic measurement requires a trigger signal to start measurement, but manual measurement does not require a trigger signal. You can use manual measurement in the same way as a Megohmmeter.		
(G)	Reset Key	Selects to return to the power reset status. Even if the measuring operation is in progress, priority is given to the Reset Key, and measurement stops to return to the power reset status. The Reset Key is enabled only in the Operation Level.		
(H)	Unit Number Setting Switch	Sets the unit number during communications.		
(I)	Status display	MANU: Indicates the manual measurement state. ERR: Indicates that a system error occurred. AGE: Indicates that it is time to replace the Main Unit (guideline).		
(J)	LVL/CH display	Displays the level, or the value of the channel number.  LVL: Indicates that the value displayed in the LVL/CH display is the "Level".  CH: Indicates that the value displayed in the LVL/CH display is the "Channel".		
(K)	PWR indicator (green)	Indicates that the Probe Unit power is ON.		
(L)	MEAS indicator (green)	Indicates that measurement is in progress for the load connected to the Probe Unit.		
(M)	ALM indicator (red)	Indicates that an alarm occurred in the load connected to the Probe Unit.		
(N)	Channel Number Setting Switch	Sets a unique channel number for each Unit when multiple Probe Units are added.		

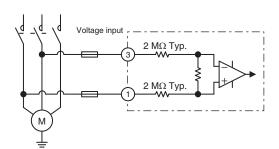
### **Terminal Section**

#### Main Unit K7GE-MGM

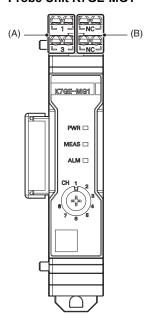


Symbol	Terminal Number	Name	Operation	
(A)	1 and 2	Operation power supply	Connect the operation power supply to the Main Unit.	
(B)	3 and 4	Trigger input	Input terminals of the external contact from where a trigger signal is applied.  No. 3: Collector of the NPN transistor, No. 4: Emitter of the NPN transistor	
(C)	5 and 6	RS-485	Connect the RS-485 communications line. No. 5: +, No. 6: -	
(D)	7	PE	A protective earthing terminal.	
(E)	NC	NC	Do not connect anything to this terminal.	
(F)	13 and 14	ALM 1 output	Compares the measurement value and alarm value 1, and outputs an alarm. No. 13: Collector of the NPN transistor, No. 14: Emitter of the NPN transistor	
(G)	15 and 16	ALM 2 output	Compares the measurement value and alarm value 2, and outputs an alarm. No. 15: Collector of the NPN transistor, No. 16: Emitter of the NPN transistor	
(H)	17 and 18	Status output during measurement	Provides notification that measurement is in progress. The output is normally open (OFF). You can use this output to design an interlock circuit to prevent accidental restart of the load during measurement operation.  No. 17: Collector of the NPN transistor, No. 18: Emitter of the NPN transistor	
(I)	19 and 20	Self-diagnosis error output	Provides notification about system error in the Main Unit. The output is normally closed (ON). No. 19: Collector of the NPN transistor, No. 20: Emitter of the NPN transistor	

## **Terminal Section**



### Probe Unit K7GE-MG1



Symbol	Terminal Number	Name	Operation
(A)	1 and 3	Voltage input	Connect the load terminals.  No. 1: Connect the R-phase in a 3-phase system, and the L-phase in a single-phase system No. 3: Connect the S-phase in a 3-phase system, and the N-phase in a single-phase system Use the No. 1 terminal to discharge the electric charge and apply the Megger voltage.
(B)	NC	NC	Do not connect anything to this terminal.

### **Connection Diagram**

# When the Load Is a Single-Phase/3-Phase Induction Motor (Direct Connection to Commercial Power Supply)

Install a contactor between the power line and the motor.



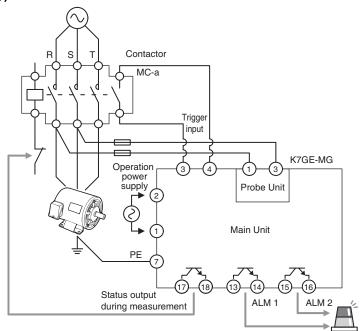
Do not connect any other device such as a transformer or a filter between the contactor and the motor. Doing so may cause incorrect measurement.

Connect the voltage input of the Probe Unit of the K7GE-MG to the secondary output terminal (motor side) of the contactor.



Make sure that it is not connected to the primary side (power supply side). It cannot be measured correctly and may cause a hazardous condition.

The figure shows a simplified view of the wiring for status output during measurement, and ALM 1 and ALM 2 outputs. Use an appropriate relay for relaying in consideration of the switching capacity of the output transistor. The specifications of the output transistor for the K7GE-MG are 24 VDC (+10%), 50 mA



#### When the Load Is an Inverter-Driven Motor

Install a contactor between the inverter output and the motor. If a noise filter is to be inserted at the output side of the inverter, insert it between the inverter output and the primary output terminal of the contactor.



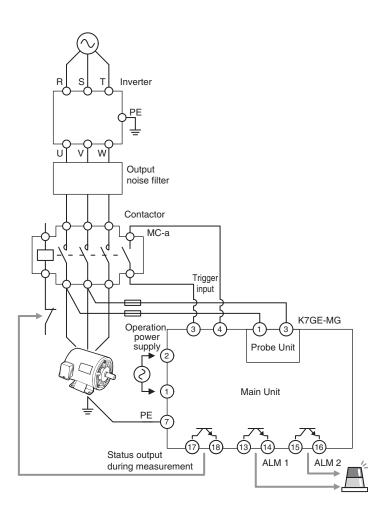
Do not connect any other device such as a transformer or a filter between the contactor and the motor. Doing so may cause incorrect measurement.

Connect the voltage input of the Probe Unit of the K7GE-MG to the secondary output terminal (motor side) of the contactor.



Make sure that it is not connected to the primary side (power supply side). It cannot be measured correctly and may cause a hazardous condition.

The figure shows a simplified view of the wiring for status output during measurement, and ALM 1 and ALM 2 outputs. Use an appropriate relay for relaying in consideration of the switching capacity of the output transistor. The specifications of the output transistor for the K7GE-MG are 24 VDC (+10%), 50 mA max.



#### When the Load Is a Servo Motor

Install a contactor between the Servo Drive output and the motor.

The contactor is required only in the power line. Relays the motor power cables other than the power line to the terminal blocks and connect it to the Servo Drive directly.

Connect the voltage input of the Probe Unit of the K7GE-MG to the secondary output terminal (motor side) of the contactor.

Turn the contactor ON and OFF when the Servo Drive power is OFF.



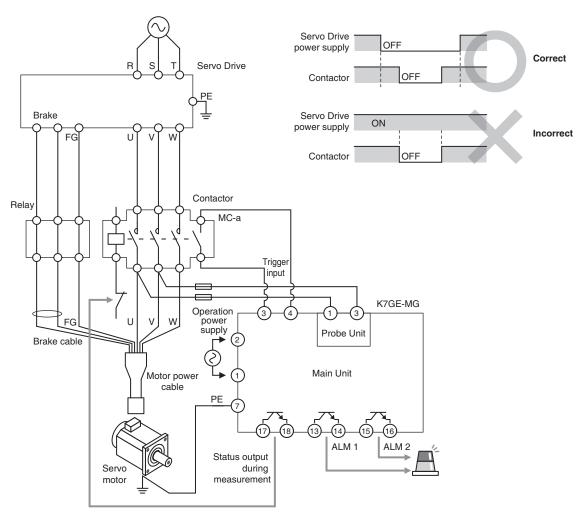
Do not connect any other device such as a transformer or a filter between the contactor and the motor. Doing so may cause incorrect measurement.



Make sure that it is not connected to the primary side (power supply side). It cannot be measured correctly and may cause a hazardous condition.



If the contactor is turned OFF while the Servo Drive is turned ON, the rotating shaft of the motor will be in a free. If the contactor is turned on after that, the motor may perform unintended operation and can be dangerous.



The figure shows a simplified view of the wiring for status output during measurement, and ALM 1 and ALM 2 outputs. Use an appropriate relay for relaying in consideration of the switching capacity of the output transistor. The specifications of the output transistor for the K7GE-MG are 24 VDC (+10%), 50 mA max.

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### Cases Where Insulation Resistance is Measured Without Disconnecting Motors

In order to accurately measure insulation resistance of a motor using a Megohmmeter, motors must be disconnected from power lines and then a Megger voltage must be applied to them individually. In practice, however, it is time-consuming to disconnect and reconnect power lines, and insulation resistance values, in some cases, are measured without disconnecting wiring, because they are useful for time-trend monitoring even if they are not accurate.

Below is a description of connection methods for automatically measuring insulation resistance by replacing a Megohmmeter with the K7GE-MG without disconnecting wiring.

For safety reasons and to obtain accurate measurement values, each individual motor is considered to have one contactor installed. Accordingly, OMRON does not recommend the following connection methods to be used.

#### When the Load Is a 3-phase Induction Motor (not recommended)

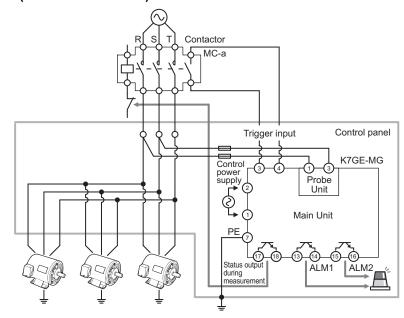
For a case where multiple motors are turned ON and OFF by a single contactor, connect the voltage input of the Probe Unit of the K7GE-MG to the secondary output terminal of the contactor.

The figure shows a simplified view of the wiring for the "status output during measurement" terminal, and ALM 1 and ALM 2 outputs. Use an appropriate relay for relaying in consideration of the switching capacity of the output transistor.

The specifications of the output transistor for the K7GE-MG are 24 VDC (+10%), 50 mA max.



The system must be designed not to turn power lines ON while the K7GE-MG is measuring. The "status output during measurement" terminal can be used to check whether the K7GE-MG is measuring or not.



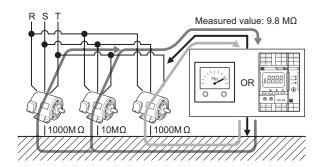
#### Reasons for non-recommendation

If a contactor is not used for each motor, an accurate measurement will not be possible because a Megger voltage is applied not only to the motor being measured but also to other motors at the same time.

The figure shows an example in which the insulation resistance of one of the three motors has dropped to 10 M $\Omega$ . Even though the right-most motor is supposed to be measured, the measured value is 9.8 M $\Omega$  which is the parallel resistance of three motors (1000 M $\Omega$ , 10 M $\Omega$  and 1000 M $\Omega$ ).



This problem is not specific to the K7GE-MG. It also occurs in measurements using conventional Megohmmeters.



If you wish to use this connection for time-trend monitoring, ensure that you fully understand *Reasons for non-recommendation* described above before using it.

#### When the Load Is an Inverter-driven Motor (not recommended)

Connect the voltage input of the Probe Unit of the K7GE-MG to the secondary output terminal of the inverter.

If a contactor is not used on the secondary coil of the inverter, the auxiliary contact cannot be used.

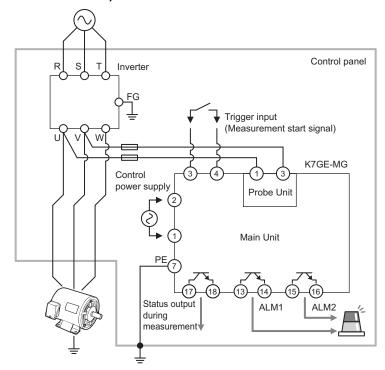
In that case, a separate contact for the timing of measurement start is required at the trigger input terminal.

The figure shows a simplified view of the wiring for the "status output during measurement" terminal, and ALM 1 and ALM 2 outputs. Use an appropriate relay for relaying in consideration of the switching capacity of the output transistor.

The specifications of the output transistor for the K7GE-MG are 24 VDC (+10%), 50 mA max.



The system must be designed not to turn power lines ON while the K7GE-MG is measuring. The "status output during measurement" terminal can be used to check whether the K7GE-MG is measuring or not.



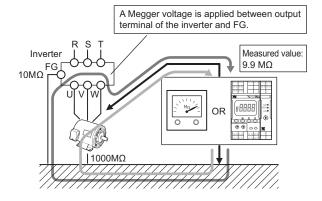
#### Reasons for non-recommendation

If a contactor is not used on the secondary coil of the inverter, a Megger voltage will be applied between the output terminal of the inverter and FG. Due to such unexpected voltage application, OMRON cannot guarantee that the output circuit of the inverter can work without failure or malfunction.

Before using such an inverter, confirm with its manufacturer to make sure there are no problems with application of a Megger voltage. The Megger voltage of the K7GE-MG is 50 VDC.



This problem is not specific to the K7GE-MG. It also occurs in measurements using conventional Megohmmeters.



Note that even if the output circuit of the inverter can be used without problems, accurate measurements cannot be made because a Megger voltage is simultaneously applied to the inverter as well as to the motor to be measured.

The figure shows an example in which the insulation resistance of the motor is 1000 M $\Omega$  and of the inverter is 10 M $\Omega$ . Even though only the motor is supposed to be measured, the measured value is 9.9 M $\Omega$  which is the parallel resistance of the inverter (10 M $\Omega$ ) and motor (1000 M $\Omega$ ).



This problem is not specific to the K7GE-MG. It also occurs in measurements using conventional Megohmmeters.

If you wish to use this connection for time-trend monitoring, ensure that you fully understand *Reasons for non-recommendation* described above before using it.

#### When the Load Is a Servo Motor (not recommended)

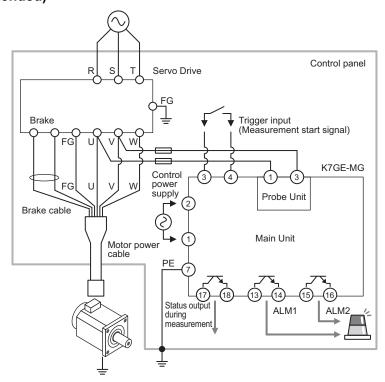
Connect the voltage input of the Probe Unit of the K7GE-MG to the output terminal of the Servo Drive.

If a contactor is not used on the secondary coil of the Servo Drive., the auxiliary contact cannot be used. In that case, a separate contact for the timing of measurement start is required at the trigger input terminal.

The figure shows a simplified view of the wiring for the "status output during measurement" terminal, and ALM 1 and ALM 2 outputs. Use an appropriate relay for relaying in consideration of the switching capacity of the output transistor. The specifications of the output transistor for the K7GE-MG are 24 VDC (+10%), 50 mA max.



The system must be designed not to turn power lines ON while the K7GE-MG is measuring. The "status output during measurement" terminal can be used to check whether the K7GE-MG is measuring or not.



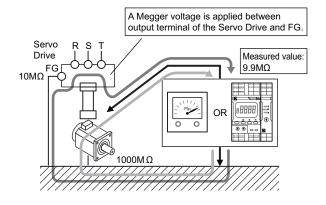
#### Reasons for non-recommendation

If a contactor is not used on the secondary coil of the Servo Drive, a Megger voltage will be applied between the output terminal of the Servo Drive and FG. Due to such unexpected voltage application, OMRON cannot guarantee that the output circuit of the Servo Drive can work without failure or malfunction.

Before using such a Servo Drive, confirm with its manufacturer to make sure there are no problems with application of a Megger voltage. The Megger voltage of the K7GE-MG is 50 VDC.



This problem is not specific to the K7GE-MG. It also occurs in measurements using conventional Megohmmeters.



Note that even if the output circuit of the Servo Drive can be used without problems, accurate measurements cannot be made because a Megger voltage is simultaneously applied to the Servo Drive as well as to the motor to be measured.

The figure shows an example in which the insulation resistance of the motor is 1000 M $\Omega$  and of the Servo Drive is 10 M $\Omega$ . Even though only the motor is supposed to be measured, the measured value is 9.9 M $\Omega$  which is the parallel resistance of the Servo Drive (10 M $\Omega$ ) and motor (1000 M $\Omega$ ).



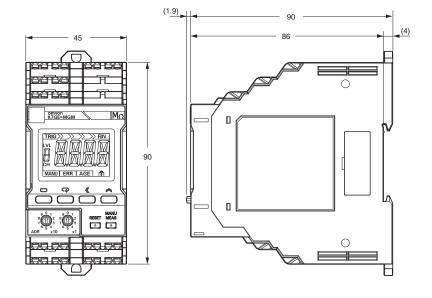
This problem is not specific to the K7GE-MG. It also occurs in measurements using conventional Megohmmeters.

If you wish to use this connection for time-trend monitoring, ensure that you fully understand *Reasons for non-recommendation* described above before using it.

Dimensions (Unit: mm)

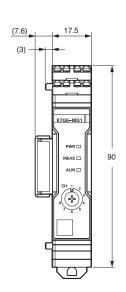
#### Main Unit K7GE-MGM

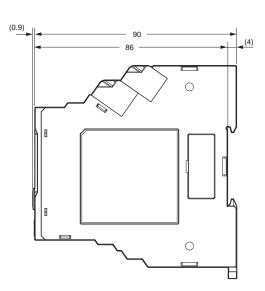




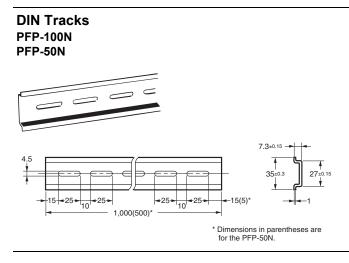
# Probe Unit K7GE-MG1

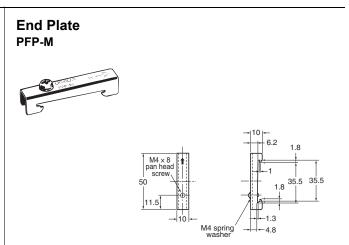




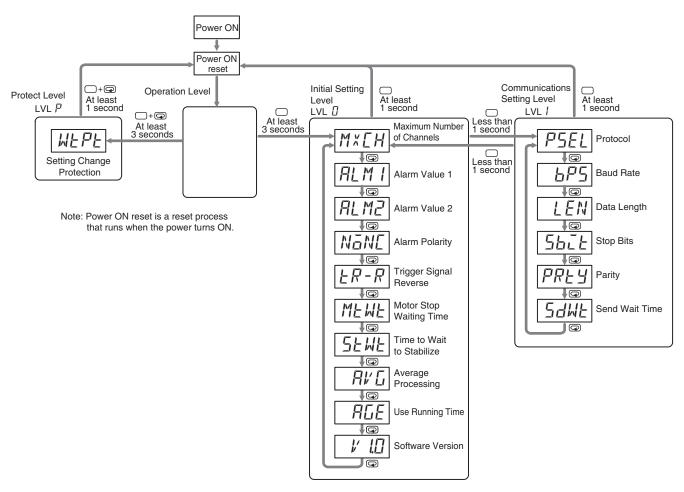


### **Optional Products for DIN Track Mounting**





### **Setting Parameter Flow**



Level	Parameter name	Characters	Setting range	Description
Protect	Setting Change Protection	WEPE	OFF/ON	Use key operations to change the setting value, <b>Enabled</b> /Disabled
	Maximum Number of Channels	М×ЕН	<u>1</u> to 8	Total number of channels, default value: 1
	Alarm Value 1	ALM I	0.0 to 99.9 MΩ	Alarm threshold value (warning), default value: 20.0
	Alarm Value 2	ALM2	0.0 to 99.9 MΩ	Alarm threshold value (critical), default value: 1.0
	Alarm Polarity	Nane	n-o/ <u>n-c</u>	Alarm output polarity, Normally open/Normally close
la Wal Cawin a	Trigger Signal Reverse	ŁR-R	OFF/ON	Start measurement when trigger contact input is OFF/ Start measurement when trigger contact input is ON
Initial Setting	Motor Stop Waiting Time	MEWE	0 to 299 s	Time from trigger input to load stopping, default value: 10
	Time to Wait to Stabilize	SEWE	0 to 99 s	Time for the measurement value to stabilize after the Megger voltage is applied, default value: <u>60</u>
	Average Processing	RV G	OFF/ON	Average processing of measurement values, None/Yes
	Use Running Time	RGE	OFF/ON	Running time estimation function, Not used/Used
	Software Version	V LO	-	Displays the software version of the K7GE-MG.  * The version number depends on the current software version.
	Protocol	PSEL	CWF/MOD	Protocol selection, CompoWay/F / Modbus RTU
	Baud Rate	bP5	<u>9.6</u> /19.2/38.4/57.6 kbps	Baud rate, default value: 9.6
Communications Setting	Data Length	LEN	<u>7</u> /8 bits	Data length, default value: 7
	Stop Bits	Sbīt	1/ <u>2</u> bits	Stop bits, default value: 2
	Parity	PRES	NONE/ <u>EVEN</u> /ODD	Parity, default value: <b>EVEN</b>
	Send Wait Time	SdWE	0 to 99 ms	Response wait time from the host, default value: 20

Note: Bold text values indicate default settings.

#### K7GE-MG

### **Condition Monitoring Configuration Tool**

Starting in February 2024, OMRON releases a software tool for configuring all models of condition monitoring devices. The unified configuration and verification environment of the software tool makes it easy to introduce condition monitoring devices. While the existing tools for condition monitoring devices will remain functional, be advised that OMRON has no plans to provide support for updates or related services. Going forward, use the Condition Monitoring Configuration Tool instead of the existing tools.

Product name	Model	Software Tool	The last day to download the tools		The new Tool will be available from February 2024 onwards
Motor Condition Monitoring Device	K6CM *1	Motor Condition Monitoring Tool *2	30 November, 2024	_	Condition Monitoring Configuration Tool
Thermal Condition Monitoring Device	К6РМ-ТН	K6PM-TH Software Tool			
Insulation Resistance Monitoring Device	K7GE-MG	K7GE-MG Logging Tool	30 June. 2024		
Heater Condition Monitoring Device	K7TM Configuration Tool				
Advanced Motor Condition Monitoring Device	K7DD	K7DD Support Tool			

<sup>\*1.</sup> Can be used only for K6CM-CI2, K6CM-VB with EIP CPU version 1.20 or higher, and K6CM-IS with EIP CPU version 1.20 or higher. \*2. The CD-ROM for the Motor Condition Monitoring Tool will no longer be supplied with K6CM manufactured in December 2024 or later.

#### **Operating Environment**

Supported OS	Windows 10 (Version1607 or later) and 11 (Japanese or English) 64 bit	
PC specifications	CPU: 1 GHz or higher, 64 bit processor Memory: 2 GB or higher Disk reserved area capacity: 20 GB or more Monitor resolution: 1920 × 1080 Others: LAN port (for network connection)	

#### How to obtain the Condition Monitoring Configuration Tool

Only download is available.

https://www.ia.omron.com/cmc\_tool

#### Communications converter for K7GE-MG, K7TM and K7DD

The Condition Monitoring Configuration Tool uses Ethernet (Modbus TCP) and the K7GE-MG, K7TM and K7DD units use serial communications (Modbus RTU), so protocol conversion is performed using a communications converter. Use a commercially available product for the communications converter. OMRON performed an evaluation test on the MGateMB3170 manufactured by MOXA.

### **Conformance to Safety Standards**

- For wiring from the Probe Unit to the load, use a Class CC, Class J, or Class T fuse with a rated current of 7 A or less.
- · The protection provided by the device may be impaired if the device is used in a manner that is not specified by the manufacturer.
- To use the Product, install it as an embedded device within a control panel.
- The table below shows the nominal voltage and measurement circuit connections available for each measurement category in the Main Power Supply System Configurations. Do not use the device under conditions that exceed this category and conditions.

	Main Power Supply System Configurations					
	3-phase, 4-wire type (neutral point grounding) TT	3-phase, 3-wire type (no grounding)	3-phase, 3-wire type (single-phase grounding)	Single-phase, 2-wire type AC or DC	Single-phase (split phase), 2-wire type AC or DC	
P2 P2 N P3 E TN-C-S		P1 P2 P3 E E	P1 P2 P3 E	L1 L2 E E	L1 N L2 E	
	L1 L2 PEN N PE					
CAT III	Phase voltage/line voltage 277 V/480 V	Line voltage 300 V	Line voltage 300 V	Line voltage 240 V	Phase voltage/ line voltage 240 V/480 V	
CAT II	347 V/600 V in addition to the above	480 V in addition to the above	480 V in addition to the above	480 V in addition to the above	Same as above	
Connection to measurement circuit	TT: Connect E in the diagram above to the No. 7 terminal (PE) of the K7GE-MGM. Connect P1 and P2 to the No. 1 and No. 3 terminals of the K7GE-MG1. TN-C-S: Connect PE in the diagram above to the No. 7 terminal (PE) of the K7GE-MGM. Connect L1 and L2 to the No. 1 and No. 3 terminals of the K7GE-MG1.	Connect E in the diagram above to the No. 7 terminal (PE) of the K7GE-MGM. Connect P1 and P2 to the No. 1 and No. 3 terminals of the K7GE-MG1.		Connect E in the diagram above to the No. 7 terminal (PE) of the K7GE-MGM. Connect L1 and L2 to the No. 1 and No. 3 terminals of the K7GE-MG1.		

#### **Measurement Category**

The measurement category classifies the places and equipment entry wire which you can connect to the measurement terminals, as prescribed in EN/IEC 61010-2-030.

Each category is as follows.

CAT I: Equipment to connect to circuits where measures are taken to

limit transient overvoltages to low levels

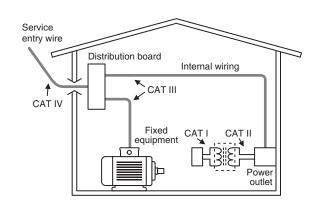
CAT II: Energy-consuming equipment with an energy supply from fixed

wiring equipment (such as a power outlet)

CAT III: Equipment in fixed wiring equipment that particularly demands

equipment reliability and effectiveness

CAT IV: Equipment to use at the electrical service entry



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