# CJ2H-CPU6□

CSM\_CJ2H-CPU\_DS\_E\_10\_3

## Setting new standards in high-speed machine control

 Small, Fast, Flexible: Inheriting and improving CJ1 features, the CJ2 CPU Units is the best choice for the machine control with high-speed and high-capacity.



CJ2H-CPU64

#### **Features**

- Even more program memory and data memory.
- Superior high-speed control performance: LOAD instructions execute in 16 ns, SINE instructions in 0.59 μs.
- Maximum throughputs with High-speed interrupt function
- Efficient debugging through highly improved Data tracing
- Secure system from memory error brought by Memory Self-restoration Function
- The more advanced motion control by the lower cost: Synchronous Unit Operation
- Increased I/O throughput speed by Immediate refreshing instructions with direct processing.

### **Ordering Information**

#### Applicable standards

Refer to the OMRON website (www.ia.omron.com) or ask your OMRON representative for the most recent applicable standards for each model.

#### **CJ2H CPU Units**

		Specifica	itions		Current consumption (A)		
Product name	I/O capacity/Mountable Units (Expansion Racks)	Program capacity	Data memory capacity	LD instruction execution time	5 V	24 V	Model
	2,560 points / 40 Units (3 Expansion Racks max.)	400K steps	832K words DM: 32K words EM: 32K words × 25 banks	0.016 μs			CJ2H-CPU68
CJ2H CPU Units		250K steps	512K words DM: 32K words EM: 32K words × 15 banks				CJ2H-CPU67
		150K steps	352K words DM: 32K words EM: 32K words × 10 banks		0.42 *	-	CJ2H-CPU66
		100K steps	160K words DM: 32K words EM: 32K words × 4 banks				CJ2H-CPU65
		50K steps	160K words DM: 32K words EM: 32K words × 4 banks				CJ2H-CPU64

<sup>\*</sup>Add 0.15 A per Adapter when using NT-AL001 RS-232C/RS-422A Adapters. Add 0.04 A per Adapter when using CJ1W-CIF11 RS-422A Adapters.

#### **Accessories**

The following accessories come with CPU Unit:

Item	Specification	
Battery	CJ1W-BAT01	
End Cover	CJ1W-TER01 (necessary to be mounted at the right end of CPU Rack)	
End Plate	PFP-M (2 pcs)	

Note: A serial port (RS-232C) connector is not provided. Purchase a connector separately for serial port connection.

Plug: XM3A-0921 (manufactured by OMRON) or equivalent Hood: XM2S-0911-E (manufactured by OMRON) or equivalent

### **General Specifications**

		CJ	CJ2H-			
	Item	CPU64 CPU65 CP	PU66	CPU67	CPU68	
Enclosure		Mounted in a panel				
Grounding		Less than 100 $\Omega$				
CPU Rack Dimension	ns	90 mm × 65 mm × 49 mm (H × D × W)				
Weight *		190 g or less				
Current Consumption	on	5 VDC, 0.42 A				
	Ambient Operating Temperature	0 to 55°C				
	Ambient Operating Humidity	10% to 90% (with no condensation)				
	Atmosphere	Must be free from corrosive gases.				
	Ambient Storage Temperature	−20 to 70°C (excluding battery)				
	Altitude	2,000 m or less				
	Pollution Degree	2 or less: Meets IEC 61010-2-201.				
Use Environment	Noise Immunity	2 kV on power supply line (Conforms to IEC 61000-4-4.)				
OSC ENVIRONMENT	Overvoltage Category	Category II: Meets IEC 61010-2-201.				
	EMC Immunity Level	Zone B				
	Vibration Resistance	Conforms to IEC60068-2-6. 5 to 8.4 Hz with 3.5-mm amplitude, 8.4 to 150 Hz Acceleration of 9.8 m/s² for 100 min in X, Y, and Z directions (10 sweeps of 10 min each 100 min total)				
	Shock Resistance	Conforms to IEC60068-2-27. 147 m/s², 3 times in X, Y, and Z directions (100 m/s² for Relay Output Units)				
	Life	5 years at 25°C				
Battery	Weight	Approx. 10 g				
	Model	CJ1W-BAT01				
Applicable Standard	ls	Conforms to cULus, NK, LR and EC Directives.				

<sup>\*</sup> Includes wight of end covers and battery.

## **Performance Specifications**

					CJ2H-				
	Items		CPU64	CPU65	CPU66	CPU67	CPU68		
User Memor	у		50K steps	100K steps	150K steps	250K steps	400K steps		
I/O Bits	T		2,560 bits						
	Overhead Pro	cessing Time	Normal Mode: 100 μs						
	Execution Tim	e	Basic Instructions: 0.016 μs min.; Special Instructions: 0.048 μs min.						
Processing Speed		I/O Interrupts and External Interrupts	Return time to cyclic	time : 26 μs or 17 μs task : 11 μs or 8 μs *					
	Interrupts	·	• .	interrupt function is us time: 22 μs or 13 μs					
		Scheduled Interrupts	Return time to cyclic	Return time to cyclic task: 11 µs or 8 µs *  * When High-speed interrupt function is used					
Maximum N	umber of Conne	ectable Units	Total per CPU Rack Total per PLC: 40 Ur	or Expansion Rack: 1	0 Units max.;				
Maximum N	umber of Expan	sion Racks	3 max.						
	I/O Area		2,560 bits (160 word	s): Words CIO 0000 to	CIO 0159				
	Link Area		3,200 bits (200 word	s): Words CIO 1000 to	CIO 1199				
	Synchronous	Data Refresh Area	1,536 bits (96 words)	): Words CIO 1200 to	CIO 1295				
010 4	CPU Bus Unit	Area	6,400 bits (400 word	s): Words CIO 1500 to	CIO 1899				
CIO Area	Special I/O Un	it Area	15,360 bits (960 wor	ds): Words CIO 2000	to CIO 2959				
	DeviceNet Are	a	` ` `	s): Words CIO 3200 to					
	3,200 bits (200 words): Words CIO 1300 to CIO 1499 37,504 bits (2,344 words): Words CIO 3800 to CIO 6143 Cannot be used for external I/O.								
Work Area			8,192 bits (512 word Cannot be used for e	s): Words W000 to W external I/O.	511				
Holding Are	Holding Area Bits in t Words			8,192 bits (512 words): Words H000 to H511 Bits in this area maintain their ON/OFF status when PLC is turned OFF or operating mode is changed. Words H512 to H1535: These words can be used only for function blocks. They can be used only for function block instances (i.e., they are allocated only for internal variables in function blocks).					
Auxiliary Are	ea		Read-only: 31,744 bits (1,984 words)  • 7,168 bits (448 words): Words A0 to A447  • 24,576 bits (1,536 words): Words A10000 to A11535 * Read/write: 16,384 bits (1,024 words) in words A448 to A1471 *  * A960 to A1471 and A10000 to A11535 cannot be accessed by CPU Bus Units, Special I/O Units, PTs, and Support Software that do not specifically support the CJ2 CPU Units.						
Temporary A	Area		16 bits: TR0 to TR15						
Timer Area			4,096 timer numbers (T0000 to T4095 (separate from counters)) 4,096 counter numbers (C0000 to C4095 (separate from timers))						
Counter Are	a			ers (C0000 to C4095 (	separate from timers)	)			
DM Area			32k words *  DM Area words for Special I/O Units: D20000 to D29599 (100 words × 96 Units)  DM Area words for CPU Bus Units: D30000 to D31599 (100 words × 16 Units)  * Bits in the EM Area can be addressed either by bit or by word. These bits cannot be addressed by CPU Bus Units, Special I/O Units, PTs, and Support Software that do not specifically support the CJ2 CPU Units.						
			32k words/bank × 25 banks max.: E00_00000 to E18_32767 max. *1 *2  *1. Bits in the EM Area can be addressed either by bit or by word. These bits cannot be addressed by CPU Bus Units, Special I/O Units, PTs, and Support Software that do not specifically support the CJ2 CPU						
EM Area			<ul> <li>Units.</li> <li>*2. EM banks D to 18 cannot be accessed by CPU Bus Units, Special I/O Units, PTs, and Support Software that do not specifically support the CJ2 CPU Units.</li> <li>*3. Force-set/reset to the EM Area is enabled by specifying a start bank in parameter settings. (unit version 1.2 or higher)</li> </ul>						
			32K words × 4 banks	32K words × 4 banks	32K words × 10 banks	32K words × 15 banks	32K words × 25 banks		
	Force-S/R	When EM force-S/R function is used *3	Bank 0 to 3	Bank 0 to 3	Bank 0 to 9	Bank 0 to E	Bank 0 to 18		
	Enabled Banks	When automatic address allocation is specified	Bank 3	Bank 3	Bank 6 to 9	Bank 7 to E	Bank 11 to 18		
Index Regist	ters		IR0 to IR15 These are special registers for storing PLC memory addresses for indirect addressing. (Index Registers can be set so that they are unique in each task or so that they are shared by all tasks.)						
Cyclic Task Flag Area			128 flags						
Memory Car	d		128 MB, 256 MB, or	512 MB					
				rograms are not exec	uted. Preparations ca	n be executed prior to	program execution in		
Operating M	odes		this mode.  MONITOR Mode: Programs are executed, and some operations, such as online editing, and changes to present values in I/O memory, are enabled in this mode.						
Evecuti :				Programs are executed	i. i nis is the normal o	perating mode.			
Execution Mode			Normal Mode						

		Itomas					CJ2H-			
		Items		CPU64	CPU65		CPU66	CPU67	CPU68	
Programmir	ıg Langu	ıages		Ladder Logic (LD), Sequential Function Structured Text (ST) Instruction Lists (IL)						
Function	Maxim	um num	nber of definitions	2,048						
Blocks	Maxim	um nun	nber of instances	2,048	2,048					
	Туре о	f Tasks		Cyclic tasks Interrupt tasks (Powertasks)	er OFF interrupt tas	ks, sched	duled interrupt t	asks, I/O interrupt ta	sks, and external interrup	
Tasks	Numbe	er of Tas	sks	Cyclic tasks: 128 Interrupt tasks: 256 (Interrupt tasks can be tasks is actually 384		tasks to	create extra cy	clic tasks. Therefore	, the total number of cycli	
	Type o	f Symbo	ols	Local symbols: Ca     Global symbols: Ca				PLC.		
Symbols (Variables)	Data Type of Symbols			BOOL (bit) UINT (one-word L UINT) (four-word ULINT) (four-word INT (one-word sig DINT (two-word sig DINT (two-word sig UINT BCD (one-w UDINT BCD (four-word sig UINT BCD (four-word sig) UINT BCD (four-word sig) UINT BCD (four-word sig) UINT BCD (four-word sig) UINT Sig) U	unsigned binary) unsigned binary) gined binary) igned binary) igned binary) igned binary) word unsigned BCD word unsigned BCD word unsigned BC floating-point) if floating-point) if hexadecimal) rd hexadecimal) rd hexadecimal) fo ASCII characters) ter) *2 types (data structul ly in Function blocks ly in Function blocks	D) *1 D) *1 Ires) *3	ion 9.0 or later	is used		
	Maxim	um Size	of Symbol	32k words						
	Array S	Symbols	s (Array Variables)	One-dimensional arr	rays					
	Numbe	r of Arr	ay Elements	32,000 elements ma	ix.					
	Memor	у Сарас	city	8,000 words (The EM Area can b banks supported by		CX-Pro	000 words grammer to use	32,000 words e up to 32K words m	ultiplied by the number	
	Numbe	r of Sar	mplings	Bits = 31, one-word data = 16, two-word data = 8, four-word data = 4						
Data	Sampli	ng Cyc	le	1 to 2,550 ms (Unit: 1 ms)						
Tracing	Trigge	r Condit	tions	ON/OFF of specified bit Data comparison of specified word Data size: 1 word, 2 words, 4 words Comparison Method: Equals (=), Greater Than (>), Greater Than or Equals (≥), Less Than (<), Less Than or Equals (≤), Not Equal (≠)						
	Delay \	/alue		-32,768 to +32,767	. ,					
Eilo Marra				Memory Card (128,	256, or 512 Mbytes	) (Use th	ne Memory Car	ds provided by OMF	RON.)	
File Memory	/			EM file memory (Part of the EM Area can be converted for use as file memory.)						
Source/ Comment Memory			ces, comments, ces, symbol tables	Capacity: 3.5 Mbytes						
	Logica	l Ports	Logical Ports	8 ports (Used for SE	ND, RECV, CMND	, PMCR,	TXDU, and RX	XDU instructions.)		
	for Cor nicatio	nmu-	Extended Logical Ports	64 ports (Used for S	END2, RECV2, CN	IND2, an	nd PMCR2 instr	ructions.)		
	CIP Co	mmu-	Class 3 Connection Type	Number of connection	ons: 128					
	nications UCMM Specification (Non-connection			Maximum number of clients that can communicate at the same time: 32 Maximum number of servers that can communicate at the same time: 32						
Communi-	Periph	eral (US	B) Port	USB 2.0-compliant E	3-type connector					
cations		Baud F		12 Mbps max.						
			nission Distance	5 m max.						
	Serial I			Interface: Conforms	to EIA RS-232C					
	- Ju. I		unications Method	Half-duplex	2020.					
			ronization Method	Start-stop						
		Baud F		0.3, 0.6, 1.2, 2.4, 4.8	3 96 192 381 5	76 or 1	15 2 (khne)			
					5, 5.0, 15.2, 50.4, 5	o, or 1	10.2 (nups)			
	Transmission Distance			15 m max.						

### **Function Specifications**

		unctions		Description		
Ossala Tissa	Minimum Cycle Time			A minimum cycle time can be set. (0.2 to 32,000 ms; Unit: 0.1 ms) The minimum cycle time setting can be changed in MONITOR mode.		
Cycle Time Management	Cycle Time Mo	nitoring		The cycle time is monitored. (0.01 to 40,000 ms; Unit: 0.01 ms)		
	Background Pr	rocessing		Instructions with long execution times can be executed over multiple cycles to prevent fluctuations in the cycle time.		
	Basic I/O		Cyclic Refreshing	Cyclic refreshing of Basic I/O Units, Special I/O Units, and CPU Bus Units		
	Units, Special	I/O Refreshing	Immediate Refreshing	I/O refreshing by immediate refreshing instructions		
	I/O Units, and CPU Bus	Refreshing	Refreshing by IORF	I/O refreshing by IORF instruction		
	Units	Unit Recogn	ition at Startup	The number of units recognized when the power is turned ON is displayed.		
	Basic I/O	Input Respo	nse Time Setting	The input response times can be set for Basic I/O Units. The response time can be increased to reduce the effects of chattering and noise at input contacts. The response time can be decreased to enable detecting shorter input pulses.		
	Units	Load OFF Function		All of the outputs on Basic I/O Units can be turned OFF when an error occurs in RUN or MONITOR mode.		
Unit (I/O)		Basic I/O Unit Status Monitoring		Alarm information can be read from Basic I/O Units and the number of Units recognized can be read.		
Management		Unit Restart Bits to Restart Units		A Special I/O Unit or CPU Bus Unit can be restarted.		
	Special I/O Units and CPU Bus Units	Synchronous Unit Operation		The start of processing for all the specified Units can be synchronized at a fixed interval. Maximum number of Units: 10 Units (Only Units that support Synchronous Operation Mode can be used.) Synchronous operation cycle: 0.5 to 10ms (default: 2 ms) Maximum number of words for synchronous data refreshing: 96 words (total of all Units)		
	Configuration Management	Automatic I/O Allocation at Startup		I/O words can be automatically allocated to the Basic I/O Units that are connected in the PLC to start operation automatically without registering Units into I/O tables.		
				The current unit configuration can be registered in I/O tables to prevent it from being changed, to reserve words, and to set words.		
		Rack/Slot First Word Settings		The first words allocated to a Units on the Racks can be set.		
	Holding I/O Memory when Changing Operating Modes		hanging Operating Modes	The status of I/O memory can be held when the operating mode is changed or power is turned ON. The forced-set/reset status can be held when the operating mode is changed or power is turned ON.		
	File Memory			Files (such as program files, data files, and symbol table files) can be stored in Memory Card, EM File Memory, or Comment Memory.		
Memory Management	Built-in Flash N	<b>l</b> lemory		The user program and Parameter Area can be backed up to an internal flash memory when they are transferred to the CPU Unit.		
	EM File Function	on		Parts of the EM Area can be treated as file memory.		
	Storing Comments			I/O comments can be stored as symbol table files in a Memory Card, EM file memory, or comment memory.		
	EM Configuration			EM Area can be set as trace memory or EM file memory.		
	Automatic File	Transfer at S	tartup	A program file and parameter files can be read from a Memory Card when the power is turned ON.		
Memory Cards	Program Repla	cement durin	g PLC Operation	The whole user program can be read from a Memory Card to CPU Unit during operation.		
Carus	Function for Re	eading and W	riting Data from a Memory	Data in I/O memory in the CPU Unit can be written to a Memory Card in CSV/TXT format.  Data in CSV/TXT format in the Memory Card can be read to I/O memory in the CPU Unit.		

	Funct	tion	Description		
Communication			-		
	Peripheral (USB) Port	Peripheral Bus	Bus for communications with various kinds of Support Software running on a personal computer. High-speed communications are supported.		
	Host Link (SYS	WAY) Communications	Host Link commands or FINS commands placed between Host Link headers and terminators can be sent from a host computer or PT to read/write I/O memory, read/control the operating mode, and perform other operations for PLC.		
	No-protocol Co	ommunications	I/O instructions for communications ports (such as TXD/RXD instructions) can be used for data transfer with peripheral devices such as bar code readers and printers.		
	NT Link Comm	unications	I/O memory in the PLC can be allocated and directly linked to various PT functions, including status control areas, status notification areas, touch switches, lamps, memory tables, and other objects.		
	Peripheral Bus		Bus for communications with various kinds of Support Software running on a personal computer. High-speed communications are supported.		
	Serial Gateway	,	This gateway enables receiving and automatically converting FINS to the CompoWay/F.		
	Scheduled Interrup	pts	Tasks can be executed at a specified interval (minimum of 0.2 ms or 0.1 ms *, Unit: 0.1 ms). * When High-speed interrupt function is used.		
	Power OFF Interru	pts	A task can be executed when CPU Unit's power turns OFF.		
Interrupt	I/O Interrupt Tasks	<b>S</b>	A task can be executed when an input signal is input to an Interrupt Input Unit.		
interrupt	External Interrupt	Tasks	A task can be executed when interrupts are requested from a Special I/O Unit or a CPU Bus Unit.		
	High-speed Interru	upt Function	Improves performance for executing interrupt tasks with certain restrictions. (Unit version 1.1 or later.)		
	Clock Function		Clock data is stored in memory.  Accuracy (Accuracy depends on the temperature.)  Ambient temperature of 55°C: –3.5 to +0.5 min error per month  Ambient temperature of 25°C: –1.5 to +1.5 min error per month  Ambient temperature of 0°C: –3 to +1 min error per month		
	Operation Start Time Storage		The time when operating mode was last changed to RUN mode or MONITOR mode is stored.		
Clock	Operation Stop Time Storage		The last time a fatal error occurred or the last time the operating mode was changed to PROGRAM mode is stored.		
	Startup Time Stora	age	The time when the power was turned ON is stored.		
	Power Interruption Time Storage		The time when the power is turned OFF is stored.		
	Total Power ON Ti	me Calculation	The total time that the PLC has been ON is stored in increments of 10 hours.		
	Power ON Clock Data Storage		A history of the times when the power was turned ON is stored.		
	User Program Ove	erwritten Time Storage	The time that the user program was last overwritten is stored.		
	Parameter Date St		The time when the Parameter Area was overwritten is stored.		
Davier	Memory Protection		Holding Area data, DM Area data, EM Area data, Counter Completion Flags, and counter present values are held even when power is turned OFF. CIO Area, Work Area, some Auxiliary Area data, and Timer Completion Flags, timer present values, index registers, and data registers can be protected by turning ON the IOM Hold Bit in the Auxiliary Area, and by also setting the IOM Hold Bit to "Hold" in the PLC Setup.		
Power Supply Management	Power OFF Detection Time Setting		The detection time for power interruptions can be set. AC power supply: 10 to 25 ms (variable) DC power supply: 2 to 5 ms (CJ1W-PD022) or 2 to 20 ms (CJ1W-PD025)		
	Power OFF Detect	ion Delay Time	The detection of power interruptions can be delayed: 0 to 10 ms (Not supported by the CJ1W-PD022.)		
Function Bloc		Interruptions Counter	The number of times power has been interrupted is counted.  Standard programming can be encapsulated as function blocks.		
	Languages in Fund	ction Block Definitions	Ladder programming or structured text		
	Online Editing		The program can be changed during operation (in MONITOR or PROGRAM mode), except for block programming areas.		
	Force-Set/Reset		Specified bits can be set or reset. Force-set/reset to the EM Area is enabled by specifying a start bank in parameter setting. (unit version 1.2 or higher)		
	Differentiate Monit	toring	ON/OFF changes in specified bits can be monitored.		
Debugging	Data Tracing		The specified I/O memory data can be stored in the trace memory in the CPU Unit. The triggers can be set.  • The trace data can be uploaded during data tracing using CX-Programmer, which enables continuously logging the data by constantly uploading the trace data (trace data uploading during tracing).  • Data tracing can be automatically started when operation is started (i.e., when the operating mode is changed from PROGRAM mode to MONITOR or RUN mode).		
	Storing Location o	of Error when an Error Occurs	The location and task number where execution stopped for a program error is recorded.		
	Storing Location of Error when an Error Occurs  Program Check		The location and task number where execution stopped for a program error is recorded.  The programs can be checked for items such as no END instruction and FALS/FAL errors at startup.		

	Func	tion	Description
	Error Log		A function is provided to store predefined error codes in CPU Unit, error information, and time at which the error occurred.
	CPU Error Detecti	on	CPU Unit WDT errors are detected.
	User-defined Failu	ıre Diagnosis	Errors can be generated for user-specified conditions: Non-fatal errors (FAL) and fatal errors (FALS).  Program section time diagnosis and program section logic diagnosis are supported (FPD
			instruction).
	Load OFF Functio	n	This function turns OFF all outputs from Output Units when an error occurs.  The RUN output from the CJ1W-PA205R turns ON while CPU Unit is in RUN mode or
	Basic I/O Load Sh	ort-circuit Detection	MONITOR mode.  This function provides alarm information from Basic I/O Units that have load short-circuit
	Failure Point Dete	ction	protection.  The time and logic of an instruction block can be analyzes using the FPD instruction.
	CPU Standby Dete	ection	This function indicates when the CPU Unit is on standby because all Special I/O Units and CPU Bus Units have not been recognized at the startup in RUN or MONITOR mode.
	System FAL Error Detection		This function generates a non-fatal (FAL) error when the user-defined conditions are met in
		(User-defined non-fatal error)  Duplicate Refreshing Error Detection	program.  This function detects an error when an immediate refreshing Instruction in an interrupt task is competing with I/O refreshing of a cyclic task.
		Basic I/O Unit Error Detection	This function detects the errors in Basic I/O Units.
		Backup Memory Error Detection	This function detects errors in the memory backup of the user programs and parameter area (backup memory).
	N 6.15	PLC Setup Error Detection	This function detects setting errors in the PLC Setup.
	Non-fatal Error Detection	CPU Bus Unit Error Detection	This function detects an error when there is an error in data exchange between the CPU Unit and a CPU Bus Unit.
		Special I/O Unit Error Detection	This function detects an error when there is an error in data exchange between the CPU Unit and a Special I/O Unit.
		Battery Error Detection	This function detects an error when a battery is not connected to the CPU Unit or when the battery voltage drops.
		CPU Bus Unit Setting Error Detection	This function detects an error when the model of a CPU Bus Unit in the registered I/O tables does not agree with the model that is actually mounted in the PLC.
Self-		Special I/O Unit Setting Error Detection	This function detects an error when the model of a Special I/O Unit in the registered I/O tables does not agree with the model of Unit that is actually mounted.
	Memory Error Detection  I/O Bus Error Detection  Unit/Rack Number Duplication Error		This function detects errors that occur in memory of the CPU Unit.
diagnosis and Restoration			This function detects when an error occurs in data transfers between the Units mounted in Rack slots and the CPU Unit and detects when the End Cover is not connected to the CPU Rack or an Expansion Rack.
			This function detects an error when the same unit number is set for two or more Units, the same word is allocated to two or more Basic I/O Units, or the same rack number is set for two or more Racks.
		Too Many I/O Points Error Detection	This function detects an error when the total number of I/O points set in the I/O tables or the number of Units per Rack exceeds the specified range.
		I/O Setting Error Detection	This function detects an error when the number of Units in the registered I/O tables does not agree with the actual number of Units that is mounted, or an Interrupt Unit has been connected in the wrong position, i.e., not in slot 0 to 4.
		Program Error Detection	This function detects errors in programs.
		Instruction Processing Error Detection	This function detects an error when the given data value is invalid when executing an instruction, or execution of instruction between tasks was attempted.
	Fatal Error Detection	Indirect DM/EM BCD Error Detection	This function detects an error when an indirect DM/EM address in BCD mode is not BCD.
		Illegal Area Access Error Detection	This function detects an error when an attempt is made to access an illegal area with an instruction operand.
		No END Error Detection	This function detects an error when there is no END instruction at the end of the program.
		Task Error Detection	This function detects an error when there are no tasks that can be executed in a cycle, there is no program for a task, or the execution condition for an interrupt task was met but there is no interrupt task with the specified number.
		Differentiation Overflow Error Detection	This function detects an error when too many differentiated instructions are entered or deleted during online editing (131,072 times or more).
		Invalid Instruction Error Detection	This function detects an error when an attempt is made to execute an instruction that is not defined in the system.
		User Program Area Overflow Error Detection	This function detects an error when instruction data is stored after the last address in user program area.
		Cycle Time Exceeded Error Detection	This function monitors the cycle time (10 to 40,000 ms) and stops the operation when the set value is exceeded.
	Fatal Error	System FALS Error Detection (User-defined Fatal Error)	This function generates a fatal (FALS) error when the user-defined conditions are met in program.
	Detection (Continued from	Version Error Detection	This function detects an error when a user program includes a function that is not supported by the current unit version.
	previous page)	Memory Card Transfer Error Detection	This function detects an error when the automatic file transfer from Memory Card fails at startup.

	Function		Description
	Simple Backup Function		This function collectively backs up the data in CPU Unit (user programs, parameters, and I/O memory) and internal backup data in the I/O Units.
	Unsolicited Communications		A function that allows the PLC to use Network Communications Instruction to send required FINS commands to a computer connected via a Host Link
Maintenance	Remote Programming and Monitoring		Host Link communications can be used for remote programming and remote monitoring through a Controller Link, Ethernet, DeviceNet, or SYSMAC LINK Network. Communications across network layers can be performed.  Controller Link or Ethernet: 8 layers  DeviceNet or SYSMAC LINK: 3 layers
	Automatic Online Connection via Network Direct Serial Connection		This function enables automatically connecting to the PLC online when the CX-Programmer is directly connected by a serial connection (peripheral (USB) port or serial port).
	Read Protection using Password		This function protects reading and displaying programs and tasks using passwords. Write protection: Set using the DIP switch. Read protection: Set a password using the CX-Programmer.
Caarreite.	FINS Write Protection		This function prohibits writing by using FINS commands sent over the network.
Security	Unit Name Function		This function allows the users to give any names to the Units. Names are verified at online connection to prevent wrong connection
	Hardware ID Using Lot Numbers		This function sets operation protection by identifying hardware using the user programs according to lot numbers stored in the Auxiliary Area.

#### **Unit Versions**

Units	Models	Unit version	
		Unit version 1.4	
CJ2H CPU Units	CJ2H-CPU6□	Unit version 1.3	
CJZH CFU UIIIIS	CJZH-CFO0	Unit version 1.2	
		Unit version 1.1 *	

<sup>\*</sup>Although the product of unit version 1.0 does not exist for the CJ2H CPU unit (CJ2H-CPU6□), this unit version 1.1 means that the functions are added based on the same functionality as CJ2H-CPU6□-EIP unit version 1.0.

### **Function Support by Unit Version**

#### **Unit Version 1.4 or Later**

CX-Programmer version 9.3 or higher must be used to enable using the functions added for unit version 1.4.

Unit	CJ2H CPU Unit		
Model	CJ2H-CPU6□		
Unit version Item	Unit version 1.4 or higher	Unit version 1.3 or earlier	
Synchronous unit operation function Position Control Units with EtherCAT interface CJ1W-NC□82 work for synchronous unit operation.	Supported.	Not supported.	

#### **Unit Version 1.3 or Later**

CX-Programmer version 9.1 or higher must be used to enable using the functions added for unit version 1.3.

	Unit	CJ2H CPU Unit		
	Model	CJ2H-CPU6□		
Item	Unit version	Unit version 1.3 or later	Unit version 1.2 or earlier	
Special instructions for certain	CJ1W-NC281/NC481/NC881 Position Control Units: PCU HIGH-SPEED POSITIONING (NCDMV(218))	Supported.	Not supported.	
Special I/O Units	CJ1W-NC281/NC481/NC881 Position Control Units: PCU POSITIONING TRIGGER (NCDTR(219))	Supported.	Not supported.	
New special instructions	SIGNED AREA RANGE COMPARE: ZCPS(088)	Supported.	Not supported.	
	DOUBLE SIGNED AREA RANGE COMPARE: ZCPSL(116)	Supported.	Not supported.	

#### **Unit Version 1.2 or Later**

CX-Programmer version 8.3 or higher must be used to enable using the functions added for unit version 1.2.

Unit	CJ2H CPU Unit		
Model	CJ2H-CPU6□		
Unit version	Unit version 1.2 or higher	Unit version 1.1 or earlier	
EM force-set/reset function	Supported.	Not supported.	

Note: User programs that use functions of CJ2H CPU Units with unit version 1.2 or later cannot be used with CJ2H CPU Units with unit version 1.1 or earlier. If an attempt is made to transfer a program that uses any of these functions from the CX-Programmer to a CPU Unit with unit version 1.1 or earlier, an error will be displayed and it will not be possible to download to the CPU Unit.

#### **Unit Version 1.1 or Later**

CX-Programmer version 8.1 or higher must be used to enable using the functions added for unit version 1.1.

Note: Although the product of unit version 1.0 does not exist for the CJ2H CPU unit (CJ2H-CPU6□), it describes here assuming that the functions are added with unit version 1.1 to the unit version 1.0 functions as well as CJ2H-CPU6□-EIP.

Unit	CJ2H CPU Unit		
Model	CJ2H-CPU6□		
Unit version Item	Unit version 1.1 or higher		
High-speed interrupt function Decreased overhead time for interrupt tasks Minimum interval setting of 0.1 ms for Scheduled Interrupt Task	Supported.		
Changing the minimum cycle time setting in MONITOR mode	Supported.		
Synchronous unit operation function Position Control Units (High-speed type) CJ1W-NC□□4 work for synchronous unit operation.	Supported.		
Addition of Immediate refreshing instruction only for specific Special I/O Units and CPU Bus Units For CJ1W-AD042: Analog Input Direct Convert AIDC (216) For CJ1W-DA042V: Analog Output Direct Convert AODC (217) For CJ1W-SCU22/32/42: Direct Receive Via Serial Communications Unit DRXDU (261) Direct Transmit Via Serial Communications Unit DTXDU (262)	Supported.		

### **Unit Versions and Programming Devices**

The following tables show the relationship between unit versions and CX-Programmer versions.

#### **Unit Versions and Programming Devices**

			Required Programming Device						
CPU Unit	Functions		CX-Programmer					D	
or o onic			Ver. 7.1 or lower	Ver.8.0	Ver.8.1/ Ver.8.2	Ver. 8.3	Ver. 9.1/9.2	Ver. 9.3 or higher	Programming Console
C IOLI CDUE	Functions	Using new functions	-	-	-	-	-	OK	
Unit version 1.4 CJ2H-CPU6 added for universion 1.4	added for unit version 1.4	Not using new functions	-	OK <b>*</b> 1	OK <b>*</b> 1	ОК	ОК	ОК	
C IOLI CDUE	Functions	Using new functions	-	-	-	-	OK	OK	
CJ2H-CPU6 added for unversion 1.3	added for unit version 1.3	Not using new functions	-	OK <b>*</b> 1	OK <b>*</b> 1	ОК	ОК	ОК	***
CJ2H-CPU6□	Functions	Using new functions	-	-	-	OK	OK	OK	<b>- *3</b>
Unit version 1.2	added for unit version 1.2	Not using new functions	-	OK <b>*</b> 1	OK <b>*</b> 1	ОК	ОК	ОК	
CJ2H-CPU6□ Unit version 1.1	Functions added for unit version 1.1	Using new functions	-	-	OK *2	OK	OK	OK	
		Not using new functions	-	-	ОК	ОК	ОК	ОК	

\*1. It is not necessary to upgrade the version of the CX-Programmer if functionality that was enhanced for the upgrade of the CPU Unit will not be used.
\*2. CX-Programmer version 8.2 or higher is required to use CJ2 CPU Units (CJ2H-CPU6□). However the functions of unit version 1.0 and only High-speed interrupt function and Changing the minimum cycle time setting in MONITOR mode are supported in CX-Programmer version 8.02.
\*3. A Programming Console cannot be used with a CJ2H CPU Unit.

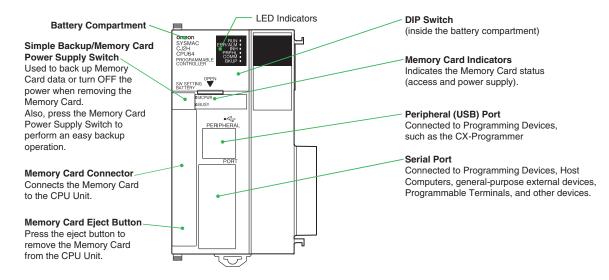
#### **Device Type Setting**

The unit version does not affect the setting made for the device type on the CX-Programmer. Select the device type as shown in the following table regardless of the unit version of the CPU Unit.

Series	CPU Unit group	CPU Unit model	Device type setting on CX-Programmer Ver. 8.0 or higher
CJ Series	CJ2H CPU Units	CJ2H-CPU6□	CJ2H

#### **External Interface**

A CJ2H CPU Unit (CJ2H-CPU6 ) provides two communications ports for external interfaces: a peripheral (USB) port and a serial port.



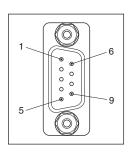
#### Peripheral (USB) Port

Item	Specification		
Baud Rate	12 Mbps max.		
Transmission Distance	5 m max.		
Interface	USB 2.0-compliant B-type connector		
Protocol	Peripheral Bus		

#### **Serial Port**

Item	Specification	
Communications method	Half duplex	
Synchronization Start-stop		
Baud rate	0.3/0.6/1.2/2.4/4.8/9.6/19.2/38.4/57.6/115.2 kbps *	
Transmission distance 15 m max.		
Interface EIA RS-232C		
Protocol	Host Link, NT Link, 1:N, No-protocol, or Peripheral Bus	

<sup>\*</sup>Baud rates for the RS-232C are specified only up to 19.2 kbps. The CJ Series supports serial communications from 38.4 kbps to 115.2 kbps, but some computers cannot support these speeds. Lower the baud rate if necessary.



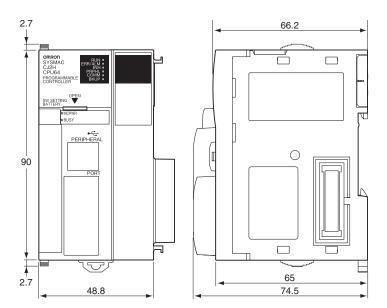
Pin No.	Signal	Name	Direction
1	FG	Protection earth	-
2	SD (TXD)	Send data	Output
3	RD (RXD)	Receive data	Input
4	RS (RTS)	Request to send	Output
5	CS (CTS)	Clear to send	Input
6	5 V	Power supply	-
7	DR (DSR)	Data set ready	Input
8	ER (DTR)	Data terminal ready	Output
9	SG (0 V)	Signal ground	-
Connector hood	FG	Protection earth	_

Note: Do not use the 5-V power from pin 6 of the RS-232C port for anything but CJ1W-CIF11 RS-422A Conversion Adapter, NT-AL001 RS-232C/RS-422A Conversion Adapter and NV3W-M□20L(-V1) Programmable Terminal. The external device or the CPU Unit may be damaged.

Dimensions (Unit: mm)

CJ2H CPU Unit CJ2H-CPU6□





### **Related Manuals**

Cat. No.	Model	Manual	Application	Description
W472	CJ2H-CPU6□-EIP CJ2H-CPU6□ CJ2M-CPU□□	CJ-series CJ2 CPU Unit Hardware User's Manual	Hardware specifications for CJ2 CPU Units	Describes the following for CJ2 CPU Units:  Overview and features Basic system configuration Part nomenclature and functions Mounting and setting procedure Remedies for errors Also refer to the Software User's Manual (W473).
W473	CJ2H-CPU6□-EIP CJ2H-CPU6□ CJ2M-CPU□□	CJ-series CJ2 CPU Unit Software User's Manual	Software specifications for CJ2 CPU Units	Describes the following for CJ2 CPU Units:  • CPU Unit operation  • Internal memory  • Programming  • Settings  • Functions built into the CPU Unit  Also refer to the Hardware User's Manual (W472)
W474	CJ2H-CPU6 -EIP CJ2H-CPU6  CJ2M-CPU3  CJ2M-CPU1  CS1G/H-CPU   CS1G/H-CPU   CJ1G/H-CPU   CJ1M-CPU   CJ1M-CPU   CS1D-CPU   CS1D-CPU   CS1D-CPU   SA CS1D-CPU   NSJ	CS/CJ/NSJ-series Instructions Reference Manual	Information on instructions	Describes each programming instruction in detail. Also refer to the <i>Software User's Manual</i> (W473) when you do programming.
W342	CJ2H-CPU6  -EIP CJ2H-CPU6   CJ2M-CPU    CS1G/H-CPU    CS1G/H-CPU    CS1D-CPU    CS1D-CPU    CS1D-CPU    CS1D-CPU    CS1W-SCU    CJ1H-CPU    CJ1H-CPU    CJ1G-CPU    CJ1G-CPU    CJ1W-SCU    CJ1W-SCU    CJ1W-SCU    CJ1W-SCU    CJ1W-SCU    CJ1W-SCU    CJ1W-SCU    CP1H-XA     CP1H-XA     CP1H-Y     NSU	CS/CJ/CP/NSJ-series Communications Command Reference Manual	Information on communications for CS/CJ/CP-series CPU Units and NSJ-series Controllers	Describes C-mode commands and FINS commands Refer to this manual for a detailed description of commands for communications with the CPU Unit using C mode commands or FINS commands.  Note: This manual describes the communications commands that are addressed to CPU Units. The communications path that is used is not relevant and can include any of the following: serial ports on CPU Units, communications ports on Serial Communications Units/Boards, and Communications Units. For communications commands addressed to Special I/O Units or CPU Bus Units, refer to the operation manual for the related Unit.
W463	CXONE-AL D-V	CX-One Setup Manual	Installing software from the CX- One	Provides an overview of the CX-One FA Integrated Tool Package and describes the installation procedure.
W446		CX-Programmer Operation Manual		,
W447	WS02-CXPC□-V□	CX-Programmer Operation Manual Functions Blocks/ Structured Text	Support Software for Windows computers  CX-Programmer operating	Describes operating procedures for the CX-Programmer. Also refer to the Software User's Manual (W473) and Instructions Reference Manual (W474) when you do programming.
W469		CX-Programmer Operation Manual SFC Programming	procedure	F29-2
W366	WS02-SIMC1-E	CS/CJ/CP/NSJ-series CX-Simulator Operation Manual	Operating procedures for CX- Simulator Simulation Support Software for Windows computers Using simulation in the CX- Programmer with CX- Programmer version 6.1 or higher	Describes the operating procedures for the CX-Simulator. When you do simulation, also refer to the CX-Programmer Operation Manual (W446), Software User's Manual (W473), and CS/CJ/NSJ series Instructions Reference Manual (W474).
W464	CXONE-AL□□D-V□	CS/CJ/CP/NSJ-series CX-Integrator Network Configuration Software Operation Manual	Network setup and monitoring	Describes the operating procedures for the CX-Integrator.

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