

Save energy and maximize performance with versatile inverter

- Triple rating: Normal Duty (ND), Low Duty (LD), and Very Low Duty (VLD)
- · PM motor control helps save energy
- Safety function IEC 61800-5-2 "Safe Torque Off (STO)"
 Conforms to machinery directive with ISO13849-1 (Category 4/PLe)
- DriveProgramming allows simple sequence control without a PLC
- EtherCAT communication using an optional communication unit provides high-speed communication for running and stopping, monitoring operating status, and changing various settings



Performance Specifications

Inverter 3G3RX2

3-phase 200-V Class

Very Low Duty (VLD)/Low Duty (LD)/Normal Duty (ND)

30	3RX2-A2□]	A2004	A2007	A2015	A2022	A2037	A2055	A2075	A2110	A2150	A2185	A2220	A2300	A2370	A2450	A2550
			VLD	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75
	ble motor capacity (l	رW)	LD	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75
(+ poio)	capacity (i	,	ND	0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55
			VLD	4.4	8.0	10.4	15.6	22.8	33.0	46.0	60.0	80.0	93.0	124	153	185	229	295
	Rated out		LD	3.7	6.3	9.4	12.0	19.6	30.0	40.0	56.0	73.0	85.0	113	140	169	210	270
	ourront (r	•,	ND	3.2	5.0	8.0	11.0	17.5	25.0	32.0	46.0	64.0	76.0	95.0	122	146	182	220
			VLD	110% 6	0 sec / 1	20% 3 se	С											
	Overload current ra	tina	LD	120% 6	0 sec / 1	50% 3 se	ec											
	ourront re	9	ND	150% 6	0 sec / 2	00% 3 se	ес											
Output	Rated out	put vo	ltage	3-phase	e (3-wire)	200 to 2	40 V (de	pending	on receiv	ving volta	ige)							
			VLD	1.5	2.8	3.6	5.4	7.9	11.4	15.9	20.8	27.7	32.2	43.0	53.0	64.1	79.3	102.2
		200 V	LD	1.3	2.2	3.3	4.2	6.8	10.4	13.9	19.4	25.3	29.4	39.1	48.5	58.5	72.7	93.5
	Rated capacity		ND	1.1	1.7	2.8	3.8	6.1	8.7	11.1	15.9	22.2	26.3	32.9	42.3	50.6	63.0	76.2
	(kVA)		VLD	1.8	3.3	4.3	6.5	9.5	13.7	19.1	24.9	33.3	38.7	51.5	63.6	76.9	95.2	122.6
		240 V	LD	1.5	2.6	3.9	5.0	8.1	12.5	16.6	23.3	30.3	35.3	47.0	58.2	70.3	87.3	112.2
			ND	1.3	2.1	3.3	4.6	7.3	10.4	13.3	19.1	26.6	31.6	39.5	50.7	60.7	75.7	91.5
	Rated inp	ut	VLD	5.2	9.5	12.4	18.6	27.1	39.3	54.8	71.4	95.2	110.7	147.6	182.1	220.2	272.6	351.2
	current (A	A)	LD	4.4	7.5	11.2	14.3	23.3	35.7	47.6	66.7	86.9	101.2	134.5	166.7	201.2	250.0	321.4
	*1		ND	3.8	6.0	9.5	13.1	20.8	29.8	38.1	54.8	76.2	90.5	113.1	145.2	173.8	216.7	261.9
Input	Rated input AC voltage			50 Hz (a	Control power supply: Power supply single phase 200 to 240 V/allowable variation range 170 to 264 V, 50 Hz (allowable variation range: 47.5 to 52.5 Hz)/60 Hz (allowable variation range: 57 to 63 Hz) Main circuit power supply: 3-phase (3-wire) 200 to 240 V/allowable variation range 170 to 264 V, 50 Hz (allowable variation range: 47.5 to 52.5 Hz)/60 Hz (allowable variation range: 57 to 63 Hz)													
	Power supply VLD		2.0	3.6	4.7	7.1	10.3	15.0	20.9	27.2	36.3	42.2	56.3	69.4	83.9	103.9	133.8	
	equipmen	ment ID		1.7	2.9	4.3	5.4	8.9	13.6	18.1	25.4	33.1	38.6	51.3	63.5	76.7	95.3	122.5
	capacity (KVA)	ND	1.5	2.3	3.6	5.0	7.9	11.3	14.5	20.9	29.0	34.5	43.1	55.3	66.2	82.6	99.8
	1		VLD	0.5 to 1	0.0 kHz					1								
	frequency ng range *:	,	LD	0.5 to 1	2.0 kHz													
operatir	ig range कर	•	ND	0.5 to 1	6.0 kHz													
Motor s	tart torque	*4		200%/0	.3 Hz													
Braking	Regenera	tive bra	aking	Equippe	ed with B	RD circu	it (with a	discharg	ing resis	tor separ	ately ins	talled)				rative bra		it
Diaking	Minimum r			50	50	35	35	35	16	10	10	7.5	7.5	5				
Disc.	Height (m	m)		255	255	255	255	255	260	260	260	390	390	390	540	550	550	700
Dimen- sion	Width (mm)		150	150	150	150	150	210	210	210	245	245	245	300	390	390	480	
	Depth (m	m)		140	140	140	140	140	170	170	170	190	190	190	195	250	250	250
Protecti	ve constru	ction		IP20 *5	/ UL ope	en type	•							•	•	•	•	
Approximate mass (kg) 3 3 3 3 6 6 6 10 10 10 22						22	33	33	47									

- *1. The rated input currents shown in the table are the values when the rated current is output. The values vary depending on impedance on the power supply (wiring, breaker, input reactor option, etc.)
- *2. The power supply equipment capacities shown in the table are the values when 220 V rated current is output. The values vary depending on impedance on the power supply (wiring, breaker, input reactor option, etc.)
- *3. The setting of rated values for carrier frequencies [bb101]/[bb201] are internally limited in accordance with the description. Also, it is recommended to set values equivalent to or above (maximum output frequency for driving ×10) Hz for the setting of carrier frequencies [bb101]/ [bb201]. Also, in the case of induction motor (IM) control, for items other than those subject to V/f control, it is recommended to set carrier frequency at 2 kHz or more. In the case of synchronous motor (SM)/permanent magnet motor (PMM) control, it is recommended to set carrier frequency at 8 kHz or more.
- *4. The value of the sensor-less vector control applied to the ND rating in the Standard motor. Torque characteristics may vary depending on the control method and the motor used.
- *5. Based on self declaration.

3-phase 400-V Class

Very Low Duty (VLD)/Low Duty (LD)/Normal Duty (ND)

<u> </u>													,		, ,	,		, ,			
3	G3RX2-□□		I	A4007	A4015	A4022	A4037	A4055	A4075	A4110	A4150	A4185	A4220	A4300	A4370	A4450	A4550	B4750	B4900	B411K	B413K
Applicat	ole motor		VLD	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	110	132	160
	capacity (l	(W)	LD	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	110	132	160
			ND	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	110	132
	Rated out	nut	VLD	4.1	5.4	8.3	12.6	17.5	25.0	31.0	40.0	47.0	62.0	77.0	93.0	116	147	176	213	252	316
	current (A		LD	3.1	4.8	6.7	11.1	16.0	22.0	29.0	37.0	43.0	57.0	70.0	85.0	105	135	160	195	230	290
			ND	2.5	4.0	5.5	9.2	14.8	19.0	25.0	32.0	39.0	48.0	61.0	75.0	91.0	112	150	180	217	260
	Overload		VLD		60 sec																
	current ra	iting	LD		60 sec																
			ND		60 sec																
Output	Rated out	put vol			se (3-w	, <i></i>		, · · ·	, <u> </u>		, <u> </u>		1	1		1					
			VLD	2.8	3.7	5.8	8.7	12.1	17.3	21.5	27.7	32.6	43.0	53.3	64.4	80.4	101.8	121.9	147.6	174.6	218.9
		400 V	LD	2.1	3.3	4.6	7.7	11.1	15.2	20.1	25.6	29.8	39.5	48.5	58.9	72.7	93.5	110.9	135.1	159.3	200.9
	Rated		ND	1.7	2.8	3.8	6.4	10.3	13.2	17.3	22.2	27.0	33.3	42.3	52.0	63.0	77.6	103.9	124.7	150.3	180.1
	(kVA)		VLD	3.6	4.7	7.2	10.9	15.2	21.7	26.8	34.6	40.7	53.7	66.7	80.5	100.5	127.3	152.4	184.5	218.2	273.7
		500 V	LD	2.7	4.2	5.8	9.6	13.9	19.1	25.1	32.0	37.2	49.4	60.6	73.6	90.9	116.9	138.6	168.9	199.2	251.1
			ND VLD	2.2	3.5	4.8	8.0	12.8	16.5	21.7	27.7	33.8	41.6	52.8	65.0	78.8	97.0	129.9	155.9	187.9	225.2
	Rated inp	4.9	6.4	9.9	15.0	20.8	29.8	36.9	47.6	56.0	73.8	91.7	110.7	138.1	175.0	209.5	253.6	300.0	376.2		
	*1		LD	3.7	5.7	8.0	13.2	19.0	26.2	34.5	44.0	51.2	67.9	83.3	101.2	125.0	160.7	190.5	232.1	273.8	345.2
			ND	3.0	4.8	6.5	11.0	17.6	22.6	29.8	38.1	46.4	57.1	72.6	89.3	108.3	133.3		214.3	258.3	309.5
Innut	Rated input AC voltage			Control power supply: Power supply single phase 380 to 500 V (allowable variation range 323 to 550 V), 50 Hz (allowable variation range: 47.5 to 52.5 Hz)/60 Hz (allowable variation range: 57 to 63 Hz)																	
Input			Main circuit power supply: 3-phase (3-wire) 380 to 500 V (allowable variation range) 323 to 550 V, 50 Hz (allowable variation range: 47.5 to 52.5 Hz)/60 Hz (allowable variation range: 57 to 63 Hz)																		
	Power su	pply	VLD	3.7	4.9	7.5	11.4	15.9	22.7	28.1	36.3	42.6	56.3	69.9	84.4	105.2	133.4	159.7	193.2	228.6	286.7
	equipmer capacity (LD	2.8	4.4	6.1	10.1	14.5	20.0	26.3	33.6	39.0	51.7	63.5	77.1	95.3	122.5	145.2	176.9	208.7	263.1
	* 2	,KVA)	ND	2.3	3.6	5.0	8.3	13.4	17.2	22.7	29.0	35.4	43.5	55.3	68.0	82.6	101.6	136.1	163.3	196.9	235.9
			VLD	0.5 to	10.0 kF	łz												0.5 to	8.0 kHz	<u>.</u>	
Carrier f	requency		LD	0.5 to	12.0 kF	łz												0.5 to	8.0 kHz	<u>.</u>	
range se	•		ND	0.5 to	16.0 kF	lz												0.5 to	10.0 kF	lz	
Motor st	art torque	*4	,	200%/	0.3 Hz													180%/	0.3 Hz		
	Regenera	tive bra	aking		ped with a discha					alled)						Regen		braking	unit se	eparate	ly
Braking	Minimum r			100	100	100	70	70	35	35	24	24	20	15	15	10	10				
	Height (m	m)		255	255	255	255	260	260	260	390	390	390	540	550	550	550	700	700	740	740
Dimen- sion	Width (mi	n)		150	150	150	150	210	210	210	245	245	245	300	390	390	390	390	390	480	480
5.5.1	Depth (mi	m)		140	140	140	140	170	170	170	190	190	190	195	250	250	250	270	270	270	270
Protective construction				IP20 ¥	≰5 / UL	open ty	ре	•	•	•	•	•	•	•	•		•	IP00 /	UL ope	n type	•
Approxi	mate mass	(kg)		3	3	3	3	6	6	6	8.5	8.5	8.5	22	31	31	31	41	41	53	53
at at Th	and a differ	.4																			

- *1. The rated input currents shown in the table are the values when the rated current is output. The values vary depending on impedance on the power supply (wiring, breaker, input reactor option, etc.)
- *2. The power supply equipment capacities shown in the table are the values when 220 V rated current is output. The values vary depending on impedance on the power supply (wiring, breaker, input reactor option, etc.)
- *3. The setting of rated values for carrier frequencies [bb101]/[bb201] are internally limited in accordance with the description. Also, it is recommended to set values equivalent to or above (maximum output frequency for driving ×10) Hz for the setting of carrier frequencies [bb101]/ [bb201]. Also, in the case of induction motor (IM) control, for items other than those subject to V/f control, it is recommended to set carrier frequency at 2 kHz or more. In the case of synchronous motor (SM)/permanent magnet motor (PMM) control, it is recommended to set carrier frequency at 8 kHz or more.
- ***4.** The value of the sensor-less vector control applied to the ND rating in the Standard motor. Torque characteristics may vary depending on the control method and the motor used.
- ***5.** Based on self declaration.

Function Specifications

Inverter 3G3RX2

	Item			Specifications						
Control mo	ode the motor)		Sine wave PWM control voltage output	ut (line sine wave modulation)						
Output fre	quency range	*1	0.00 to 590.00 Hz							
Frequency	accuracy		Digital command ±0.01% and analog	command ±0.2% (25°C±10°C) against	the maximum frequency					
Frequency	resolution		Digital setting: 0.01 Hz Analog setting: maximum frequency/4 (Ai1 terminal/Ai2 terminal: 12 bit/0 to	000 +10 V or 0 to +20 mA, Ai3 terminal 12 b	oit/-10 to +10 V)					
Control mo		lation) #2	ІМ	V/f control (fixed torque/reduced torque cascade model sensorless vector corcontrol, vector control with sensor.						
(rrequency	//voltage calcu	iation) *2	SM/PMM	Synchronous starting sensorless vector control	tor control, IVMS starting smart					
Speed fluc	tuation *3		±0.5% (during sensorless vector contr	rol)						
Accelerati	on or decelera	tion time	0.00 to 3600.00 sec (linear, S-shaped, U-shaped, reverse U-shaped, EL-S shaped)							
Display m	onitor		Output frequency, output current, outp	Output frequency, output current, output torque, trip history, I/O terminal status, I/O power *4, P-N voltage.						
Starting fu	inctions		Start after DC braking, frequency collection start, frequency entrainment start, reduced voltage start, retry start							
Stopping f	functions		Free-run stop, DC braking after deceleradjustment)	eration stop or terminal DC braking (bra	aking power, operating speed					
Stall preve	ention function	I	Overload restraining function, overcur	rent suppression function, overvoltage	suppression function					
Protective function *5 Other functions			Undervoltage error, Current detector e voltage error, Instantaneous power fa temperature error, Temperature error,	or, Braking resister Overload error, Ove rror, CPU error, External trip error, USP ilure error, Temperature detector error, Input open-phase error, IGBT error, Out ad error, Controller overload error, RS4	error, Ground fault error, Incoming over Cooling fan rotation speed reduction tput open-phase error, Thermistor error					
			V/f free settings (7 points), Upper/lower limit frequency limiter, Frequency jump, Curve acceleration/deceleration, Manual torque boost, Energy-saving operation, Analog output adjustment function, Minimum frequency, Carrier frequency adjustment, Motor electronic thermal function (free setting is also possible), Inverter electronic thermal function, External start/end (volume/ratio), Frequency input selection, Trip retry, Restart after instantaneous stop, Output of signals, Initialization settings, PID control, Automatic deceleration at power shut-off, Brake control function, and Auto-tuning for commercial switching function (online/offline).							
		Standard operator keypad	Parameter setting using arrow keys							
			Ai1/Ai2 terminal (when changing volta	Setting through input of 0 to 10 VDC voltage (input impedance: $10 \text{ k}\Omega$)						
	Eroguanov		Ai1/Ai2 terminal (when changing curre	Setting through input of 0 to 20 mA current (input impedance: 100 Ω)						
	Frequency setting	External signals *6	Ai3 terminal	Setting through input of -10 to +10 V voltage (input impedance: 10 k Ω)						
			Multistage speed terminal (use of input terminal function)	15 speed						
			Pulse string input (A/B terminal, use of input terminal function) 32 kHz × 2 at maximum							
		External port	Setting via RS485 serial communication	on (protocol: Modbus-RTU)						
	Normal rotation/	Standard operator keypad	Execution with the RUN /STOP key (normal rotation/reverse rotation can be	pe switched by setting parameters)						
	reverse rotation	External signals	Normal rotation operation (FW)/revers available (when an input terminal fund	se rotation (RV) (when an input termina ttion is assigned)	I function is assigned) 3-wire input					
Innut	Run/stop	External port	Setting via RS485 serial communication	on (protocol: Modbus-RTU (maximum:	115.2 kbps)					
Input			11 terminals (input of pulse string is available on terminal A and B) FW (Normal rotation)/RV (Reverse rotation), CF1-4 (Multistage speed 1-4), SF1-7 (Multistage speed bit 1-7), ADD (Addition of frequency), SCHG (Switching of frequency command), STA (3-wire start)/STP (3-wire stop)/F_R (3-wire normal/reverse), AHD (Retention of analog command), FUP (Increase of speed via remote operation/FDN							
	Input termin		(Deceleration via remote operation), UDC (Deletion of data via remote operation), F-OP (Forced command switching), SET (Second control), RS (Reset), JG (Jogging), DB (External current braking), 2CH (2-stage acceleration/deceleration), FRS (Free-run stop), EXT (External abnormality), USP (Prevention of restart after restoration of power), CS (Commercial switching), SFT (Soft-lock), BOK (Brake check), OLR (Overload restriction switching), KHC (Clearance of integrated input power), OKHC (Clearance of integrated output power), PID (PID1 disabled), PIDC (PID2 integration reset), SVC1-4 (PID1 multistage target values 1-4), PRO (PID gain switching), PIO (PID output switching), SLEP (SLEEP condition satisfied)/WAKE (WAKE condition satisfied), TL (Torque restriction enabled), TRQ1, 2 (Switching of torque limit 1, 2), PPI (Switching of P/PI control), CAS (Switching of control gain), FOC (Preparatory excitation), ATR (Torque control enabled), TBS (Torque bias enabled), LAC (Cancellation of acceleration/deceleration), Mi1-11 (General-purpose input 1-11), PCC (Clearance of pulse counter), ECOM (Start of EzCOM), PRG (Program run), HLD (Acceleration/deceleration stop), REN (Operation permission signal), PLA (Pulse string input A), and PLB (Pulse string input B)							
	Backup pov terminal		P+/P-: DC24V input (allowable input v	roltage: 24 V±10%)						
	STO input to	erminal	2 terminals (simultaneous input)							
	Thermistor	input terminal	1 terminal (possible to switch between positive temperature coefficient/negative temperature coefficient resistance element)							

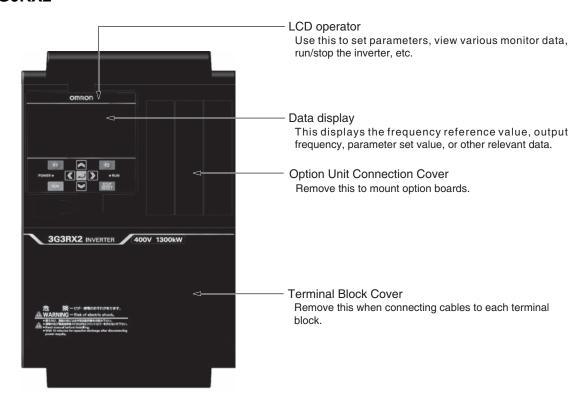
	Item		Specifications							
	Output terminal function	Transistor output 5 terminal, 1a conta	ct relay 1 point, 1c contact relay 1 point							
Output	Relay and alarm relay (16, AL)	operation), RVR (During reverse rotat command operator keypad), SETM (SOTQ (Over torque) *7, IP (During inst limitation), IPS (During power failure dithermal warning), THC (Electronic the notice), FR (Operation command sign. OL/OL2 (Overload advance notice), Esignal), OD/OD2 (PID deviation excedisconnection), Ai1Dc/Ai2Dc/Ai3Dc (A	whed signal), IRDY (Operation ready completion), FWR (During normal rotation operation), FREF (Frequency command operator keypad), REF (Operation becond control under selection), AL (Alarm signal), MJA (Severe failure signal), antaneous power failure), UV (Under insufficient voltage), TRQ (During torque eceleration), RNT (RUN time over), ONT (Power on time over), THM (Electronic ermal warning), WAC (Capacitor life advance notice), WAF (Fan life advance al), OHF (Cooling fin heating advance notice), LOC/LOC2 (Low-current signal), 8RK (Brake release), BER (Brake abnormality), ZS (Zero-speed detection sistive), FBV/FBV2 (PID feedback comparison), NDc (Communication analog disconnection Ai1/Ai2/Ai3), WCAi1/WCAi2/WCAi3 (Window comparator on result 1-7), MO1-7 (General output 1-7), and OVS (Receiving overvoltage).							
	EDM output terminal	Output for STO diagnosis								
	Monitor output terminal *8	Possible to output through selection for	rom monitor data of parameters							
EMC filter s	witching *9	Possible to enable the EMC noise filter (switching method is different depending on the model)								
External ac	cess to PC	USB Micro-B								
		ND (normal duty)	-10 to 50°C							
	Ambient temperature *10	LD (low duty)	-10 to 45°C							
		VLD (very low duty) -10 to 40°C								
Use	Storage temperature *11	-20 to 65°C								
environment	Humidity	20-90%RH (location free of condensation)	tion)							
	Vibration *12		X2-A2004 to A2220 / 3G3RX2-A4007 to A4220 X2-A2300 to A2550 / 3G3RX2-A4300 to A413K							
	Use location *13	1000 m altitude or lower (location free	from corrosive gas, oil mist, and dust)							
		Smoothing capacitor 10 years								
Expected L	ife time	Designed life of cooling fan 10 years	(models equipped with a cooling fan) free from dust							
		Memory element on the control circuit	board							
Applicable	standards *14	Conformance to UL/cUL standards, EU Directives and UK legislation, RCM, Functional Safety SIL3/PLe, KC								
Painting co	lor	Black								
Operating,	display	LCD Operator *15								
Number of	option slots	3 ports								
Other optio	ns	Braking resistor, AC reactor, DC reac	tor, noise filter, EtherCAT Communication, PG							
		l								

- *1. The output frequency range depend on the control and motor used. When running the inverter exceeding 60 Hz, check the maximum allowable frequency with the manufacturer of the motor.
- *2. When the control mode is changed, unless the motor constant is appropriately configured, you cannot obtain the desired starting torque or the inverter may trip.
- *3. The variable range of motor speed may vary depending on your system or the environment where the motor is used. Please contact us for details.
- *4. Both the input power and output power are reference values, which are not appropriate for use in calculation of efficiency values, etc. To obtain an accurate value, use an external device.
- *5. The IGBT error [E030] is generated by the protective function not only for short circuit protection but also when IGBT is damaged. Depending on the operating conditions of the inverter, the overcurrent error [E001] may occur, instead of the IGBT error.
- *6. At the factory default setting, when voltage and current on Ai1/Ai2 terminal is changed using a switch, with input of voltage at 9.8 V and current at 19.8 mA, the maximum frequency is commanded. To change characteristics, make adjustments using the analog start/end function.
- *7. The threshold for signal output varies depending on the motor to be combined with the inverter, parameter adjustment, etc.
- *8. The output data of analog voltage monitor and analog current monitor are reference values for connecting an analog meter. Due to the meter to be connected and variation in analog output circuit, the maximum output value may slightly vary from 10 V or 20 mA. To change characteristics, make adjustments using the Ao1 adjustment and Ao2 adjustment functions. Some monitor data cannot be output.
- *9. To enable the EMC filter, connect with a power supply grounded at a neutral point. Otherwise, the leakage current may increase.
- *10. Use the 400 V class inverter at an input voltage of 500 VAC or below. If input voltage exceeds 500 VAC due to fluctuation of power, use the inverter at 40°C or lower ambient temperature.
- ***11.** The storage temperature is the temperature during transport.
- *12. To be in accordance with the testing method specified in JIS C 60068-2-6: 2010 (IEC 60068-2-6:2007)
- ***13.** When the inverter is used in a location at 1000 m or higher altitude, air pressure reduces approximately 1% every 100 m elevation. Perform 1% current der- ating and conduct evaluation for every 100 m elevation.
- *14. For insulation distance, comply with UL and CE standards
- *15. When a clock function is used, the optional battery (CR2032, 3 V) is required. When you purchase, this LCD operator does not come with the battery.

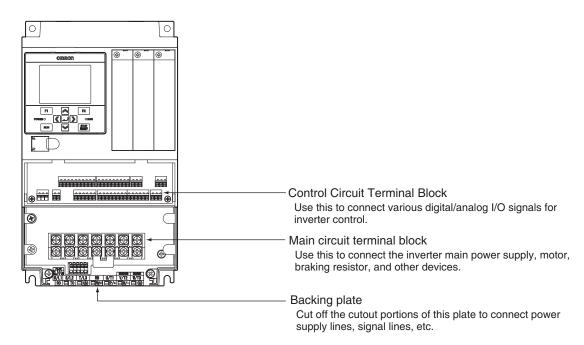
Components and Functions

Note: Example of the 3G3RX2-A2055/A2075/A2110/A4055/A4075/A4110

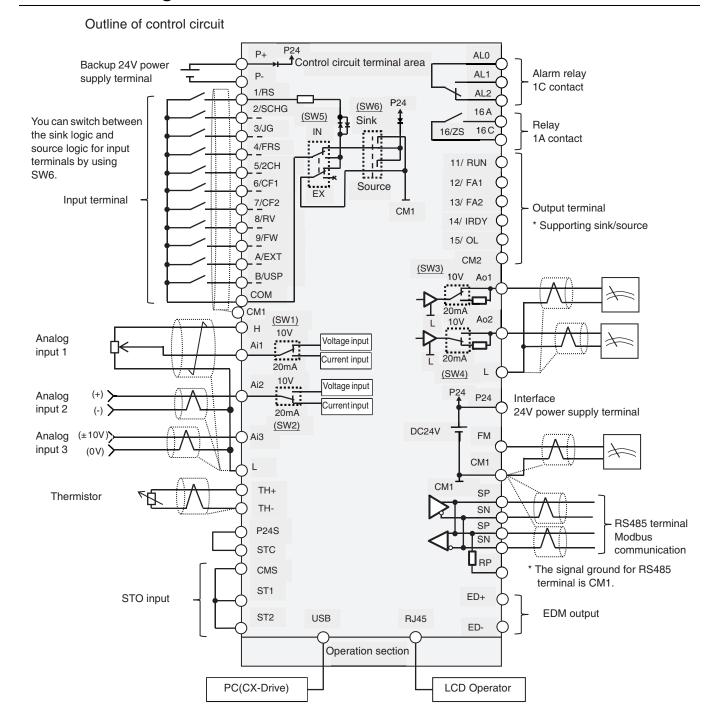
Inverter 3G3RX2



Open the terminal block cover to wire the main circuit terminal block and the control circuit terminal block. Moreover, you can open the Option Unit Connection Cover to mount option boards.



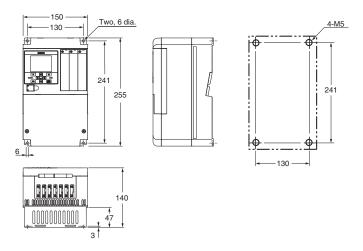
Connection Diagram



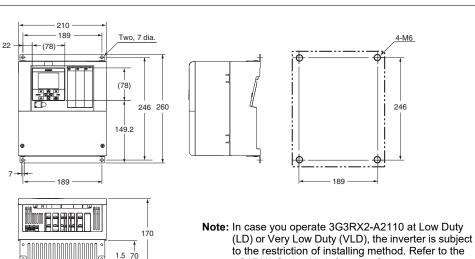
Dimensions (unit: mm)

Inverter 3G3RX2

3G3RX2-A2004 3G3RX2-A2007 3G3RX2-A2015 3G3RX2-A2022 3G3RX2-A2037 3G3RX2-A4007 3G3RX2-A4015 3G3RX2-A4022 3G3RX2-A4037

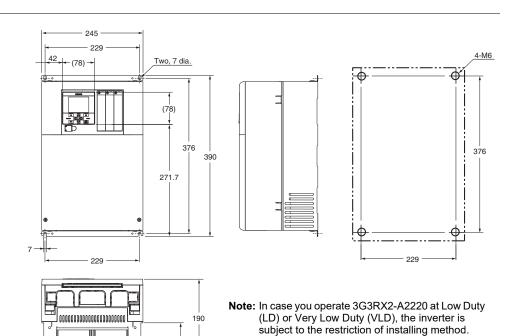


3G3RX2-A2055 3G3RX2-A2075 3G3RX2-A2110 3G3RX2-A4055 3G3RX2-A4075 3G3RX2-A4110



203

3G3RX2-A2150 3G3RX2-A2185 3G3RX2-A2220 3G3RX2-A4150 3G3RX2-A4185 3G3RX2-A4220



1.5

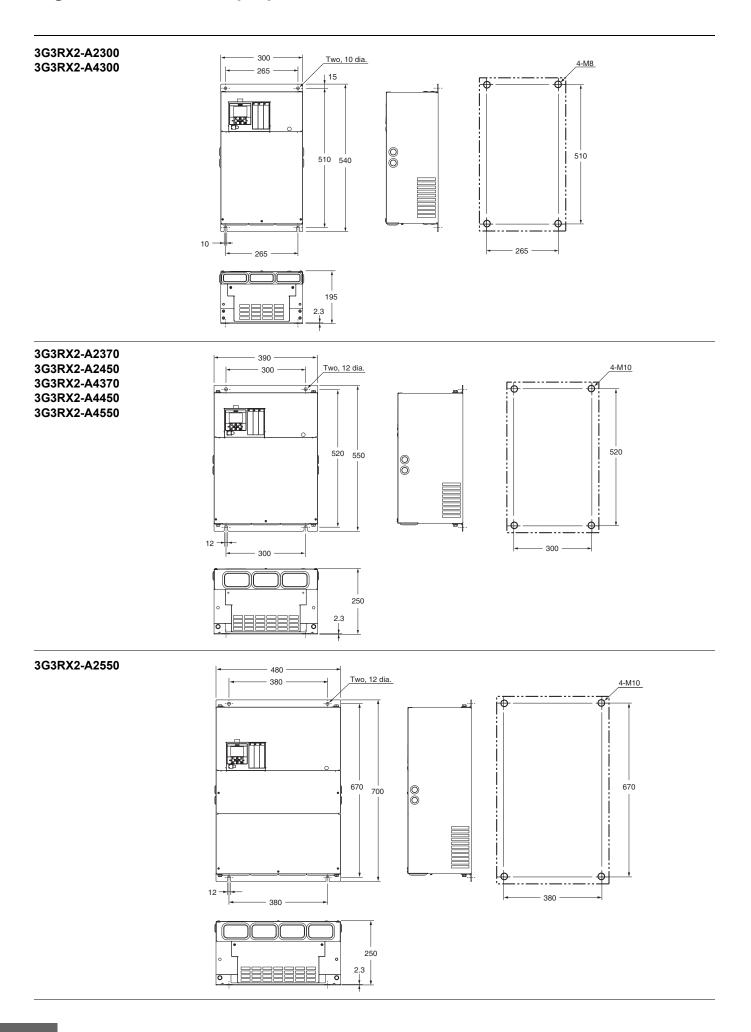
235

3G3RX2 Series High-function General-purpose Inverter User's Manual (Cat.No.I620) for details.

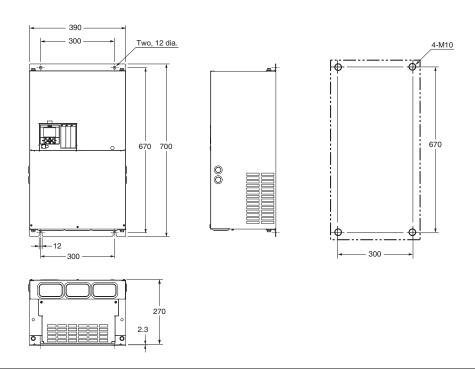
Refer to the 3G3RX2 Series High-function

General-purpose Inverter User's Manual

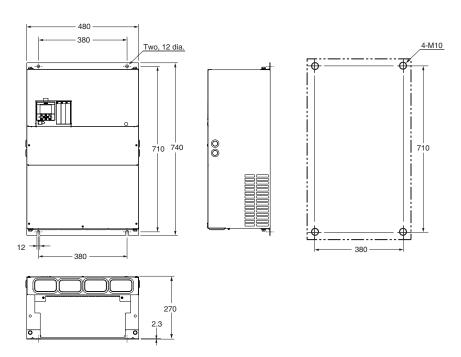
(Cat.No.I620) for details.



3G3RX2-B4750 3G3RX2-B4900



3G3RX2-B411K 3G3RX2-B413K



Communication Unit

The EtherCAT Communication Unit is an interface unit. When installed to an RX2 series high-function general-purpose inverter, it provides support for 100-Mbps EtherCAT.

Common Specifications

Item	Specifications
Model	3G3AX-RX2-ECT
Power supply	Supplied from the inverter
Protective structure	Open type (IP20)
Ambient operating temperature	-10 to 50°C
Ambient storage temperature	-20 to 65°C
Ambient operating humidity	20% to 90% (with no condensation)
Vibration *1	5.9 m/s ² (0.6 G), 10 to 55 Hz
Application environment	Indoors (There should be no corrosive gas, oil mist, or metal dust.)
Weight	100 g max. (Shipping weight: approx. 200 g)
Applicable standards	Conformance to EU Directives and UK legislation, UL/cUL, CSA, KC, RCM

^{*1.} When using the EtherCAT Communication Unit with the inverters listed below, install the unit where it is not subjected to vibration or shock. Vibration or shock can cause communication errors or malfunctions. Applicable models: 3G3RX2-A2300 to A2550, 3G3RX2-A4300 to B413K

EtherCAT Communications Specifications

Item	Specifications								
Communications standard	IEC 61158 Type12, IEC 61800-7 CiA 402 drive profile								
Physical layer	100BASE-TX (IEEE802.3)								
	RJ45 × 2 (shielded type)								
Connector	ECAT IN: EtherCAT input								
	ECAT OUT: EtherCAT output								
Communications media	Category 5 or higher (cable with double, aluminum tape and braided shielding) is recommended.								
Communications distance	Distance between nodes: 100 m max.								
Process data	Fixed PDO mapping								
Frocess data	User PDO mapping								
Mailbox (CoE)	Emergency messages, SDO requests, and SDO responses								
Synchronization mode	FreeRun mode *1								
	L/A IN (Link/Activity IN) × 1								
LED display	L/A OUT (Link/Activity OUT) × 1								
LED display	RUN × 1								

^{*1.} In FreeRun mode, slaves perform I/O processing, i.e., refresh I/O data asynchronously with the communications cycle of the master. The communications cycle is determined by the cycle time of the master. For the communications response time of the EtherCAT Communication Unit, refer to the EtherCAT Communication Unit User's Manual (Cat.No. 1663) for details.

Note that FreeRun mode in the synchronization mode has a different meaning from free-run stop of an Inverter.

Version Information

CiA402 drive profile

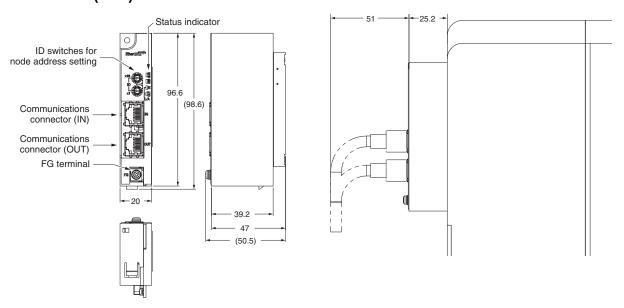
The following table gives the relationship between unit versions of EtherCAT Communication Unit and the corresponding Sysmac Studio versions.

EtherCAT Communication Unit version	Sysmac Studio
Ver. 1.0 or later	Ver. 1.47 or higher

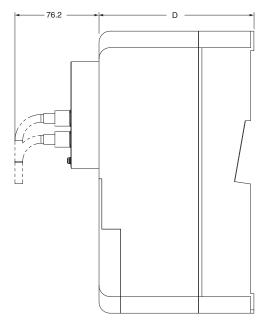
ERR × 1

Velocity mode

Dimensions (mm)



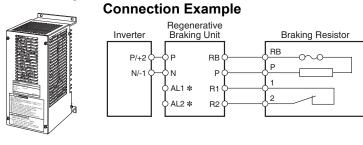
Note: For the overall depth when the EtherCAT Communication Unit is installed with an EtherCAT cable connected, add 76.2 mm to the dimension D of the Inverter. The dimension D differs depending on its capacity of the Inverter. Please refer to the manual for the Inverter.



Options

Regenerative Braking Unit 3G3AX-RBU□□

Used with a Braking Resistor when the deceleration time of the motor is needed to be reduced in the 3G3RX2.



* The alarm output terminals for the Regenerative Braking Unit. Provide a circuit to turn off the primary power supply for the Inverter when the temperature relay of the built-in resistor or optional Braking Resistor is activated.

Note: The Braking Resistor (RBA, RBB, RBC) has a built-in thermal fuse. This thermal fuse may blow due to rising temperature after the thermal relay between terminal 1 and terminal 2 issued an alarm. When the fuse blows, replace the resistor and correctly wire the alarm output terminals. If an temperature error is detected, stop the inverter and cool down well before restart.

Specifications

Built-in Resistance Type (3G3AX-RBU21/-RBU22/-RBU41)

	Class	3-phase 2	00-V class	3-phase 400-V class					
	Model name (3G3AX-)	RBU21	RBU22	RBU41 *1					
Connection res	istance	17 Ω min.	17 Ω min.	34 Ω min.					
Operating volta	ge ON/OFF	ON: 362.5 ± 5 V, OFF: 355 ± 5 V (-5% or -10% setting available)		ON: 725 ± 5 V, OFF: 710 ± 5 V (-5% or -10% setting available)					
Operation indic	ation	LED ON (Lit)							
Parallel interloc	king operation function *2	5 units max.							
	Internal resistance	120 W, 180 Ω	120 W, 20 Ω	120 W, 180 Ω × 2 in series					
	Allowable consecutive ON time	10 s max.	0.5 s max.	10 s max.					
Built-in resistor	Allowable operation cycle	Cycle 1/10 (ON for 10 s, OFF for 90 s)	Cycle 1/80 (ON for 0.5 s, OFF for 40 s)	Cycle 1/10 (ON for 10 s, OFF for 90 s)					
	Power consumption	Instantaneous 0.73 kW Short-time rating 120 W	Instantaneous 6.6 kW Short-time rating 120 W	Instantaneous 1.46 kW Short-time rating 240 W					
Protective function	Built-in resistor overheat protection	Recover Built-in temperature fuse (recover	Ć 200 mA (R [°] load), 12 V DC 500 m/	igher. A (R load), 42 V DC 200 mA (R load)					
	Ambient temperature	−10 to 50°C							
Omenation	Ambient storage temperature	−20 to 65°C							
Operating environment	Ambient operating humidity	20% to 90% (with no condensation)							
C.T.T. C.IIIICITE	Vibration	5.9 m/s ² (0.6G) 10 to 55 Hz							
	Location	At a maximum altitude of 1,000 m (without corrosive gases or dust)						
Paint color		Munselle 5Y7/1 (cooling fan: alumir	ium ground color)						

- *1. To use the braking resistor (Model: 3G3AX-RAB/RBB/RBC) for the 400-V class regenerative braking unit, be sure to remove the built-in resistor and connect two resistors of the same model in series. Using a 400-V class regenerative braking unit with only a single braking resistor connected may cause damage to the braking resistor.
- *2. Use DIP switches to set the number of connected units.
- *3. The built-in resistor has a thermal fuse. If the alarm terminals are not connected, the fuse may blow out in order to prevent the resistor from burning due to overheating. If the fuse blows out, the built-in resistor must be replaced.

Specifications

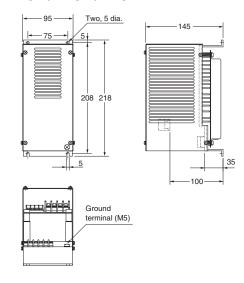
External resistor type (3G3AX-RBU23/-RBU24/-RBU42/-RBU43)

	Class	3-phase 2	00-V class	3-phas	e 400-V class					
	Model name (3G3AX-)	RBU23	RBU24	RBU42 *1	RBU43 *1					
	Continuous operation	6Ω min.	$4~\Omega$ min.	24 Ω min.	12 Ω min.					
Discharge resistance	Short-time/ operation Allowable operation cycle/ Continuous ON time	4 Ω min. 1/5 2 min	2 Ω min. 1/5 2 min	10 Ω min. 1/10 10 s	6 Ω min. 1/5 2 min					
Operating volta	ge ON/OFF	ON: 362.5 ± 5 V, OFF: 355 (–5% or –10% setting ava		ON: 725 ± 5 V, OFF: 7 (–5% or –10% setting						
Operation indic	ation	LED ON (Lit)								
Maximum numb	er of units operating in parallel *2	2 units max.								
Protective functions	Internal power module overheat protection	Built-in relay specifications Cooling fin temperature Rating of contact Minimum load		ximately 100°C or higher. 36 V DC 2 A (R load)						
	Ambient temperature	-10 to 50°C								
Onevetina	Ambient storage temperature	−20 to 65°C								
Operating environment	Ambient operating humidity	20% to 90% (with no cond	ensation)							
On vironinion	Vibration	4.9 m/s ² (0.5G) 10 to 55 H	Z							
	Location	At a maximum altitude of 1	,000 m (without corrosive	gases or dust)						
Paint color		Munselle 5Y7/1 (cooling fan: aluminum ground color)								

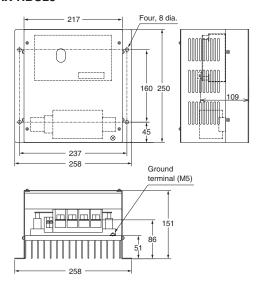
- ***1.** To use the braking resistor (3G3AX-RAB/RBB/RBC) for the 400-V class regenerative braking unit, be sure to remove the built-in resistor and connect two resistors of the same model in series. Using a 400-V class regenerative braking unit with only a single braking resistor connected may cause damage to the braking resistor.
- *2. Use DIP switches to set the number of connected units.

Dimensions (Unit: mm)

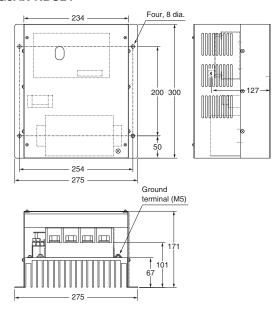
3G3AX-RBU21/-RBU22/-RBU41



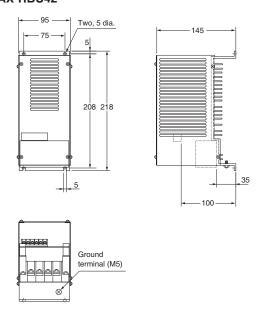
3G3AX-RBU23



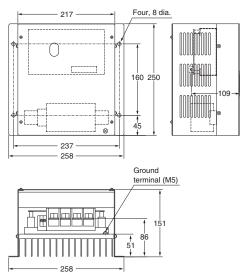
3G3AX-RBU24



3G3AX-RBU42

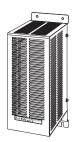


3G3AX-RBU43



Braking Resistor 3G3AX-RBA/-RBB/-RBC□□□□□

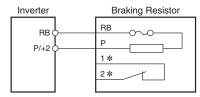
Consumes the regenerative motor energy with a resistor to reduce deceleration time.







Connection Example



*The alarm output terminals for the Braking Resistor. Provide a circuit to turn off the primary power supply for the Inverter when the temperature relay of the Braking Resistor is activated.

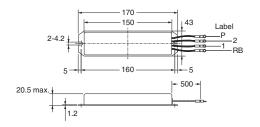
Specifications

Model		(ict type BA⊟⊟⊟	1)	(ard type BB□□□□)	Medium capacity type (3G3AX-RBC□□□□)			
		1201	1202	1203	1204	2001	2002	3001	4001	4001	6001	12001	
Resistance	Capacity		120) W		200	W	300 W	400 W	400 W	600 W	1200 W	
Resistance	Resistance (Ω)	180	100	50	35	180	100	50	35	50	35	17	
Allowable braki	brakingfrequency (%) 5 2.5 1.5 1.0 10 7.5 7.5 7.5 10		10										
Allowable conti	nuousbraking time (s)	20	12	5	3		30		20	10			
Weight (kg)			0.	27		0.	97	1.68	2.85	2.5	3.6	6.5	
Fault detection	function	Minimum Normally	current: 5 ON (NC c	mA, ontact)	overy impo	/ AC 2 A n	nax.)			Built-in temperature relay, Normally ON (NC contact) Contact capacity:240 V AC 3 A (R load) 0.2 A (L load), 36 V DC 2 A (R load)			
	Ambient operating temperature	-10 to 50)°C										
	Ambient storage temperature	-20 to 65	5°C										
General specifications	Ambient operating humidity	20% to 9	0% (RH) v	vith no cor	ndensation								
	Vibration	5.9 m/s (0.6 G) 10 t	to 55 Hz C	omplies w	ith JISC09	11						
	Location	At a max	imum altitu	ude of 1,00	00 m (with	out corrosi	ve gases	or dust)					
	Cooling method	Self-cooli	ing										

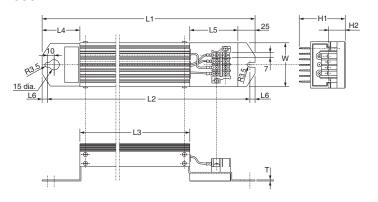
^{*}Built-in resistors are equipped with thermal fuses. If the alarm is not connected, the fuse may blow to prevent burnout due to overheating. If the fuse blows, the built-in resistor will need to be replaced.

Dimensions (Unit: mm)

3G3AX-RBA



3G3AX-RBB

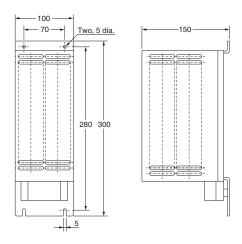


Model	Dimensions (mm)									
Wodel	L1	L2	L3	L4	L5	L6				
3G3AX-RBB2001	310	295	160	55	70	7.5				
3G3AX-RBB2002	310	295	160	55	70	7.5				
3G3AX-RBB3001	470	455	320	55	70	7.5				

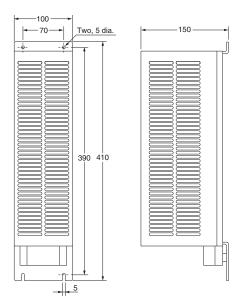
Model	Dir	nensi	ons (m	ım)	Weight	Те	rminal	
Wodei	H1	H2	W	Т	[kg]	S	screws	
3G3AX-RBB2001	67	12	64	1.6	0.97			
3G3AX-RBB2002	67	12	64	1.6	0.97		M3.5	
3G3AX-RBB3001	67	12	64	1.6	1.68		IVIO.O	
3G3AX-RBB4001	94	15	76	2	2.85			

3G3AX-RBB4001 435 422 300 50 60 6.5

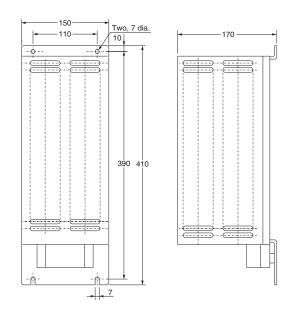
3G3AX-RBC4001



3G3AX-RBC6001



3G3AX-RBC12001



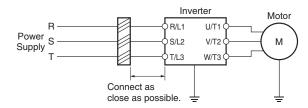
Radio Noise Filter 3G3AX-ZCL□

Connected to the inverter input/output cables to reduce noise coming into the inverter from the power supply line and noise flowing from the inverter into the power supply line.





Connection Example



Note 1: Wind each of three phase wires in the same direction.

2: Can be used on both the input and output sides of the Inverter.

Specifications 3G3AX-ZCL1

Applicable		200 V	class		400 V class						
Inverter	Inp	out	out	put	Inp	out	output				
capacity (kW)	Quan- tity	No. of turns	Quan- tity	No. of turns	Quan- tity	No. of turns	Quan- tity	No. of turns			
0.2	1	4	1	4	1	4	1	4			
0.4	1	4	1	4	1	4	1	4			
0.75	1	4	1	4	1	4	1	4			
1.5	1	4	1	4	1	4	1	4			
2.2	1	4	1	4	1	4	1	4			
3.0	1	4	1	4	1	4	1	4			
3.7	1	4	1	4	1	4	1	4			
4.0	1	4	1	4	1	4	1	4			
5.5	1	4	1	4	1	4	1	4			
7.5	1	4	1	4	1	4	1	4			
11	1	3	1	3	1	4	1	4			
15	1	2	1	2	1	4	1	4			

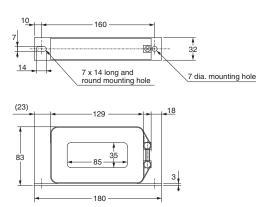
Specifications 3G3AX-ZCL2

Applicable		200 V	class		400 V class					
Inverter	Inp	out	out	put	Inp	out	output			
capacity (kW)	Quan- tity	No. of turns								
0.1	1	4	1	4	1	4	1	4		
0.2	1	4	1	4	1	4	1	4		
0.4	1	4	1	4	1	4	1	4		
0.75	1	4	1	4	1	4	1	4		
1.5	1	4	1	4	1	4	1	4		
2.2	1	4	1	4	1	4	1	4		
3.0	1	4	1	4	1	4	1	4		
3.7	1	4	1	4	1	4	1	4		
4.0	1	4	1	4	1	4	1	4		
5.5	1	4	1	4	1	4	1	4		
7.5	1	4	1	4	1	4	1	4		

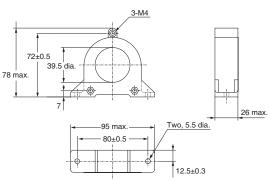
Note: When the inverter is used in the LD or VLD mode, select a radio noise filter according to the capacity of the used motor that is more than one size larger than in the ND mode.

Dimensions (Unit: mm)

3G3AX-ZCL1



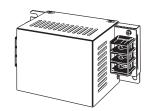
3G3AX-ZCL2

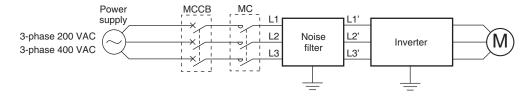


Input Noise Filter 3G3AX-NFI□□

Reduces noise coming into the inverter from the power supply line and noise flowing from the inverter into the power supply line. Connect as close to the Inverter as possible.

Connection Example





Specifications

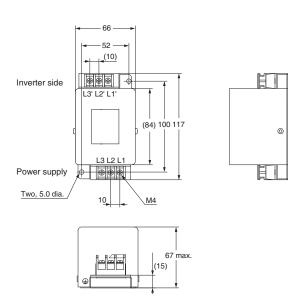
		Inver	ter				Input noise	e filter specific	ations	
Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model	Max. input voltage	Rated input current (at 50°C) [A]	Heat generation [W]	Leakage current (at 60 Hz)
			ND	0.4	3.3					
	0.4	3G3RX2-A2004	LD	0.75	3.9	3G3AX-NFI21		6	3	
			VLD	0.75	3.9	303AX-111 121		0	3	
			ND	0.75	5.5					
	0.75	3G3RX2-A2007	LD	1.5	7.2					
			VLD	1.5	7.2	3G3AX-NFI22		10	4	
			ND	1.5	8.3					
	1.5	3G3RX2-A2015	LD	2.2	10.8					
			VLD	2.2	10.8					
			ND	2.2	12	3G3AX-NFI23		20	6	
	2.2	3G3RX2-A2022	LD	3.7	13.9	3G3AX-N1 123		20	U	
			VLD	3.7	13.9					
			ND	3.7	18					
	3.7	3G3RX2-A2037	LD	5.5	23					
			VLD	5.5	23	3G3AX-NFI24		30	9	
			ND	5.5	26					
	5.5	3G3RX2-A2055	LD	7.5	37					
			VLD	7.5	37	3G3AX-NFI25		40	12	
			ND	7.5	35					
	7.5	3G3RX2-A2075	LD	11	48					
			VLD	11	48	3G3AX-NFI26		60	17	1.5 mA
			ND	11	51		250 VAC +10%			max.
200-V class	11	3G3RX2-A2110	LD	15	64		+1070			(250 VAC)
Class			VLD	15	64	3G3AX-NFI27		80	21	
			ND	15	70					
	15	3G3RX2-A2150	LD	18.5	80					Ī
			VLD	18.5	80	3G3AX-NFI28		100	23	
			ND	18.5	84					
	18.5	3G3RX2-A2185	LD	22	94					
			VLD	22	94					
			ND	22	105	000477 NEI00		450	45	
	22	3G3RX2-A2220	LD	30	120	3G3AX-NFI29		150	45	
			VLD	30	120					
			ND	30	133					
	30	3G3RX2-A2300	LD	37	150					
			VLD	37	150	3G3AX-NFI2A		200	50	
			ND	37	160					
	37	3G3RX2-A2370	LD	45	186					
			VLD	45	186	3G3AX-NFI2B		250	68	
			ND	45	200				00	
	45	3G3RX2-A2450	LD	55	240					
			VLD 55 240 3G3AX-NFI2C	300	56					
			ND	55	242	, , , , , , , , , , , , , , , , , , , ,		- 50		
	55	3G3RX2-A2550	LD	75	280					
	33	2 201012-712000	VLD	75	280					
	1	1	V - D	, ,	200	l .				1

		Inver	ter				Input noise	e filter specific	ations	
Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model	Max. input voltage	Rated input current (at 50°C) [A]	Heat generation [W]	Leakage current (at 60 Hz)
			ND	0.75	2.8					
	0.75	3G3RX2-A4007	LD	1.5	4.3					
			VLD	1.5	4.3					
			ND	1.5	4.2	3G3AX-NFI41		7	2	
	1.5	3G3RX2-A4015	LD	2.2	5.9					
			VLD	2.2	5.9					
			ND	2.2	5.8					
	2.2	3G3RX2-A4022	LD	3.7	8.1					
			VLD	3.7	8.1	3G3AX-NFI42		10	4	
			ND	3.7	9.8					
	3.7	3G3RX2-A4037	LD	5.5	13.3					
			VLD	5.5	13.3					
			ND	5.5	15	3G3AX-NFI43		20	6	
	5.5	3G3RX2-A4055	LD	7.5	20	000,000		20	Ü	
			VLD	7.5	20					
			ND	7.5	21					
	7.5	3G3RX2-A4075	LD	11	24					
			VLD	11	24	3G3AX-NFI44		30	9	
			ND	11	28					7.5 4
	11	3G3RX2-A4110	LD	15	32		480 VAC			7.5 mA max.
400-V			VLD	15	32	3G3AX-NFI45	+10%	40	12	(480 VAC)
class			ND	15	35					
	15	3G3RX2-A4150	LD	18.5	41					
			VLD	18.5	41	3G3AX-NFI46		50	15	
			ND	18.5	42					
	18.5	3G3RX2-A4185	LD	22	47					
			VLD	22	47	3G3AX-NFI47		60	17	
			ND	22	53					
	22	3G3RX2-A4220	LD	30	63					
			VLD	30	63	3G3AX-NFI48		80	21	
			ND	30	64					
	30	3G3RX2-A4300	LD	37	77					
			VLD	37	77	3G3AX-NFI49		100	23	
			ND	37	83					
	37	3G3RX2-A4370	LD	45	94					
			VLD	45	94					
			ND	45	100	3G3AX-NFI4A		150	45	
	45	3G3RX2-A4450	LD	55	116			.50		
			VLD	55	116					
			ND	55	121					
	55	3G3RX2-A4550	LD	75	149					
			VLD	75	149					

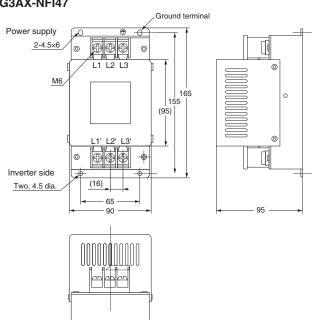
Dimensions (Unit: mm)

Model	Case, enclosure rating	Terminal size	Wire diameter	Weight [kg]
3G3AX-NFI21	Plastic, IP00	M4	1.25 mm ²	0.5
3G3AX-NFI22	Plastic, IP00	M4	2 mm ²	0.6
3G3AX-NFI23	Plastic, IP00	M4	2 mm², 3.5 mm²	0.7
3G3AX-NFI24	Plastic, IP00	M4	5.5 mm ²	0.8
3G3AX-NFI25	Plastic, IP00	M5	8 mm ²	1.4
3G3AX-NFI26	Plastic, IP00	M5	14 mm ²	1.8
3G3AX-NFI27	Metal, IP00	M6	3.6	
3G3AX-NFI28	Metal, IP00	M8	30 mm ²	4.6
3G3AX-NFI29	Metal, IP00	M8	38 mm², 60 mm²	9.0
3G3AX-NFI2A	Metal, IP00	M10	100 mm ² or 38 mm ² , 2 wires parallel	16
3G3AX-NFI2B	Metal, IP00	M10	100 mm² or 38 mm², 2 wires parallel	16
3G3AX-NFI2C	Metal, IP00	M10	150 mm ² or 60 mm ² , 2 wires parallel	23
3G3AX-NFI41	Plastic, IP00	M4	1.25 mm², 2 mm²	0.7
3G3AX-NFI42	Plastic, IP00	M4	2 mm ²	0.7
3G3AX-NFI43	Plastic, IP00	M4	2 mm², 3.5 mm²	0.7
3G3AX-NFI44	Plastic, IP00	M4	5.5 mm ²	0.8
3G3AX-NFI45	Plastic, IP00	M5	8 mm ²	1.4
3G3AX-NFI46	Plastic, IP00	M5	14 mm²	1.6
3G3AX-NFI47	Plastic, IP00	M5	14 mm²	1.8
3G3AX-NFI48	Metal, IP00	M6	22 mm ²	3.6
3G3AX-NFI49	Metal, IP00	M8	38 mm ²	4.6
3G3AX-NFI4A	Metal, IP00	38 mm², 60 mm²	9.0	

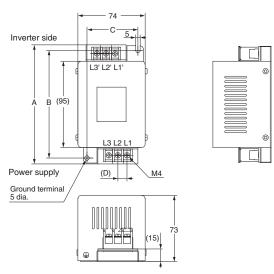
3G3AX-NFI21 3G3AX-NFI22



3G3AX-NFI25/3G3AX-NFI26 3G3AX-NFI45/3G3AX-NFI46 3G3AX-NFI47

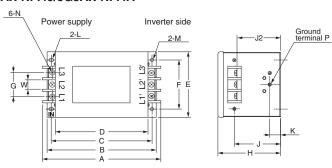


3G3AX-NFI23/3G3AX-NFI24 3G3AX-NFI41/3G3AX-NFI42 3G3AX-NFI43/3G3AX-NFI44



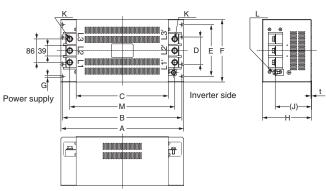
Model		Dimension	ons (mm)	
Wodel	Α	В	С	D
3G3AX-NFI23	128	118	56	10
3G3AX-NFI24	144	130	56	11
3G3AX-NFI41	144	130	56	11
3G3AX-NFI42	144	130	56	11
3G3AX-NFI43	144	130	56	11
3G3AX-NFI44	144	130	56	11

3G3AX-NFI27/3G3AX-NFI28 3G3AX-NFI29/3G3AX-NFI48 3G3AX-NFI49/3G3AX-NFI4A



Model		Dimensions (mm)														
Wodei	Α	В	С	D	Е	F	G	Н	J	J2	K	L	M	N	Р	W
3G3AX-NFI27	217	200	185	170	120	90	44	115	85	82	20	R2.75, Length 7	5.5 dia.	M6	M4	17
3G3AX-NFI28	254	230	215	200	150	120	57	115	80	75	30	R3.75, Length 8	6.5 dia.	M8	M6	23
3G3AX-NFI29	314	300	280	260	200	170	57	130	90	85	35	R3.75, Length 8	6.5 dia.	M8	M6	23
3G3AX-NFI48	217	200	185	170	120	90	44	115	85	85	20	R2.75, Length 7	5.5 dia.	M6	M4	17
3G3AX-NFI49	254	230	215	200	150	120	57	115	80	75	30	R3.75, Length 8	6.5 dia.	M8	M6	23
3G3AX-NFI4A	314	300	280	260	200	170	57	130	90	85	35	R3.75, Length 8	6.5 dia.	M8	M6	23

3G3AX-NFI2A/3G3AX-NFI2B 3G3AX-NFI2C



Model	Dimensions (mm)														
Woder	Α	В	С	D	E	F	G	Н	J	K	L	М	N		
3G3AX-NFI2A	450	430	338	100	190	230	7	180	(133)	M10	M8	385	1.0		
3G3AX-NFI2B	450	450	450 450	430 330	550	336 100	100 190	250	,	100	(133)	IVITO	IVIO	303	1.0
3G3AX-NFI2C	500	475	400		160	200	12	180	(133)	M10	M8	445	1.2		

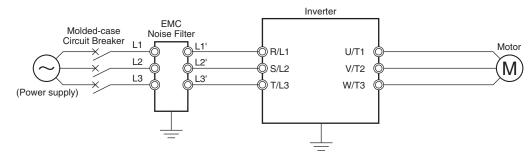
EMC Noise Filter 3G3AX-EFI□□□

Separately installed option used to comply with the EC's EMC Directives. Select a filter appropriate for the Inverter model.

Although an EMC Noise Filter is built into the RX2, it may be necessary to provide another EMC Noise Filter when the cable between the Motor and the Inverter is long.



Connection Example



Specifications

		Inver	ter				EMC n	oise filter s	pecification	s	
Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model	Max. input voltage	Rated input current [A]	Heat generation [W]	Leakage current (at 480 VAC 60 Hz)	Class
			ND	0.4	3.3						
	0.4	3G3RX2-A2004	LD	0.75	3.9	2024V EE144		7	4	150 mA max.	
			VLD	0.75	3.9	3G3AX-EFI41		,	4	150 mA max.	
			ND	0.75	5.5						
	0.75	3G3RX2-A2007	LD	1.5	7.2						
			VLD	1.5	7.2	3G3AX-EFI42		10	4	150 mA max.	
			ND	1.5	8.3						
	1.5	3G3RX2-A2015	LD	2.2	10.8						
			VLD	2.2	10.8						
			ND	2.2	12	3G3AX-EFI43		20	8	170 mA max.	
	2.2	3G3RX2-A2022	LD	3.7	13.9	3G3AX-L1 143		20	0	170 IIIA IIIax.	
			VLD	3.7	13.9						
			ND	3.7	18						
	3.7	3G3RX2-A2037	LD	5.5	23						
			VLD	5.5	23	3G3AX-EFI44		30	9	170 mA max.	
			ND	ND 5.5 26							
	5.5	3G3RX2-A2055	LD	7.5	37						
			VLD	7.5	37	3G3AX-EFI45		40	15	170 mA max.	
			ND	7.5	35		480 VAC +10%				Α
200-V class	7.5	3G3RX2-A2075	LD	11	48		1 10%				
0.000			VLD	11	48	3G3AX-EFI47		60	15	250 mA max.	
			ND	11	51						
	11	3G3RX2-A2110	LD	15	64						
			VLD	15	64	3G3AX-EFI48		80	21	250 mA max.	
			ND	15	70						
	15	3G3RX2-A2150	LD	18.5	80						
			VLD	18.5	80	3G3AX-EFI49		100	23	250 mA max.	
			ND	18.5	84						
	18.5	3G3RX2-A2185	LD	22	94						
			VLD	22	94						
			ND	22	105	2024V EE144		150	45	250 m A may	
	22	3G3RX2-A2220	LD	30	120	3G3AX-EFI4A		150	45	250 mA max.	
			VLD	30	120						
			ND	30	133						
	30	3G3RX2-A2300	LD	37	150		1				1
			VLD	37	150	3G3AX-EFI4B		200	50	250 mA max.	
			ND	37	160						
	37	3G3RX2-A2370	LD	45	186						
			VLD	45	186						

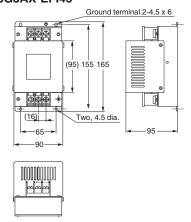
		Inver	ter			EMC noise filter specifications								
Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model	Max. input voltage	Rated input current [A]	Heat generation [W]	Leakage current (at 480 VAC 60 Hz)	Class			
			ND	0.75	2.8									
	0.75	3G3RX2-A4007	LD	1.5	4.3					Leakage current (at 480 VAC				
			VLD	1.5	4.3									
			ND	1.5	4.2	3G3AX-EFI41		7	4	150 mA max.				
	1.5	3G3RX2-A4015	LD	2.2	5.9									
			VLD	2.2	5.9									
			ND	2.2	5.8									
	2.2	3G3RX2-A4022	LD	3.7	8.1									
			VLD	3.7	8.1	3G3AX-EFI42		10	4	150 mA max.				
			ND	3.7	9.8									
	3.7	3G3RX2-A4037	LD	5.5	13.3									
			VLD	5.5	13.3									
			ND	5.5	15	00041/ 55140				470				
	5.5	3G3RX2-A4055	LD	7.5	20	3G3AX-EFI43		20	8	150 mA max. 170 mA max. 170 mA max. 170 mA max. 250 mA max. 250 mA max. 250 mA max.				
			VLD	7.5	20									
			ND	7.5	21									
	7.5	3G3RX2-A4075	LD	11	24									
			VLD	11	24	3G3AX-EFI44		30	9	170 mA max.				
			ND	11	28									
	11	3G3RX2-A4110	LD	15	32									
			VLD	15	32	3G3AX-EFI45		40	15	170 mA max.				
			ND	15	35									
	15	3G3RX2-A4150	LD	18.5	41		480 VAC							
400-V			VLD	18.5	41	3G3AX-EFI46	+10%	50	15	250 mA max.	Α			
class			ND	18.5	42									
	18.5	3G3RX2-A4185	LD	22	47									
		0001012711100	VLD	22	47	3G3AX-EFI47		60	15	250 mA max				
			ND	22	53	000,012.11.				200 113 111.011				
	22	3G3RX2-A4220	LD	30	63									
		0001012711220	VLD	30	63	3G3AX-EFI48		80	21	250 mA max				
			ND	30	64	000,012,110				200 113 111.011				
	30	3G3RX2-A4300	LD	37	77									
		0001012711000	VLD	37	77	3G3AX-EFI49		100	23	250 mA max				
			ND	37	83	000,012,110				200 113 111.011				
	37	3G3RX2-A4370	LD	45	94		-							
		0001012711010	VLD	45	94					150 mA max. 170 mA max. 170 mA max. 250 mA max. 250 mA max. 250 mA max. 250 mA max.				
			ND	45	100									
	45	3G3RX2-A4450	LD	55	116	3G3AX-EFI4A		150	45	250 mA max.				
	40	00010/27/4400	VLD	55	116									
			ND	55	121									
	55	3G3RX2-A4550	LD	75	149		-							
	33	3G31\X2-A4330	VLD	75	149									
	75	3G3RX2-B4750	ND LD	75 90	164 176	3G3AX-EFI4B		200	50	250 mA max.				
	10	JGJRAZ-D4/30												
			VLD	90	176									
	00	2C2BV2 B4000	ND	90	194						-			
	90	3G3RX2-B4900	LD VLD	110 110	199 199									

Dimensions (Unit: mm)

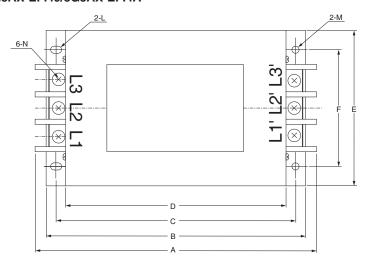
Model	Case, enclosure rating	Screw size	Wire size	Weight [kg]
3G3AX-EFI41		N/4	1.25 mm², 2 mm²	0.7
3G3AX-EFI42		M4	2 mm ²	0.7
3G3AX-EFI43	Plastic, IP00		2 mm², 3.5 mm²	1.0
3G3AX-EFI44		M5	5.5 mm ²	1.3
3G3AX-EFI45			8 mm ²	1.4
3G3AX-EFI46			14 mm ²	2.9
3G3AX-EFI47		M6	14 mm ²	3.0
3G3AX-EFI48	M-t-L IDOO		22 mm ²	3.6
3G3AX-EFI49	Metal, IP00	140	30 mm², 38 mm²	4.3
3G3AX-EFI4A		M8	38 mm², 60 mm²	9.0
3G3AX-EFI4B		M10	100 mm ² or 38 mm ² , 2 wires parallel	16.0

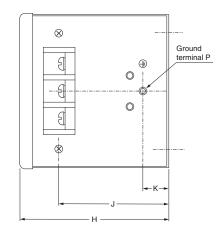
3G3AX-EFI41 3G3AX-EFI42

3G3AX-EFI43/3G3AX-EFI44 3G3AX-EFI45



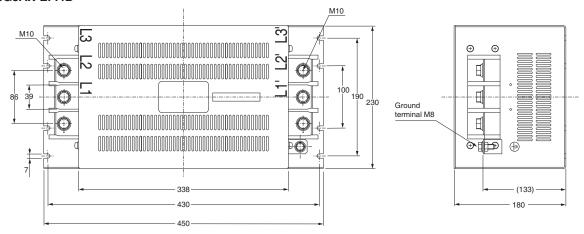
3G3AX-EFI46/3G3AX-EFI47/3G3AX-EFI48 3G3AX-EFI49/3G3AX-EFI4A





Model		Dimensions [mm]												
Wodei	Α	В	С	D	E	F	Н	J	K	L	М	N	Р	
3G3AX-EF146														
3G3AX-EF147	217	220	185	170	120	90	115	85	20	R2.75, Length 7	5.5 dia.	M6	M4	
3G3AX-EF148														
3G3AX-EF149	254	230	215	200	150	120	115	80	30	R3.25, Length 8	6.5 dia.	M8	M6	
3G3AX-EF14A	314	300	280	260	200	170	130	90	35	R3.25, Length 8	6.5 dia.	M8	M6	

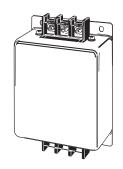
3G3AX-EFI4B

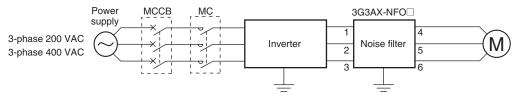


Output Noise Filter 3G3AX-NFO□□

Reduces noise generated by the Inverter. Connect as close to the Inverter as possible.

Connection Example



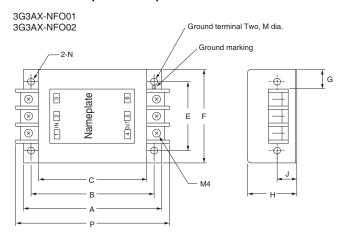


Specifications

		Inve		Output noise filter specifications					
Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model	Rated voltage	Rated input current [A]	Weight [kg]
			ND	0.4	3.0				
	0.4	3G3RX2-A2004	LD	0.75	3.7	2C2AV NEO04		6	0.7
			VLD	0.75	3.7	3G3AX-NFO01		6	0.7
			ND	0.75	5.0				
	0.75	3G3RX2-A2007	LD	1.5	6.3				
			VLD	1.5	6.3				
			ND	1.5	7.5	3G3AX-NFO02		12	0.9
	1.5	3G3RX2-A2015	LD	2.2	9.4	3G3AX-NFUUZ		12	0.9
			VLD	2.2	9.4				
			ND	2.2	10.5				
	2.2	3G3RX2-A2022	LD	3.7	12				
			VLD	3.7	12				
			ND	3.7	16.5	3G3AX-NFO03		25	2.1
	3.7	3G3RX2-A2037	LD	5.5	19.6	3G3AA-NFO03		23	2.1
			VLD	5.5	19.6				
			ND	5.5	24				
	5.5	3G3RX2-A2055	LD	7.5	30				
			VLD	7.5	30				
		3G3RX2-A2075	ND	7.5	32	3G3AX-NFO04	500 VAC	50	3.7
:00-V :lass	7.5		LD	11	44	3G3AA-NFO04		50	3.1
			VLD	11	44				
			ND	11	46				
	11	3G3RX2-A2110	LD	15	58				
			VLD	15	58	3G3AX-NFO05		75	5.7
			ND	15	64				
	15	3G3RX2-A2150	LD	18.5	73				
			VLD	18.5	73				
			ND	18.5	76	3G3AX-NFO06		100	8.4
	18.5	3G3RX2-A2185	LD	22	85	3G3AA-NFO00		100	0.4
			VLD	22	85				
			ND	22	95				
	22	3G3RX2-A2220	LD	30	113				
			VLD	30	113				
			ND	30	121	3G3AX-NFO07		150	9.0
	30	3G3RX2-A2300	LD	37	140	SUSAA-NEUU/		130	9.0
			VLD	37	140				
			ND	37	145				
	37	3G3RX2-A2370	LD	45	169				
			VLD	45	169				

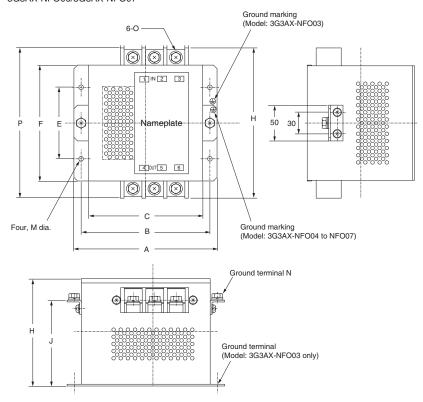
		Inve	erter			Outpu	t noise filte	r specification	s
Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model	Rated voltage	Rated input current [A]	Weight [kg]
			ND	0.75	2.5				
	0.75	3G3RX2-A4007	LD	1.5	3.1				
			VLD	1.5	3.1				
			ND	1.5	3.8	3G3AX-NFO01		6	0.7
	1.5	3G3RX2-A4015	LD	2.2	4.8				
			VLD	2.2	4.8				
			ND	2.2	5.3				
	2.2	3G3RX2-A4022	LD	3.7	6.7				
			VLD	3.7	6.7	3G3AX-NFO02		12	0.9
			ND	3.7	9.0		_		
	3.7	3G3RX2-A4037	LD	5.5	11.1				
			VLD	5.5	11.1				
			ND	5.5	14				
	5.5	3G3RX2-A4055	LD	7.5	16				
	7.5		VLD	7.5	16	3G3AX-NFO03		25	2.1
			ND	7.5	19				
		3G3RX2-A4075	LD	11	22				
			VLD	11	22				
			ND	11	25				
	11	3G3RX2-A4110	LD	15	29				
		0001012-714-110	VLD	15	29				
		3G3RX2-A4150	ND	15	32		500 VAC		
00-V	15		LD	18.5	37		300 VAC		
lass	10		VLD	18.5	37	3G3AX-NFO04		50	3.7
			ND	18.5	38	303/2/-111 004		30	5.7
	18.5	3G3RX2-A4185	LD	22	43				
	10.5	3G3RAZ-A4163	VLD	22	43				
			ND	22	43				
	00	202000 44000	LD	30	57		-		
	22	3G3RX2-A4220	VLD	30					
					57				
	20	202000 44202	ND	30	58	3G3AX-NFO05		75	5.7
	30	3G3RX2-A4300	LD	37	70				
			VLD	37	70				
		0000000 44000	ND	37	75		_		
	37	3G3RX2-A4370	LD	45	85	000477 115005		460	
			VLD	45	85	3G3AX-NFO06		100	8.4
	4-	000000	ND	45	91		-		
	45	3G3RX2-A4450	LD	55	105				
			VLD	55	105				
			ND	55	112	3G3AX-NFO07		150	9.0
	55	3G3RX2-A4550	LD	75	135				
			VLD	75	135				
			ND	75	149				
	75	3G3RX2-B4750	LD	90	160				
			VLD	90	160				

Dimensions (Unit: mm)



Model		Dimensions [mm]											
	Α	В	С	E	F	G	Н	J	M	Р	N		
3G3AX-NFO01	140	125	110	70	98	22	50	20	4.5	156	2-R2.25 Length 6		
3G3AX-NFO02	160	145	130	80	113	30	70	25	5.5	176	2-R2.75 Length 7		

3G3AX-NFO03/3G3AX-NFO04/3G3AX-NFO05 3G3AX-NFO06/3G3AX-NFO07



Model		Dimensions [mm]											
Model	Α	В	С	E	F	Н	J	M	N	0	P		
3G3AX-NFO03	160	145	130	80	112	120		6.5 dia.		M4	154		
3G3AX-NFO04	200	180	160	100	162	150	120	6.5 dia.	M5	M5	210		
3G3AX-NFO05	220	200	180	100	182	170	140	6.5 dia.	M6	M6	230		
3G3AX-NFO06	220	200	180	100	182	170	140	6.5 dia.	M8	M8	237		
3G3AX-NFO07	240	220	200	150	202	170	140	6.5 dia.	M8	M8	257		

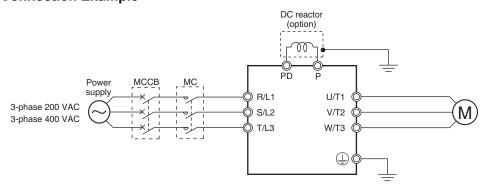
DC Reactor 3G3AX-DL□□□□

Used to suppress harmonic current generated from the Inverter.

Suppresses harmonic current better than the AC Reactor and can be used with the AC Reactor.



Connection Example



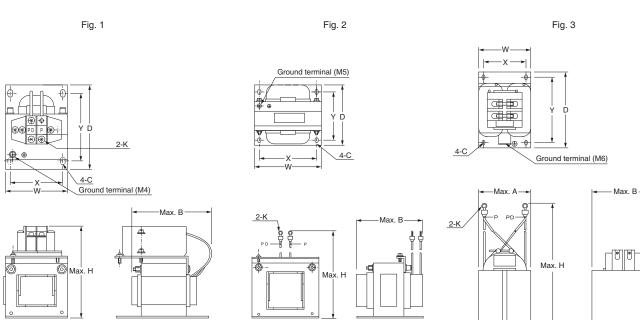
Specifications

		Inver	ter			DC reactor specifications						
Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model	Inductance [mH]	Heat generation [W]	Operating ambient temperature /humidity	Location		
			ND	0.4	3.3	3G3AX-DL2004	10.7	8				
	0.4	3G3RX2-A2004	LD	0.75	3.9							
			VLD	0.75	3.9	3G3AX-DL2007	6.75	15				
			ND	0.75	5.5							
	0.75	3G3RX2-A2007	LD	1.5	7.2							
			VLD	1.5	7.2	3G3AX-DL2015	3.51	25				
			ND	1.5	8.3							
	1.5	3G3RX2-A2015	LD	2.2	10.8							
			VLD	2.2	10.8	3G3AX-DL2022	2.51	35				
			ND	2.2	12							
	2.2	3G3RX2-A2022	LD	3.7	13.9							
			VLD	3.7	13.9	3G3AX-DL2037	1.60	45				
			ND	3.7	18							
	3.7	3G3RX2-A2037	LD	5.5	23							
		5.5 3G3RX2-A2055	VLD	5.5	23	3G3AX-DL2055	1.11	55				
			ND	5.5	26							
	5.5		LD	7.5	37	00041/ 01 0075	0.04	0.5				
			VLD	7.5	37 35	3G3AX-DL2075	0.84	95		At an		
	7.5	2C2DV2 A2075	ND	7.5					-	altitude of		
	7.5	3G3RX2-A2075			2C2AV DI 2440	0.50	90		1,000 m			
			ND	11	51	3G3AX-DL2110	0.59	80	-10 to 50°C	max.;		
200-V	11	3G3RX2-A2110	LD	15	64				20% to 90%	indoors (without		
class		3G31XZ-AZ110	VLD	15	64	3G3AX-DL2150	0.44	135		corrosive		
			ND	15	70	303AX-DL2130	0.44	133		gases or dust)		
	15	3G3RX2-A2150	LD	18.5	80					uusi)		
	10	0001012-712100	VLD	18.5	80							
			ND	18.5	84							
	18.5	3G3RX2-A2185	LD	22	94	3G3AX-DL2220	0.30	200				
		000.0.27.2.00	VLD	22	94							
			ND	22	105							
	22	3G3RX2-A2220	LD	30	120							
			VLD	30	120	3G3AX-DL2300	0.23	220				
			ND	30	133							
	30	3G3RX2-A2300	LD	37	150							
			VLD	37	150	3G3AX-DL2370	0.19	275				
			ND	37	160							
	37	37 3G3RX2-A2370 45 3G3RX2-A2450	LD	45	186							
			VLD	45	186	3G3AX-DL2450	0.16	335				
			ND	45	200	†						
	45		LD	55	240				1			
			VLD	55	240	3G3AX-DL2550	0.13	360				
			ND	55	242							
	55	3G3RX2-A2550	LD	75	280							
	00 0	3G3RAZ-AZ330	VLD	75	280							

		Inver	ter				DC reac	tor specificat	ions	
Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model	Inductance [mH]	Heat generation [W]	Operating ambient temperature /humidity	Location
			ND	0.75	2.8	3G3AX-DL4007	27.0	15		
	0.75	3G3RX2-A4007	LD	1.5	4.3					
			VLD	1.5	4.3	3G3AX-DL4015	14.0	25		
			ND	1.5	4.2					
	1.5	3G3RX2-A4015	LD	2.2	5.9					
			VLD	2.2	5.9	3G3AX-DL4022	10.1	35		
			ND	2.2	5.8					
	2.2	3G3RX2-A4022	LD	3.7	8.1					
			VLD	3.7	8.1	3G3AX-DL4037	6.4	45		
			ND	3.7	9.8					
	3.7	3G3RX2-A4037	LD	5.5	13.3					
			VLD	5.5	13.3	3G3AX-DL4055	4.41	55		
			ND	5.5	15					
	5.5	3G3RX2-A4055	LD	7.5	20					
	7.5		VLD	7.5	20	3G3AX-DL4075	3.35	95		
		0000000	ND	7.5	21					
	7.5	3G3RX2-A4075	LD	11	24	000437 51 4440	0.00			At an
			VLD	11	24	3G3AX-DL4110	2.33	80		altitude o
	44	3G3RX2-A4110	ND	11	28					1,000 m max.;
	11		LD	15 15	32	3G3AX-DL4150	4.75	405	-10 to 50°C 20% to 90%	indoors
400-V class			VLD	_	32	3G3AX-DL4150	1.75	135	20% 10 90%	(without
olass .	15	3G3RX2-A4150	ND LD	15 18.5	35 41					corrosive gases or
	15	3G3RAZ-A4150	VLD	18.5	41					dust)
			ND	18.5	41					
	18.5	3G3RX2-A4185	LD	22	47	3G3AX-DL4220	1.20	200		
	10.5	3031012-74103	VLD	22	47					
			ND	22	53					
	22	3G3RX2-A4220	LD	30	63				+	
		0001012711220	VLD	30	63	3G3AX-DL4300	0.92	230		
			ND	30	64	000/0/ 221000	0.02	200		
	30	3G3RX2-A4300	LD	37	77				-	
			VLD	37	77	3G3AX-DL4370	0.74	275		
			ND	37	83					
		3G3RX2-A4370	LD	45	94				1	
			VLD	45	94	3G3AX-DL4450	0.61	340		
			ND	45	100					
		3G3RX2-A4450	LD	55	116				1	
			VLD	55	116	3G3AX-DL4550	0.5	400		
			ND	55	121					
	55	3G3RX2-A4550	LD	75	149					
	55 5		VLD	75	149					

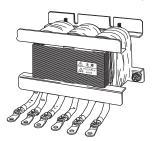
Dimensions (Unit: mm)

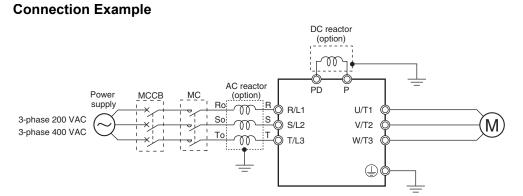
Inverter		Fig.	Applicable				Dime	nsions	[mm]				Weight	Standard
input power supply	Model	No.	motor capacity [kW]	w	D	Н	Α	В	х	Υ	С	K	[kg]	applicable wire
	3G3AX-DL2002		0.2	66	90	98		85	56	72	5.2×8	M4	0.8	1.25 mm ² min.
	3G3AX-DL2004		0.4	66	90	98		95	56	72	5.2×8	M4	1.0	1.25 mm ² min.
	3G3AX-DL2007	F: 4	0.75	66	90	98		105	56	72	5.2×8	M4	1.3	2 mm ² min.
	3G3AX-DL2015	Fig. 1	1.5	66	90	98		115	56	72	5.2×8	M4	1.6	2 mm ² min.
	3G3AX-DL2022		2.2	86	100	116		105	71	80	6×9	M4	2.1	2 mm ² min.
	3G3AX-DL2037		3.7	86	100	118		120	71	80	6×9	M4	2.6	3.5 mm ² min.
	3G3AX-DL2055		5.5	111	100	210		110	95	80	7×11	M5	3.6	8 mm² min.
3/1-phase 200 VAC	3G3AX-DL2075	F: 0	7.5	111	100	212		120	95	80	7×11	M6	3.9	14 mm ² min.
200 1710	3G3AX-DL2110	Fig. 2	11	146	120	252		110	124	96	7×11	M6	6.5	22 mm² min.
	3G3AX-DL2150		15	146	120	256		120	124	96	7×11	M8	7.0	38 mm² min.
	3G3AX-DL2220		18.5, 22	120	175	356	140	145	98	151	7×11	M8	9.0	60 mm ² min.
	3G3AX-DL2300		30	120	175	386	155	150	98	151	7×11	M8	13.0	38 mm² x 2 min.
	3G3AX-DL2370	Fig. 3	37	120	175	390	155	150	98	151	7×11	M10	13.5	38 mm² x 2 min.
	3G3AX-DL2450		45	160	190	420	180	150	120	168	7×11	M10	19.0	60 mm ² x 2 min.
	3G3AX-DL2550		55	160	190	424	180	180	120	168	7×11	M12	24.0	80 mm ² x 2 min.
	3G3AX-DL4007		0.75	66	90	98		95	56	72	5.2×8	M4	1.1	1.25 mm ² min.
	3G3AX-DL4015		1.5	66	90	98		115	56	72	5.2×8	M4	1.6	2 mm² min.
3-phase	3G3AX-DL4022	F: 4	2.2	86	100	116		105	71	80	6×9	M4	2.1	2 mm² min.
400 VAC	3G3AX-DL4037	Fig. 1	3.7	86	100	116		120	71	80	6×9	M4	2.6	2 mm² min.
	3G3AX-DL4055		5.5	111	100	138		110	95	80	7×11	M4	3.6	3.5 mm ² min.
	3G3AX-DL4075		7.5	111	100	138		115	95	80	7×11	M4	3.9	3.5 mm ² min.
	3G3AX-DL4110	F: 0	11	146	120	250		105	124	96	7×11	M5	5.2	5.5 mm ² min.
	3G3AX-DL4150	Fig. 2	15	146	120	252		120	124	96	7×11	M6	7.0	14 mm² min.
	3G3AX-DL4220		18.5, 22	120	175	352	140	145	98	151	7×11	M6	9.5	22 mm² min.
3-phase 400 VAC	3G3AX-DL4300		30	120	175	356	140	145	98	151	7×11	M8	9.5	30 mm² min.
.50 1710	3G3AX-DL4370	Fig. 3	37	120	175	386	155	150	98	151	7×11	M8	13.5	38 mm² min.
	3G3AX-DL4450		45	160	190	416	180	145	120	168	7×11	M8	16.5	60 mm ² min.
	3G3AX-DL4550	1	55	160	190	416	190	170	120	168	7×11	M8	23.0	38 mm² x 2 min.



AC Reactor 3G3AX-AL□□□□

Connect the AC Reactor if the capacity of the power supply is much larger than that of the Inverter or the power factor is required to be improved.





Specifications

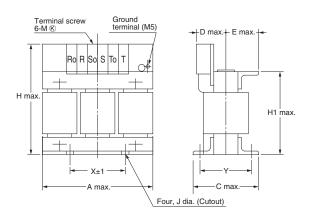
		Inver	ter			AC reactor specifications						
Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model	Inductance [mH]	Heat generation [W]	Operating ambient temperature/ humidity	Location		
			ND	0.4	3.3							
	0.4	3G3RX2-A2004	LD	0.75	3.9							
			VLD	0.75	3.9							
			ND	0.75	5.5	3G3AX-AL2025	2.8	12				
	0.75	3G3RX2-A2007	LD	1.5	7.2							
			VLD	1.5	7.2							
			ND	1.5	8.3							
	1.5	3G3RX2-A2015	LD	2.2	10.8							
			VLD	2.2	10.8							
			ND	2.2	12	3G3AX-AL2055	0.88	25				
	2.2	3G3RX2-A2022	LD	3.7	13.9							
			VLD	3.7	13.9							
			ND	3.7	18							
	3.7	3G3RX2-A2037	LD	5.5	23							
			VLD	5.5	23							
			ND	5.5	26	3G3AX-AL2110	0.35	50				
	5.5	3G3RX2-A2055	LD	7.5	37							
	7.5		VLD	7.5	37							
			ND	7.5	35					At an altitude of		
		3G3RX2-A2075	LD	11	48					1,000 m		
			VLD	11	48				-10 to 50°C	max.;		
00-V		3G3RX2-A2110	ND	11	51	3G3AX-AL2220	0.18	50	20% to 90%	indoors (without		
lass	11		LD	15	64	JG3AA-AL2220				corrosive		
			VLD	15	64					gases or		
			ND	15	70					dust)		
	15	3G3RX2-A2150	LD	18.5	80							
			VLD	18.5	80							
			ND	18.5	84	3G3AX-AL2330	0.09	85				
	18.5	3G3RX2-A2185	LD	22	94							
			VLD	22	94							
			ND	22	105				4			
	22	3G3RX2-A2220	LD	30	120							
			VLD	30	120							
			ND	30	133	3G3AX-AL2500	0.071	95				
	30	3G3RX2-A2300	LD	37	150							
			VLD	37	150							
	0.7	0000000 40070	ND	37	160							
	37	3G3RX2-A2370	LD	45	186							
			VLD	45	186	4						
	4-	000000000000	ND	45	200	3G3AX-AL2750	0.046	100				
	45	3G3RX2-A2450	LD	55	240							
			VLD	55	240	1						
			ND	55	242							
	55	3G3RX2-A2550	LD	75	280							
			VLD	75	280							

		Inver	ter				AC reac	tor specificat	ions		
Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model	Inductance [mH]	Heat generation [W]	Operating ambient temperature/ humidity	Location	
			ND	0.75	2.8						
	0.75	3G3RX2-A4007	LD	1.5	4.3	3G3AX-AL4025	7.7	12			
			VLD	1.5	4.3	3G3AA-AL4023	7.7	12			
			ND	1.5	4.2						
	1.5	3G3RX2-A4015	LD	2.2	5.9						
			VLD	2.2	5.9						
			ND	2.2	5.8	3G3AX-AL4055	3.5	25			
	2.2	3G3RX2-A4022	LD	3.7	8.1	1					
			VLD	3.7	8.1						
			ND	3.7	9.8						
	3.7	3G3RX2-A4037	LD	5.5	13.3	<u> </u>					
			VLD	5.5	13.3	1					
		0000000 44055	ND	5.5	15	3G3AX-AL4110	1.3	50			
	5.5	3G3RX2-A4055	LD	7.5	20	1					
	7.5 3		VLD	7.5	20	1					
		3G3RX2-A4075	ND LD	7.5 11	21 24						
	7.5	3G3RAZ-A4075	VLD	11	24	1				At an	
			ND	11	28	1				altitude of 1,000 m	
	11	3G3RX2-A4110	LD	15	32	3G3AX-AL4220	0.74	60	10 to 50°C	max.;	
400-V			VLD	15	32				-10 to 50°C 20% to 90%	indoors	
class			ND	15	35	1				(without corrosive	
	15	3G3RX2-A4150	LD	18.5	41						gases or
			VLD	18.5	41	†				dust)	
			ND	18.5	42	1					
	18.5	3G3RX2-A4185	LD	22	47	3G3AX-AL4330	0.36	90			
			VLD	22	47	†					
			ND	22	53	1					
	22	3G3RX2-A4220	LD	30	63				1		
			VLD	30	63	1					
			ND	30	64	3G3AX-AL4500	0.29	95			
	30	3G3RX2-A4300	LD	37	77	JGJAA-AL4500	0.29	30			
			VLD	37	77						
			ND	37	83						
	37 3	3G3RX2-A4370	LD	45	94						
			VLD	45	94	1					
			ND	45	100	3G3AX-AL4750	0.19	100			
	45	3G3RX2-A4450	LD	55	116	330,00,712,1700	0.10	100			
			VLD	55	116	1					
			ND	55	121						
	55	3G3RX2-A4550	LD	75	149						
		3G3RA2-A4550	VLD	75	149						

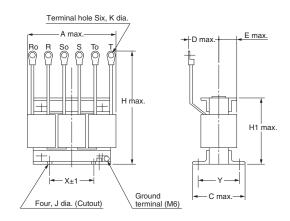
Dimensions (Unit: mm)

Inverter input		Applicable					Dime	ensions	[mm]					Weight
power supply	Model	motor capacity [kW]	Α	С	D	E	н	H1	х	Y	J	K	w	[kg]
	3G3AX-AL2025	0.2 to 1.5	120	82	60	40	150	94	50	67	6	4.0	9.5	2.8
	3G3AX-AL2055	2.2, 3.7	120	98	60	40	150	94	50	75	6	4.0	9.5	4.0
	3G3AX-AL2110	5.5, 7.5	150	103	70	55	170	108	60	80	6	5.3	12.0	5.0
3-phase 200 VAC	3G3AX-AL2220	11, 15	180	113	75	55	190	140	90	90	6	8.4	16.5	10.0
	3G3AX-AL2330	18.5, 22	180	113	85	60	230	140	125	90	6	8.4	22.0	11.0
	3G3AX-AL2500	30, 37	260	113	85	60	290	202	100	90	7	8.4	27.0	19.0
	3G3AX-AL2750	45, 55	260	144	110	80	290	207	125	112	7	8.4	28.5	25.0
	3G3AX-AL4025	0.4 to 1.5	130	82	60	40	150	94	50	67	6	4	9.5	2.7
	3G3AX-AL4055	2.2, 3.7	130	98	60	40	150	94	50	75	6	5	12.5	4.0
	3G3AX-AL4110	5.5, 7.5	150	116	75	55	170	106	60	98	6	5	12.5	6.0
3-phase 400 VAC	3G3AX-AL4220	11, 15	180	103	75	55	190	140	100	80	6	5.3	12.0	10.0
100 1710	3G3AX-AL4330	18.5, 22	180	123	85	60	230	140	100	100	6	6.4	16.5	11.5
	3G3AX-AL4500	30, 37	260	113	85	60	290	202	100	90	7	8.4	22.0	19.0
	3G3AX-AL4750	45, 55	260	146	110	80	290	207	125	112	7	8.4	22.0	25.0

3G3AX-AL2025/3G3AX-AL2055/ 3G3AX-AL4025/3G3AX-AL4055/3G3AX-AL4110



3G3AX-AL2110/3G3AX-AL2220/3G3AX-AL2330 3G3AX-AL2500/3G3AX-AL2750/3G3AX-AL4220 3G3AX-AL4330/3G3AX-AL4500/3G3AX-AL4750



PG Option Unit 3G3AX-RX2-PG01

The PG Option Unit is an optional unit for the 3G3RX2 Series Inverter. With this unit, you can realize highly accurate system operation with minimum speed fluctuation, and position control via pulse train position command input by detecting the rotation speed of the motor with an encoder and using the data for feedback.

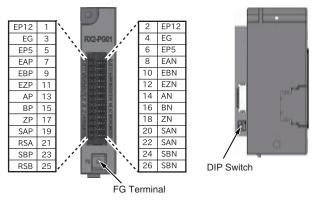


Specifications

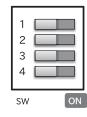
	Item		Specifications				
Model		3G3AX-RX2-P0	G01				
Dimensio (width × h	ns neight × depth)	20.5 × 98.0 × 7	0.0 mm				
Weight		170 g					
	Ambient operating temperature	-10 to 50°C					
Ambient operating humidity		20 to 90% RH	With no icing or condensation				
Environ ment	Storage temperature *	-20 to 65°C					
	Vibration resistance	5.9 m/s ² (0.6G)	, 10 to 55 Hz				
	Protective structure	IP00					
Encoder	feedback	Standard encoder pulse number: 1024 pulse/r Max. input pulse number : 200k pulse/s					
Position	command	Max. input pulse number : 200k pulse/s					
Protectio	n function	Encoder cable disconnection Error PG Option Unit Connection Error					

^{*}The storage temperature is the temperature during transportation.

Terminal Arrangement and DIP Switch Setting



Setting the DIP Switch



Slide to the left to turn the switch OFF, and slide to the right to turn the switch ON.

Switch No.		Settings
-	ON	Encoder phase A / B, disconnection detection enabled
	OFF	Encoder phase A / B, disconnection detection disabled
2	ON	Encoder phase Z, disconnection detection enabled
2	OFF	Encoder phase Z, disconnection detection disabled
	ON	Do not shouse
3	OFF	Do not change
	ON	Do not change
4	OFF	Do not change

Note: All switches are set to OFF as the default setting.

Wire size and recommended rod terminal shape

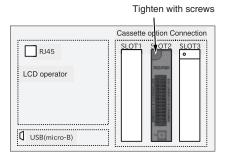
Wire size mm² (AWG)	L1 [mm]	L2 [mm]	d dia. [mm]	D dia. [mm]
0.25 (24)	10.0	14.5	0.8	2.0
0.34 (22)	10.0	14.5	0.8	2.0
0.5 (20)	10.0	16.0	1.1	2.5
0.75 (18)	10.0	16.0	1.3	3.4



Terminal Functions

Terminal name		Terminal	Functions			
		symbol	i diletions	Common terminal	Electric specifications	
Input terminal	Pulse train position command input	SAP SAN SBP SBN RSA RSB	 Pulse train input procedure MD0: 90° phase difference pulse MD1: Forward/Reverse signal, pulse train MD2: Forward pulse/Reverse pulse Mode mode selection (ob-11). RSA: Termination resistor ON/OFF termin RSB: Termination resistor ON/OFF termin Termination resistor: 150 Ω, switch the wiring RSA, RSB terminals released: Built-in ter RSA-SAN short-circuit, RSB-SBN short-cenabled 	5V DC receiver input (RS-422 compliance)		
	Encoder signal input	EAP EAN EBP EBN EZP EZN	A, B, Z: Rotary encoder signal input	Photo coupler input (Corresponds to the 5V DC line driver output type rotary encoder)		
Output terminal	Encoder signal output	AP AN BP BN ZP ZN			5V DC line driver output (RS-422 compliance)	
	Power supply for encoder	EP5	+5V DC power supply		Total supply capacity of EP5 and EP12	
		EP12	+12V DC power supply		(250 mA max.)	
Functional Grounding terminal FG		FG	Connect to the Functional Grounding connection. (Screw size: M3)			

InstallationInstall the unit in SLOT2 and tighten with screws.



Ordering Information

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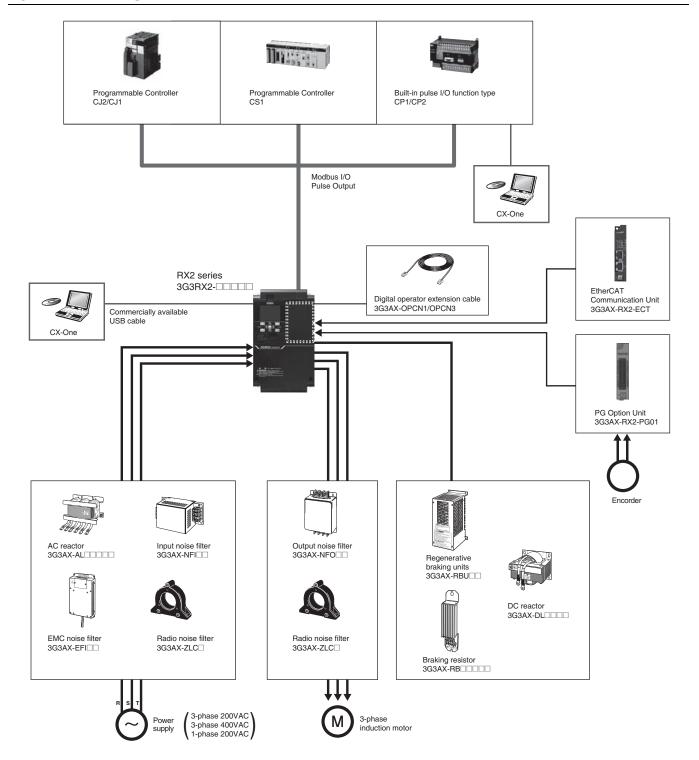
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System Configuration



High-function General-purpose Inverters RX2 Series Interpreting Model Numbers

3G3RX2-A2055

Max. A	applicable Motor Capacity Standard F	Rating (ND)
004	0.4 kW	
007	0.75 kW	
015	1.5 kW	
022	2.2 kW	
037	3.7 kW	
055	5.5 kW	
075	7.5 kW	
110	11 kW	
150	15 kW	
185	18.5 kW	
220	22 kW	
300	30 kW	
370	37 kW	
450	45 kW	
550	55 kW	
750	75 kW	
900	90 kW	
11K	110 kW	
13K	132 kW	
Voltage	e class	
2	3-phase 200 VAC (200-V class)	
4	3-phase 400 VAC (400-V class)	
Enclos	ure rating	
Α	IP20/UL open type	

IP00/UL open type

Ordering Information

RX2 series Inverter Models

		Max. applicabl	e motor capacity		
Rated voltage	Enclosure ratings	Normal Duty (ND)	Low Duty (LD)/ Very Low Duty (VLD)	Model	
		0.4 kW	0.75 kW	3G3RX2-A2004	
		0.75 kW	1.5 kW	3G3RX2-A2007	
		1.5 kW	2.2 kW	3G3RX2-A2015	
		2.2 kW	3.7 kW	3G3RX2-A2022	
		3.7 kW	5.5 kW	3G3RX2-A2037	
		5.5 kW	7.5 kW	3G3RX2-A2055	
		7.5 kW	11 kW	3G3RX2-A2075	
3-phase 200 VAC	IP20	11 kW	15 kW	3G3RX2-A2110	
		15 kW	18.5 kW	3G3RX2-A2150	
		18.5 kW	22 kW	3G3RX2-A2185	
		22 kW	30 kW	3G3RX2-A2220	
		30 kW	37 kW	3G3RX2-A2300	
		37 kW	45 kW	3G3RX2-A2370	
		45 kW	55 kW	3G3RX2-A2450	
		55 kW	75 kW	3G3RX2-A2550	
		0.75 kW	1.5 kW	3G3RX2-A4007	
		1.5 kW	2.2 kW	3G3RX2-A4015	
		2.2 kW	3.7 kW	3G3RX2-A4022	
		3.7 kW	5.5 kW	3G3RX2-A4037	
		5.5 kW	7.5 kW	3G3RX2-A4055	
		7.5 kW	11 kW	3G3RX2-A4075	
	IP20	11 kW	15 kW	3G3RX2-A4110	
	IP20	15 kW	18.5 kW	3G3RX2-A4150	
3-phase 400 VAC		18.5 kW	22 kW	3G3RX2-A4185	
3-phase 400 VAC		22 kW	30 kW	3G3RX2-A4220	
		30 kW	37 kW	3G3RX2-A4300	
		37 kW	45 kW	3G3RX2-A4370	
		45 kW	55 kW	3G3RX2-A4450	
		55 kW	75 kW	3G3RX2-A4550	
		75 kW	90 kW	3G3RX2-B4750	
	IP00	90 kW	110 kW	3G3RX2-B4900	
	IFUU	110 kW	132 kW	3G3RX2-B411K	
		132 kW	160 kW	3G3RX2-B413K	

Communication Unit

Name	Model
EtherCAT Communication Unit	3G3AX-RX2-ECT

Related Options

Name		Specifications	Model
		General purpose with Braking resistor	3G3AX-RBU21
	3-phase 200 VAC	High Regeneration purpose with Braking resistor	3G3AX-RBU22
		General purpose for 30 kW ★	3G3AX-RBU23
Regenerative Braking Units		General purpose for 55 kW ★	3G3AX-RBU24
		General purpose with Braking resistor	3G3AX-RBU41
	3-phase 400 VAC	General purpose for 30 kW ★	3G3AX-RBU42
		General purpose for 55 kW ★	3G3AX-RBU43
		Resistor 120 W, 180 Ω	3G3AX-RBA1201
	Compact type	Resistor 120 W, 100 Ω	3G3AX-RBA1202
		Resistor 120 W, 50 Ω	3G3AX-RBA1203
		Resistor 120 W, 35 Ω	3G3AX-RBA1204
		Resistor 200 W, 180 Ω	3G3AX-RBB2001
Braking Resistor	Ctandard type	Resistor 200 W, 100 Ω	3G3AX-RBB2002
	Standard type	Resistor 300 W, 50 Ω	3G3AX-RBB3001
		Resistor 400 W, 35 Ω	3G3AX-RBB4001
		Resistor 400 W, 50 Ω	3G3AX-RBC4001
	Medium capacity type	Resistor 600 W, 35 Ω	3G3AX-RBC6001
		Resistor 1200 W, 17 Ω	3G3AX-RBC12001

^{*} The braking resistor is optionally required.

Regenerative Braking Unit and Braking Resistor Combination

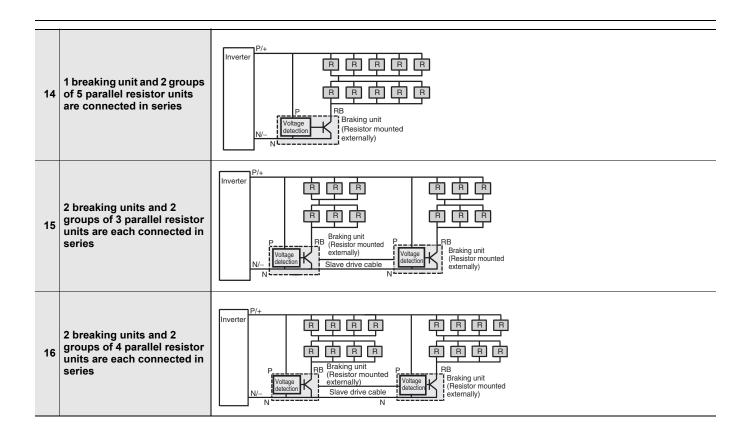
Select the combination of the regenerative braking unit(s) and the braking resistor(s) as follows, according to your inverter. If the usage rate exceeds 10% ED, or if you need a torque larger than the approximate braking torque, you need to follow the instruction provided in Braking Resistor Selection

- Inverter: Select the model of your inverter. The table below assumes that your inverter is used in the heavy load mode and connected to a single
 motor with the same capacity. Make sure that the approximate braking torque in the table shows the assumed value per a motor with
 the same capacity at ND mode. When using this inverter at LD or VLD mode, you need to calculate the torque value by dividing VLD
 by ND.
- Operating conditions: Show the torque during deceleration and the deceleration time (in % ED) calculated as a percentage of the cycle time for 1 cycle of operation including the stop time.
- Braking unit/Breaking resistor: Show the required the model and number of units.
- Connection form: Show the configuration of the regenerative braking unit(s) and braking resistor(s) illustrated in the connection form table below.
- Restrictions: Show the maximum deceleration time allowable for the combination shown here and the minimum resistance that can be connected to the inverter's built-in regenerative braking circuit or external regenerative braking unit(s).

	Inve	rter	Operatir	ng conditions	Braking u	nit	Braking resis	tor		Restrictions	
Voltage class	Max. applicable motor capacity (kW)	Model	Model %ED Approximate braking torque (%)		Model	Number of units	Model	Number of units	Connec- tion form	Allowable continuous braking time(s)	Min. connectable resistance (Ω)
	0.4	3G3RX2-A2004	3.0%	220%	Built-in Inverter		3G3AX-RBA1201	1	1	20	50
	0.4	3G3RAZ-AZ004	10.0%	220%	Built-in inverter		3G3AX-RBB2001	1	1	30	50
	0.75	2C2DV2 A2007	3.0%	120%	Duilt in Inventor		3G3AX-RBA1201	1	1	20	50
	0.75	3G3RX2-A2007	10.0%	120%	Built-in Inverter		3G3AX-RBB2001	1	1	30	50
	1.5	2C2DV2 A2045	2.5%	110%	Duilt in Inventor		3G3AX-RBA1202	1	1	12	35
	1.5	3G3RX2-A2015	10.0%	215%	Built-in Inverter		3G3AX-RBC4001	1	1	10	35
	2.2	3G3RX2-A2022	3.0%	150%	Built-in Inverter		3G3AX-RBB3001	1	1	30	35
	2.2	3G3RAZ-AZUZZ	10.0%	150%	Built-iii iiivertei		3G3AX-RBC4001	1	1	10	35
	3.7	3G3RX2-A2037	3.0%	125%	Built-in Inverter		3G3AX-RBB4001	1	1	20	35
	3.7	10.0% 125%	125%	Built-in inverter		3G3AX-RBC6001	1	1	10	35	
	.		3.0%	120%	Built-in Inverter		3G3AX-RBB3001	2	2	30	16
	5.5	3G3RAZ-AZ055	10.0%	120%	Built-in inverter		3G3AX-RBC4001	2	2	10	16
	7.5	3G3RX2-A2075	3.0%	125%	Built-in Inverter		3G3AX-RBB4001	2	2	20	10
	7.5	3G3RAZ-AZ075	10.0%	125%	Built-in inverter		3G3AX-RBC6001	2	2	10	10
200-V	11	3G3RX2-A2110	3.0%	125%	Built-in Inverter		3G3AX-RBB4001	3	4	20	10
Class	11	SGSRAZ-AZTIU	10.0%	125%	Built-in inverter		3G3AX-RBC6001	3	4	10	10
	15	3G3RX2-A2150	3.0%	130%	Duilt in Investor		3G3AX-RBC12001	2	2	10	7.5
	15	3G3RAZ-AZ130	10.0%	130%	Built-in Inverter		3G3AX-RBC12001	2	2	10	7.5
	18.5	202002 42405	3.0%	105%	Duilt in Inventor		3G3AX-RBC12001	2	2	10	7.5
	16.5	3G3RX2-A2185	10.0%	105%	Built-in Inverter		3G3AX-RBC12001	2	2	10	7.5
	00	202000 40000	3.0%	130%	Duilt in law at a		3G3AX-RBC12001	3	4	10	5
	22	3G3RX2-A2220	10.0%	130%	Built-in Inverter		3G3AX-RBC12001	3	4	10	5
	20	202002 42200	3.0%	160%	3G3AX-RBU24	1	3G3AX-RBC12001	5	11	10	2
	30	3G3RX2-A2300	10.0%	160%	3G3AX-RBU24	1	3G3AX-RBC12001	5	11	10	2
	37 3G3RX2-A2	202002 42270	3.0%	130%	3G3AX-RBU24	1	3G3AX-RBC12001	5	11	10	2
		3G3RAZ-AZ370	10.0%	130%	3G3AX-RBU24	1	3G3AX-RBC12001	5	11	10	2
	45	45 3G3RX2-A2450	3G3AX-RBU24	1	3G3AX-RBC12001	6	12	10	2		
	45		3G3AX-RBU24	1	3G3AX-RBC12001	6	12	10	2		
	55	3G3RX2-A2550	3.0%	120%	3G3AX-RBU24	1	3G3AX-RBC12001	7	13	10	2
	33	3031XX2-A2330	10.0%	120%	3G3AX-RBU24	1	3G3AX-RBC12001	7	13	10	2

	Inve	rter	Operatin	ng conditions	Braking u	nit	Braking resis	stor		Restr	ictions
Voltage class	Max. applicable motor capacity (kW)	Model	%ED (%)	Approximate braking torque (%)	Model	Number of units	Model	Number of units	Connection form	Allowable continuous braking time(s)	Min. connectable resistance (Ω)
	0.75	2C2DV2 A4007	3.0%	220%	Built in Invertor		3G3AX-RBA1201	2	3	20	100
	0.75	3G3RAZ-A4007	10.0%	220%	built-in inverter		3G3AX-RBB2001	2	3	30	100
	1.5	3C3PV2 A4015	Model Model Model Number of units Model 2 33 GSAX-RBB2001 2 33 Model 120% Model	3	20	100					
	1.0	30310(Z-A4013		3	30	100					
	22	3G3BX2-44022	2.5%	150%	Model Built-in Inverter 3G3AX-RBU42 Built-in Inverter 3G3AX-RBU43 3G3AX-RBU43		3G3AX-RBA1202	2	3	12	100
	2.2	3G3I\X2-A4022	10.0%	220%	Built-III IIIVertei		3G3AX-RBC4001	2	3	10	100
	2.7	2C2DV2 A4027	3.0%	175%	Model Built-in Inverter 3G3AX-RBU42 Built-in Inverter 3G3AX-RBU43		3G3AX-RBB3001	2	3	30	70
	3.1	3G3RAZ-A4U37	10.0%	175%	Built-iii iiivertei		3G3AX-RBC4001	2	3	10	70
	### applicable motor capacity (kW) 0.75	2C2DV2 A4055	3.0%	120%	Built in Invertor		3G3AX-RBB3001	2	3	30	70
	5.5	3G3RAZ-A4055	10.0%	120%	built-in inverter		3G3AX-RBC4001	2	3	10	70
	7.5	202002 44075	3.0%	125%	Duilt in Investor		3G3AX-RBB4001	2	3	20	35
	7.5	3G3RAZ-A4075	10.0%	125%	built-in inverter		3G3AX-RBC6001	2	3	10	35
	44	202000 44440	3.0%	120%	Duilt in Inventor		3G3AX-RBB3001	4	5	30	35
	11	3G3RX2-A4110	10.0%	120%	Built-in inverter		3G3AX-RBC4001	4	5	10	35
		0000000 44450	3.0%	125%	B 30 1 1		3G3AX-RBB4001	4	5	20	24
		3G3RX2-A4150	10.0%	125%	Built-in Inverter		3G3AX-RBC6001	4	5	10	24
		3G3RX2-A4185	3.0%	140%	B 311 1 1		3G3AX-RBB3001	8	6	30	24
400-V	18.5		10.0%	140%	Built-in Inverter		3G3AX-RBC4001	8	6	10	24
Class		0000000	3.0%	120%			3G3AX-RBB3001	8	6	30	20
	22	3G3RX2-A4220	10.0%	120%	Built-in Inverter		3G3AX-RBC4001	8	6	10	20
		0000000	10.0%	100%	Built-in Inverter		3G3AX-RBC12001	4	5	10	15
	30	3G3RX2-A4300	10.0%	150%	3G3AX-RBU42	1	3G3AX-RBC12001	6	9	10	10
		0000000 4 4000	3.0%	100%	Built-in Inverter		3G3AX-RBC12001	4	5	10	15
	37	3G3RX2-A4370	10.0%	155%	3G3AX-RBU43	1	3G3AX-RBC12001	6	9	10	6
			3.0%	130%	3G3AX-RBU43	1	3G3AX-RBC12001	6	9	10	6
	45	3G3RX2-A4450	10.0%	130%	3G3AX-RBU43	1	3G3AX-RBC12001	6	9	10	6
			3.0%	140%	3G3AX-RBU43	1	3G3AX-RBC12001	8	10	10	6
	55	3G3RX2-A4550	10.0%	140%	3G3AX-RBU43	1	3G3AX-RBC12001	8	10	10	6
		0000000000000	3.0%	130%	3G3AX-RBU43	1	3G3AX-RBC12001	10	14	10	6
	/5	3G3RX2-B4750	10.0%	130%	3G3AX-RBU43	1	3G3AX-RBC12001	10	14	10	6
		0000000 5 1005	3.0%	105%	3G3AX-RBU43	1	3G3AX-RBC12001	10	14	10	6
	90	3G3RX2-B4900	10.0%	105%	3G3AX-RBU43	1	3G3AX-RBC12001	10	14	10	6
	410	0000000	3.0%	105%	3G3AX-RBU43	2	3G3AX-RBC12001	12	15	10	6
	110	3G3RX2-B411K	10.0%	105%	3G3AX-RBU43	2	3G3AX-RBC12001	12	15	10	6
	100	000000000000000000000000000000000000000	3.0%	115%	3G3AX-RBU43	2	3G3AX-RBC12001	16	16	10	6
	132	3G3RX2-B413K	10.0%	115%	3G3AX-RBU43	2	3G3AX-RBC12001	16	16	10	6

Connection configuration TYPE TYPE Inverter Inverter 1 breaking unit 1 resistor unit R Resisto and 3 resistor units connected (Resistor mounted in parallel 2 resistor units externally) 2 connected in parallel Inverter 1 breaking unit and 2 groups of 2 Inverte 2 resistor units parallel resistor connected in units are series connected in series 3 resistor units connected in parallel Inverter 1 breaking unit and 2 groups of 3 parallel resistor Inverter 2 groups of 2 units are parallel resistor connected in units are series connected in series Inverter Inverte 2 groups of 4 1 breaking unit parallel resistor and 2 groups of 4 units are parallel resistor connected in units connected series are connected in Braking unit series (Resistor mounted externally) 1 breaking unit and 5 11 resistor units connected in Braking unit (Resistor mounted parallel externally) Inverter R R 1 breaking unit and 6 12 resistor units connected in RB Braking unit parallel (Resistor mounted externally) Inverte RRRRR 1 breaking unit and 7 13 resistor unitsconnected in (Resistor mounted externally)



Name	Model
Radio Noise Filter	3G3AX-ZCL2
Radio Noise Filter	3G3AX-ZCL1

				Inverter				
Name	Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model	
				ND	0.4	3.3		
		0.4	3G3RX2-A2004	LD	0.75	3.9		
				VLD	0.75	3.9	3G3AX-NFI21	
				ND	0.75	5.5		
		0.75	3G3RX2-A2007	LD	1.5	7.2		
				VLD	1.5	7.2	3G3AX-NFI22	
				ND	1.5	8.3		
		1.5	3G3RX2-A2015	LD	2.2	10.8		
				VLD	2.2	10.8		
				ND	2.2	12		
		2.2	3G3RX2-A2022	LD	3.7	13.9	3G3AX-NFI23	
				VLD	3.7	13.9	1	
				ND	3.7	18	1	
		3.7	3G3RX2-A2037	LD	5.5	23		
			VLD	5.5	23	3G3AX-NFI24		
			ND	5.5	26	JOSAX-NF124		
		5.5	3G3RX2-A2055	LD	7.5	37	3G3AX-NFI25	
		0.0	0001012712000	VLD	7.5	37		
				ND	7.5	35	-	
		7.5	3G3RX2-A2075	LD	11	48		
		7.0	0001012-712010	VLD	11	48	3G3AX-NFI26	
				ND	11	51		
put Noise	200-V		3G3RX2-A2110	LD	15	64		
lter	class		30310X2-A2110	VLD	15	64	3G3AX-NFI27	
				ND	15	70		
		15	3G3RX2-A2150	LD	18.5	80		
		13		VLD	18.5	80	3G3AX-NFI28	
				ND	18.5	84		
		18.5	3G3RX2-A2185	LD	22	94		
		16.5	3G3RA2-A2163	VLD	22	94	_	
					22		-	
		00	202000 40000	ND		105	3G3AX-NFI29	
		22	3G3RX2-A2220	LD	30	120	-	
				VLD	30	120	-	
		00	202000 4222	ND	30	133		
		30	3G3RX2-A2300	LD	37	150	20247 11515	
				VLD	37	150	3G3AX-NFI2A	
		0.7	202DVC 40270	ND	37	160		
		37	3G3RX2-A2370	LD	45	186	20047	
				VLD	45	186	3G3AX-NFI2B	
			000000	ND	45	200		
		45	3G3RX2-A2450	LD	55	240	1	
				VLD	55	240	3G3AX-NFI2C	
				ND	55	242		
		55	3G3RX2-A2550	LD	75	280		
				VLD	75	280	1	

		Inverter								
Name	Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model			
				ND	0.75	2.8				
		0.75	3G3RX2-A4007	LD	1.5	4.3				
				VLD	1.5	4.3				
				ND	1.5	4.2	3G3AX-NFI41			
		1.5	3G3RX2-A4015	LD	2.2	5.9				
				VLD	2.2	5.9				
				ND	2.2	5.8				
		2.2	3G3RX2-A4022	LD	3.7	8.1				
				VLD	3.7	8.1	3G3AX-NFI42			
				ND	3.7	9.8	-			
			3.7	3G3RX2-A4037	LD	5.5	13.3			
				VLD	5.5	13.3	1			
	5.5		ND	5.5	15					
		3G3RX2-A4055	LD	7.5	20	3G3AX-NFI43				
			VLD	7.5	20					
			ND	7.5	21					
		7.5	3G3RX2-A4075	LD	11	24	3G3AX-NFI44			
				VLD	11	24				
			3G3RX2-A4110	ND	11	28	3G3AX-NFI45 3G3AX-NFI46 3G3AX-NFI47			
		400-V class 15		LD	15	32				
nput Noise	400-V			VLD	15	32				
Filter			3G3RX2-A4150	ND	15	35				
				LD	18.5	41				
				VLD	18.5	41				
				ND	18.5	42				
		18.5	3G3RX2-A4185	LD	22	47				
				VLD	22	47				
				ND	22	53	-			
		22	3G3RX2-A4220	LD	30	63				
				VLD	30	63	3G3AX-NFI48			
				ND	30	64	-			
		30	3G3RX2-A4300	LD	37	77				
				VLD	37	77	3G3AX-NFI49			
				ND	37	83				
		37	3G3RX2-A4370	LD	45	94				
				VLD	45	94				
				ND	45	100				
		45	3G3RX2-A4450	LD	55	116	3G3AX-NFI4A			
				VLD	55	116	+			
				ND	55	121	_			
		55	3G3RX2-A4550	LD	75	149				
		30 3	JG3RAZ-A455U	1		1				

				Inverter				
Name	Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model	
				ND	0.4	3.3		
		0.4	3G3RX2-A2004	LD	0.75	3.9	2024V EE144	
				VLD	0.75	3.9	3G3AX-EFI41	
				ND	0.75	5.5		
		0.75	3G3RX2-A2007	LD	1.5	7.2		
				VLD	1.5	7.2	3G3AX-EFI42	
				ND	1.5	8.3		
		1.5	3G3RX2-A2015	LD	2.2	10.8		
				VLD	2.2	10.8		
				ND	2.2	12	20047 55142	
		2.2	3G3RX2-A2022	LD	3.7	13.9	3G3AX-EFI43	
				VLD	3.7	13.9		
				ND	3.7	18		
		3.7	3G3RX2-A2037	LD	5.5	23	3G3AX-EFI44	
				VLD	5.5	23		
				ND	5.5	26	1	
		5.5	3G3RX2-A2055	LD	7.5	37		
				VLD	7.5	37	3G3AX-EFI45	
				ND	7.5	35		
MC Noise	200-V class	7.5	3G3RX2-A2075	LD	11	48	3G3AX-EFI47	
inter 4	Class			VLD	11	48		
			3G3RX2-A2110	ND	11	51		
		11		LD	15	64		
				VLD	15	64	3G3AX-EFI48	
				ND	15	70		
		15	3G3RX2-A2150	LD	18.5	80		
				VLD	18.5	80	3G3AX-EFI49	
				ND	18.5	84		
		18.5	3G3RX2-A2185	LD	22	94		
				VLD	22	94		
				ND	22	105	-	
		22	3G3RX2-A2220	LD	30	120	3G3AX-EFI4A	
				VLD	30	120	1	
				ND	30	133	1	
		30	3G3RX2-A2300	LD	37	150		
				VLD	37	150	3G3AX-EFI4B	
				ND	37	160	1	
		37	3G3RX2-A2370	LD	45	186		
				VLD	45	186		

^{*} Although an EMC Noise Filter is built into the RX2, it may be necessary to provide another EMC Noise Filter when the cable between the Motor and the Inverter is long.

	Inverter Valtage Max. applicable Rated input Rate										
Name	Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection			Model				
				ND	0.75	2.8					
		0.75	3G3RX2-A4007	LD	1.5	4.3	1				
				VLD	1.5	4.3					
				ND	1.5	4.2	3G3AX-EFI41				
		1.5	3G3RX2-A4015	LD	2.2	5.9					
				VLD	2.2	5.9					
			3G3RX2-A4022	ND	2.2	5.8					
		2.2		LD	3.7	8.1					
				VLD	3.7	8.1	3G3AX-EFI42				
				ND	3.7	9.8					
		3.7	3G3RX2-A4037	LD	5.5	13.3					
				VLD	5.5	13.3					
				ND	5.5	15	3G3AX-EFI43				
		5.5	3G3RX2-A4055	LD	7.5	20	3G3AX-EFI43				
			VLD	7.5	20						
				ND	7.5	21	3G3AX-EFI44				
		7.5	3G3RX2-A4075	LD	11	24					
				VLD	11	24					
			ND	11	28						
		11	3G3RX2-A4110	LD	15	32	3G3AX-EFI45				
				VLD	15	32					
				ND	15	35	-				
		15	3G3RX2-A4150	LD	18.5	41					
IC Noise	400-\/	400-V	3G3RX2-A4185	VLD	18.5	41	3G3AX-EFI46				
ter *	class			ND	18.5	42					
				LD	22	47					
				VLD	22	47	3G3AX-EFI47 3G3AX-EFI48				
			3G3RX2-A4220	ND	22	53					
		22		LD	30	63					
				VLD	30	63					
				ND	30	64					
		30	3G3RX2-A4300	LD	37	77					
				VLD	37	77	3G3AX-EFI49				
				ND	37	83					
		37	3G3RX2-A4370	LD	45	94					
		<i>3.</i>		VLD	45	94	-				
				ND	45	100	-				
		45	3G3RX2-A4450	LD	55	116	3G3AX-EFI4A				
		70	3001012714400	VLD	55	116	-				
				ND	55	121	-				
		55	3G3RX2-A4550	LD	75	149					
		55	3001 (AZ-A4300	VLD	75	149	-				
				ND	75	164	-				
		75	3C3DV2 D4750				3G3AX-EFI4B				
		75	3G3RX2-B4750	LD	90	176	_				
				VLD	90	176					
		00	202BY2 B 1222	ND	90	194					
		90	3G3RX2-B4900	LD	110	199					

^{*} Although an EMC Noise Filter is built into the RX2, it may be necessary to provide another EMC Noise Filter when the cable between the Motor and the Inverter is long.

				Inverter				
Name	Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model	
				ND	0.4	3		
		0.4	3G3RX2-A2004	LD	0.75	3.7	3G3AX-NFO01	
				VLD	0.75	3.7	3G3AX-NFOUT	
				ND	0.75	5	=	
		0.75	3G3RX2-A2007	LD	1.5	6.3		
				VLD	1.5	6.3		
				ND	1.5	7.5	20247 NEO22	
		1.5	3G3RX2-A2015	LD	2.2	9.4	3G3AX-NFO02	
				VLD	2.2	9.4	=	
				ND	2.2	10.5		
		2.2	3G3RX2-A2022	LD	3.7	12		
				VLD	3.7	12	-	
				ND	3.7	16.5		
	3.7	3G3RX2-A2037	LD	5.5	19.6	3G3AX-NFO03		
				VLD	5.5	19.6		
			3G3RX2-A2055	ND	5.5	24		
		5.5		LD	7.5	30		
	200-V class				VLD	7.5	30	-
					ND	7.5	32	-
utput Noise ilter		7.5	3G3RX2-A2075	LD	11	44	3G3AX-NFO04	
iiter	Class			VLD	11	44		
			3G3RX2-A2110	ND	11	46	3G3AX-NFO05	
		11		LD	15	58		
				VLD	15	58		
				ND	15	64		
		15	3G3RX2-A2150	LD	18.5	73		
				VLD	18.5	73	-	
				ND	18.5	76	-	
		18.5	3G3RX2-A2185	LD	22	85	3G3AX-NFO06	
				VLD	22	85	-	
				ND	22	95	-	
		22	3G3RX2-A2220	LD	30	113		
				VLD	30	113	1	
			ND	30	121	-		
		30	3G3RX2-A2300	LD	37	140	3G3AX-NFO07	
				VLD	37	140	+	
				ND	37	145	-	
		37	3G3RX2-A2370	LD	45	169		
		3,	200.012712070	VLD	45	169		

				Inverter											
Name	Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model								
				ND	0.75	2.5									
		0.75	3G3RX2-A4007	LD	1.5	3.1									
				VLD	1.5	3.1									
				ND	1.5	3.8	3G3AX-NFO01								
		1.5	3G3RX2-A4015	LD	2.2	4.8									
				VLD	2.2	4.8									
				ND	2.2	5.3									
		2.2	3G3RX2-A4022	LD	3.7	6.7									
				VLD	3.7	6.7	3G3AX-NFO02								
				ND	3.7	9									
		3.7	3G3RX2-A4037	LD	5.5	11.1									
				VLD	5.5	11.1									
				ND	5.5	14	1								
		5.5	3G3RX2-A4055	LD	7.5	16	1								
				VLD	7.5	16	3G3AX-NFO03								
				ND	7.5	19	1								
	7.5	3G3RX2-A4075	LD	11	22	1									
				VLD	11	22	-								
Output Noise 400-V class				ND	11	25									
	11	3G3RX2-A4110	LD	15	29										
				VLD	15	29	3G3AX-NFO04								
		400-V class 15	3G3RX2-A4150	ND	15	32									
				LD	18.5	37									
riiler	Class			VLD	18.5	37									
				ND	18.5	38									
			18.5 3G3RX2-A4185	LD	22	43									
				VLD	22	43									
				ND	22	48									
		22	22	22	22	22	22	22	22	22	3G3RX2-A4220	LD	30	57	
				VLD	30	57									
				ND	30	58	1								
		30	3G3RX2-A4300	LD	37	70	3G3AX-NFO05								
				VLD	37	70	1								
				ND	37	75	1								
		37	3G3RX2-A4370	LD	45	85									
				VLD	45	85	3G3AX-NFO06								
				ND	45	91	1								
		45	3G3RX2-A4450	LD	55	105									
				VLD	55	105	1								
				ND	55	112	1								
		55	3G3RX2-A4550	LD	75	135	3G3AX-NFO07								
				VLD	75	135	1								
				ND	75	149	1								
		75	3G3RX2-B4750	LD	90	160									
				VLD	90	160									

		Inverter												
Name	Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model							
				ND	0.4	3.3	3G3AX-DL2004							
		0.4	3G3RX2-A2004	LD	0.75	3.9								
				VLD	0.75	3.9	3G3AX-DL2007							
				ND	0.75	5.5								
		0.75	3G3RX2-A2007	LD	1.5	7.2								
				VLD	1.5	7.2	3G3AX-DL2015							
				ND	1.5	8.3								
		1.5	3G3RX2-A2015	LD	2.2	10.8								
				VLD	2.2	10.8	3G3AX-DL202							
				ND	2.2	12								
		2.2	3G3RX2-A2022	LD	3.7	13.9								
				VLD	3.7	13.9	3G3AX-DL2037							
				ND	3.7	18	1							
		3.7	3G3RX2-A2037	LD	5.5	23								
				VLD	5.5	23	3G3AX-DL205							
	5.5		ND	5.5	26									
		5.5	3G3RX2-A2055	LD	7.5	37	3G3AX-DL2075							
				VLD	7.5	37								
			ND	7.5	35	-								
		7.5 200-V class 11	3G3RX2-A2075	LD	11	48								
				VLD	11	48	3G3AX-DL211							
			3G3RX2-A2110	ND	11	51	-							
C Reactor				LD	15	64	3G3AX-DL215							
o mouoto.	class			VLD	15	64								
				ND	15	70								
			15	3G3RX2-A2150	LD	18.5	80							
		15	10		VLD	18.5	80							
					ND	18.5	84							
		19.5	3C3DV2 A2185			94	3G3AX-DL222							
		VLD 22	18.5	18.5 	18.5	18.5	18.5	18.5	18.5	3G31\X2-A2163			94	_
					-									
		00	2C2DV2 40000	ND	22	105								
		22	3G3RX2-A2220	LD	30	120								
			1	VLD	30	120	3G3AX-DL230							
		20	202000 40000	ND	30	133								
		30	3G3RX2-A2300	LD	37	150	20047 5: 55							
				VLD	37	150	3G3AX-DL237							
				ND	37	160								
		37	3G3RX2-A2370	LD	45	186	_							
			1	VLD	45	186	3G3AX-DL245							
				ND	45	200								
		45	3G3RX2-A2450	LD	55	240	1							
				VLD	55	240	3G3AX-DL255							
				ND	55	242								
		55	3G3RX2-A2550	LD	75	280								
				VLD	75	280								

				Inverter			
Name	Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model
				ND	0.75	2.8	3G3AX-DL400
		0.75	3G3RX2-A4007	LD	1.5	4.3	
				VLD	1.5	4.3	3G3AX-DL401
				ND	1.5	4.2	
		1.5	3G3RX2-A4015	LD	2.2	5.9	
				VLD	2.2	5.9	3G3AX-DL402
			ND	2.2	5.8		
		2.2	3G3RX2-A4022	LD	3.7	8.1	
				VLD	3.7	8.1	3G3AX-DL403
				ND	3.7	9.8	1
		3.7	3G3RX2-A4037	LD	5.5	13.3	
				VLD	5.5	13.3	3G3AX-DL405
				ND	5.5	15	-
			3G3RX2-A4055	LD	7.5	20	3G3AX-DL4075
				VLD	7.5	20	
			3G3RX2-A4075	ND	7.5	21	3G3AX-DL4110
				LD	11	24	
				VLD	11	24	
		11	3G3RX2-A4110	ND	11	28	
				LD	15	32	
400-V			VLD	15	32	3G3AX-DL415	
C Reactor	class		15 3G3RX2-A4150	ND	15	35	-
				LD	18.5	41	3G3AX-DL4220
				VLD	18.5	41	
			3G3RX2-A4185	ND	18.5	42	
		18.5		LD	22	47	
				VLD	22	47	
				ND	22	53	
		22	3G3RX2-A4220	LD	30	63	
				VLD	30	63	
				ND	30	64	
		30	3G3RX2-A4300	LD	37	77	+
				VLD	37	77	3G3AX-DL437
				ND	37	83	
		37	3G3RX2-A4370	LD	45	94	
				VLD	45	94	3G3AX-DL4450
				ND	45	100	1
		45	3G3RX2-A4450	LD	55	116	
				VLD	55	116	3G3AX-DL455
				ND	55	121	1
		55 000573 14					
		55	3G3RX2-A4550	LD	75	149	

				Inverter			
Name	Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model
				ND	0.4	3.3	
		0.4	3G3RX2-A2004	LD	0.75	3.9	
				VLD	0.75	3.9	
				ND	0.75	5.5	3G3AX-AL2025
		0.75	3G3RX2-A2007	LD	1.5	7.2	
				VLD	1.5	7.2	
				ND	1.5	8.3	
		1.5	3G3RX2-A2015	LD	2.2	10.8	
				VLD	2.2	10.8	
		2.2 3G3RX		ND	2.2	12	20247 41 2255
			3G3RX2-A2022	LD	3.7	13.9	3G3AX-AL2055
				VLD	3.7	13.9	
				ND	3.7	18	
		3.7	3G3RX2-A2037	LD	5.5	23	
				VLD	5.5	23	
		5.5		ND	5.5	26	3G3AX-AL2110
			3G3RX2-A2055	LD	7.5	37	
				VLD	7.5	37	
		7.5	3G3RX2-A2075	ND	7.5	35	
				LD	11	48	
				VLD	11	48	
		11	3G3RX2-A2110	ND	11	51	3G3AX-AL2220
AC Reactor	200-V			LD	15	64	
	class			VLD	15	64	
		15 3G3RX2-A2150	3G3RX2-A2150	ND	15	70	
				LD	18.5	80	
			VLD	18.5	80	-	
				ND	18.5	84	-
		18.5	18.5 3G3RX2-A2185	LD	22	94	3G3AX-AL2330
		.0.0	0001012712100	VLD	22	94	_
				ND	22	105	-
		22	3G3RX2-A2220	LD	30	120	_
		22	0001012712220	VLD	30	120	
				ND	30	133	
		30	3G3RX2-A2300	LD	37	150	3G3AX-AL2500
		00	0001012712000	VLD	37	150	_
				ND	37	160	-
		37	3G3RX2-A2370	LD	45	186	
		31	3001 (AZ-AZ310	VLD	45	186	+
				ND	45	200	+
		45	3G3RX2-A2450	LD	55	240	3G3AX-AL2750
		40	3G31\AZ-AZ43U				4
				VLD	55	240 242	_
		FF	2C2DV2 A2550	ND	55		
		55	3G3RX2-A2550	LD	75	280	
				VLD	75	280	

				Inverter			
Name	Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model
				ND	0.75	2.8	
		0.75	3G3RX2-A4007	LD	1.5	4.3	
				VLD	1.5	4.3	3G3AX-AL402
				ND	1.5	4.2	
		1.5	3G3RX2-A4015	LD	2.2	5.9	
				VLD	2.2	5.9	
				ND	2.2	5.8	1
		2.2	3G3RX2-A4022	LD	3.7	8.1	3G3AX-AL405
				VLD	3.7	8.1	
				ND	3.7	9.8	
		3.7	3G3RX2-A4037	LD	5.5	13.3	
				VLD	5.5	13.3	1
				ND	5.5	15	1
			3G3RX2-A4055 3G3RX2-A4075	LD	7.5	20	3G3AX-AL4110
				VLD	7.5	20	
				ND	7.5	21	
				LD	11	24	
				VLD	11	24	
400-V		11	3G3RX2-A4110	ND	11	28	
				LD	15	32	
			VLD	15	32	1	
AC Reactor	class		3G3RX2-A4150	ND	15	35	1
				LD	18.5	41	3G3AX-AL4330
				VLD	18.5	41	
		18.5	3G3RX2-A4185	ND	18.5	42	
				LD	22	47	
				VLD	22	47	
		22		ND	22	53	
			3G3RX2-A4220	LD	30	63	
				VLD	30	63	
				ND	30	64	-
		30	3G3RX2-A4300	LD	37	77	3G3AX-AL4500
				VLD	37	77	
			ND	37	83	1	
		37	3G3RX2-A4370	LD	45	94	
				VLD	45	94	-
				ND	45	100	1
		45	3G3RX2-A4450	LD	55	116	3G3AX-AL4750
				VLD	55	116	1
				ND	55	121	1
		55	3G3RX2-A4550	LD	75	149	
	55 3G3RX2- <i>i</i>		1		1		

,		
Name	Specifications	Model
PG Option Unit	For Position or Frequency Control	3G3AX-RX2-PG01
2 igital operator comiconing	RJ45 connector, EIA568-compliant cable (UTP category 5), Cable Length 1 m	3G3AX-OPCN1
	RJ45 connector, EIA568-compliant cable (UTP category 5), Cable Length 3 m	3G3AX-OPCN3

Recommended EtherCAT Communications Cables

Use a straight STP (shielded twisted-pair) cable of category 5 or higher with double shielding (aluminum tape and braiding) for EtherCAT.

Cable with Connectors

	Item	Recommended manufacturer	Cable length (m)	Model
	Cable with Connectors on Both Ends (B M5/B M5)		0.3	XS6W-6PUR8SS30CM-YF
	Cable with Connectors on Both Ends (RJ45/RJ45) Standard RJ45 plugs *1		0.5	XS6W-6PUR8SS50CM-YF
Wire gauge and number of pairs: AWG26, 4-pair cable	Cable color: Yellow *2	OMRON	1	XS6W-6PUR8SS100CM-YF
Cable sheath material: PUR		OWKON	2	XS6W-6PUR8SS200CM-YF
	* 4		3	XS6W-6PUR8SS300CM-YF
	4.		5	XS6W-6PUR8SS500CM-YF
	Cable with Connectors on Both Ends (D 145/D 145)	OMRON	0.3	XS5W-T421-AMD-K
	Cable with Connectors on Both Ends (RJ45/RJ45) Rugged RJ45 plugs *2 Cable color: Light blue		0.5	XS5W-T421-BMD-K
			1	XS5W-T421-CMD-K
			2	XS5W-T421-DMD-K
			5	XS5W-T421-GMD-K
Wire gauge and number of pairs:			10	XS5W-T421-JMD-K
AWG22, 2-pair cable	Cable with Connectors on Both Ends		0.5	XS5W-T421-BMC-SS
	(M12 Straight/RJ45) Shield strengthening connector cable *3		1	XS5W-T421-CMC-SS
	M12/Smartclick connector and rugged RJ45 plug	OMBON	2	XS5W-T421-DMC-SS
	Cable color: Black	OMRON	3	XS5W-T421-EMC-SS
			5	XS5W-T421-GMC-SS
			10	XS5W-T421-JMC-SS

^{*1.} Cables with standard RJ45 plugs are available in the following lengths: 0.2 m, 0.3 m, 0.5 m, 1 m, 1.5 m, 2 m, 3 m, 5 m, 7.5 m, 10 m, 15 m, 20 m. Cables with rugged RJ45 plugs are available in the following lengths: 0.3 m, 0.5 m, 1 m, 2 m, 3 m, 5 m, 10 m, 15 m. For details, refer to the *Industrial Ethernet Connectors Catalog* (Cat. No. G019).

Cables/Connectors

It	em	Recommended manufacturer	Model
Wire gauge and number of pairs:	Cable	Kuramo Electric Co.	KETH-SB *1
AWG24, 4-pair cable	RJ45 Connector	Panduit Corporation	MPS588-C * 1
Wire gauge and number of pairs: AWG22, 2-pair cable	Cable	Kuramo Electric Co.	KETH-PSB-OMR *2
	Cable	JMACS Japan Co., Ltd.	PNET/B *2
	RJ45 Assembly Connector	OMRON	XS6G-T421-1 *2

^{*1.} We recommend you to use the above Cable and RJ45 Connector together.

^{*2.} Cable colors are available in yellow, green, and blue.

^{*3.} For details, contact your OMRON representative.

^{*2.} We recommend you to use the above Cable and RJ45 Assembly Connector together.

Software

How to Select Required Support Software for Your Controller

The required Support Software depends on the Controller to connect. Please check the following table when purchasing the Support Software.

Item	Omron PLC System	Omron Machine Automation Controller System
Controller	CS, CJ, CP, and other series	NJ series
Inverter	Inverter RX2-series	Inverter RX2-series with EtherCAT Communication Unit 3G3AX-RX2-ECT
Software	FA Integrated Tool Package CX-One (CX-Drive: Version 3.00 or higher)	Automation Software Sysmac Studio (Version 1.47 or higher)

FA Integrated Tool Package CX-One

	Specifications			
Product name		Number of licenses	Media	Model
FA Integrated Tool Package CX-One Ver.4.□	The CX-One is a comprehensive software package that integrates Support Software for OMRON PLCs and components. CX-One Version 4.□ includes CX-Drive Ver.3.□.	1 license * 1	DVD	CXONE-AL01D-V4

^{*1.} Multi licenses are available for the CX-One (3, 10, 30, or 50 licenses).

Note: 1. For details, refer to the CX-One Catalog (Cat. No. R134), visit your local OMRON website.

2. The RX2-series is supported by CX-Drive version 3.00 or higher.

Automation Software Sysmac Studio

The Sysmac Studio is the software that provides an integrated environment for setting, programming, debugging and maintenance of machine automation controllers including the NJ/NX-series CPU Units, NY-series Industrial PC, EtherCAT Slave, and the HMI.

For details, refer to your local OMRON website and Sysmac Studio Catalog (Cat. No. P138).

Note: The RX-series with EtherCAT Communication Unit 3G3AX-RX2-ECT version 1.0 or later is supported by Sysmac Studio version 1.47 or higher.

Overview of Inverter Selection

For detail of Inverter selection, refer to the RX2 series User's Manual. (Man.No.I620).

Motor Capacity Selection

Before selecting an invertor, first the motor should be chosen.In selecting the motor, first calculate the load inertia for the applications, and then calculate the required capacity and torque.

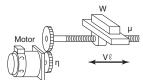
Make a simple selection (use Formulas for the required output power)

This method of calculation helps select a motor by calculating the output (W) required by the motor to maintain its regular rotations. It does not include calculation of the effect of acceleration/deceleration. Therefore, make allowance for the calculated value to select a motor. This calculation method can be applied to applications that operate constantly such as fans, conveyers, agitators etc.

This calculation method must not be applied to the following applications:

- Those requiring instant start-up.
- · Those that frequently repeat operation and stop.
- Those that have a large inertia at the power transfer part.
- · Those that have an inefficient power transfer part.

For Straight-Line Operation: Normal Power PO (kW)



$$P_o = \frac{\mu \cdot W \cdot V\ell}{6120 \cdot n}$$

μ: Friction Coefficient

µ: Friction Coefficient
W: Mass of Straight-Line travelling part (kg)

√ε: Speed of Straight-Line Travelling part (m/min)
η: Decelerator (Transfer part) Efficiency

For Rotating Operation: Normal Power PO (kW)



$$P_{o} (kW) = \frac{2\pi \cdot T\ell \cdot N\ell}{60 \cdot \eta} \times 10^{-3}$$

Tℓ: Load Torque (Load Shaft) (N·m)
Nℓ: Load Shaft Rotation Speed (r/min)
n: Transfer part (n≤1)

Detailed Selection Method (R.M.S Algorithm)

This method helps to select a motor by calculating the effective torque and maximum torque required to achieve a certain pattern of operation for the application. It selects a motor that is optimal for a particular operation pattern.

Calculate the inertia with a Motor Shaft Conversion Value

Calculate inertias of all the components with the formula for inertia calculation shown below to convert them to a motor conversion value.



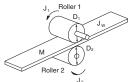
$$J_W = J_1 + J_2 = \left(\frac{M_1 \cdot D^2}{8} + \frac{M_2 \cdot D^2}{4}\right) \times 10^{-6} (kg \cdot m^2)$$

- J_w: Inertia (kg·m²)
- J, : Cylinder Inertia (kg·m²)
- J_a: Inertia from Object (kg·m²)
- D : Diameter (mm)
- M ,: Mass of Cylinder (kg)
- M2: Mass of Object (kg)

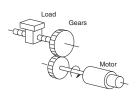
$$J_{w} = J_{1} + J_{2} + J_{3} + J_{4} = \left(\frac{M_{1} \cdot D_{1}^{2}}{8} + \frac{M_{2} \cdot D_{2}^{2}}{8} \cdot \frac{D_{1}^{2}}{D_{2}^{2}} + \frac{M_{3} \cdot D_{1}^{2}}{4} + \frac{M_{4} \cdot D_{1}^{2}}{4}\right) \times 10^{-6} (kg \cdot m^{2})$$



- J_w: Inertia (kg⋅m²)
- $J_1: Cylinder \ 1 \ Inertia \ (kg \cdot m^2)$
- J₂: Inertia from Cylinder 2 (kg·m²)
- J₃: Inertia from Object (kg·m²)
 J₄: Inertia from Belt (kg·m²)
- 2 (kg·m²) M_,: Mass of Cylin
- D₁: Cylinder 1 Diameter (mm)
 D₂: Cylinder 2 Diameter (mm)
 M,: Mass of Cylinder 1 (kg)
 - M₂: Mass of Cylinder 2 (kg)
 - M₃: Mass of Object (kg)
 - M₄: Mass of Belt (kg)



- $_{W} = J_{1} + \left(\frac{D_{1}}{D_{2}}\right)^{2} J_{2} + \frac{M \cdot D_{1}^{2}}{4} \times 10^{-6} (\text{kg} \cdot \text{m}^{2})$
- Jw: System Inertia (kg·m²)
- J₁: Roller 1 Inertia (kg·m²)
 J₂: Roller 2 Inertia (kg·m²)
- J₂: Roller 2 Inertia (kg·m
- D₁: Roller 1 Diameter (mm)
- D₂: Roller 2 Diameter (mm)
- M : Work Equivalent Mass (kg)



$$J_1 = J_1 + G^2(J_2 + J_w) (kg \cdot m^2)$$

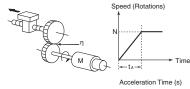
- J L: Load Inertia of Motor Shaft Conversion (kg·m²)
- J_w: Load Inertia (kg·m²)
- $\boldsymbol{J}_{_1}$: Gear Inertia on Motor Side (kg·m²)
- J₂: Gear Inertia on Load Side (kg·m²)
- Z₁: Number of Gear Teeth on Motor Side
- Z₂: Number of Gear Teeth on Load Side

Gear Ratio G = Z₁/Z₂

Calculate Motor Shaft Conversion Torque and Effective Torque

Calculate the acceleration torque from the load torque calculated from both the motor shaft conversion value and the motor rotor inertia. Then Combine this acceleration torque and the Load torque calculated from the friction force and the external force that are applied to the load. Now you get the required torque to operate a motor.

Acceleration Torque



Acceleration Torque (T_A)

$$T_A = \frac{2\pi N}{60t_A} \left(J_M + \frac{J_L}{\eta} \right) (N \cdot m)$$

T_A: Acceleration/Deceleration Torque (N·m)

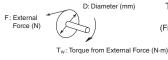
Time J_L: Motor Shaft Conversion Load Inertia (kg⋅m²)
J_M: Inertial of Motor Itself (kg⋅m²)

n : Gear Transmission Efficiency

N : Motor Rotation Speed (r/min)

N : Motor Rotation Speed (r/min)

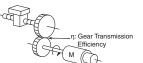
Motor Shaft Conversion Load Torque (External Force/ Friction)



$$T_W = F \cdot \frac{D}{2} \times 10^{-3} (N \cdot m)$$

(Friction is generally,

F = μW μ: Friction Coefficient W: Mass of Moving Part



$$T_{\scriptscriptstyle L} = \, T_{\scriptscriptstyle W} {\cdot} \frac{G}{\eta} \, \, (N {\cdot} m)$$

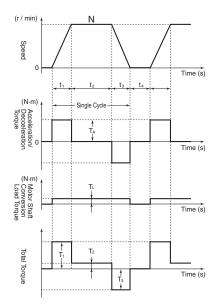
- T₁: Motor Shaft Conversion Load Torque (N·m)
- T_w: Load Torque (N·m)
- Z.: Number of Gear Teeth on Motor Side
- Z_2 : Number of Gear Teeth on Load Side
- Gear (Deceleration) Ratio G = Z₁/Z₂

Calculation of Total Torque and Effective Torque

Effective Torque: TRMS (N·m)

$$= \ \sqrt{ \frac{ \ \Sigma \left(T_{i} \right)^{2} \cdot t_{\ i} }{ \ \Sigma t_{\ i} } } = \ \sqrt{ \frac{ T_{1}^{2} \cdot t_{\ 1} + T_{2}^{2} \cdot t_{\ 2} + T_{3}^{2} \cdot t_{\ 3} + T_{4}^{2} \cdot t_{\ 4} }{ t_{\ 1} + t_{\ 2} + t_{\ 3} + t_{\ 4} }$$

Maximum Torque: $T_{MAX} = T_1 = T_A + T_L$



Note: Please make use of the Servo Motor selection software, which can calculate the motor shaft conversion inertia and effective/maximum torque, as above.

Motor Selection

Use the formula below to calculate the motor capacity from the effective torque and the maximum torque that were obtained above. Select the larger of the two generated values as the motor capacity. Select a motor the capacity of which is larger than the calculated value and makes allowance for an error.

Motor Capacity corresponding to Effective Torque

Motor Capacity (kW) = 1.048⋅N⋅T_{RMS}⋅10⁻⁴

N: Maximum Rotations (r/min)

Motor Capacity capable of Providing Maximum Torque

Motor Capacity (kW) = $1.048 \cdot N \cdot T_{MAX} \cdot 10^{-4} / 1.5$

N: Maximum Rotations (r/min)

Inverter Capacity Selection

Select an inverter that can be used for the selected motor in the process of "Motor Selection".

Generally, select an inverter which fits the maximum applicable motor capacity of the selected motor.

After selecting an inverter, check if it meets with all of the following conditions. If it does not, select an inverter that has a one class larger capacity and check the feasibility again.

Motor Rated Current \leq Inverter Rated Output Current Maximum Time of Continuous Torque Output Time in an Application \leq 1 minute

Note: 1. Where the inverter overload capacity is "120% of Rated Output Current for 1 minute", check it for 0.8 minute.

2. Where a 0 Hz sensor-less vector control is being used, or where torque must be maintained for 0 (r/min) rotation speed and where 150% of the rated torque is frequently required, use an invertor which is one rank larger than the one selected by the above method.

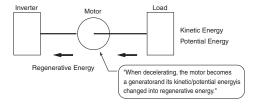
Outline of Braking Resistor Selection Importance of Braking Resistor

If the regenerative energy generated in deceleration or descent in an application is too great, the main circuit of an inverter may have an increased voltage and it may be damaged.

Because the inverter usually contains the overvoltage LAD stop function, it is not actually damaged. However, the motor stops detecting an error, making a stable and continuous operation disabled. Therefore, you must discharge the regenerative energy outside of the inverter.

What is Regenerative Energy?

A load connected to a motor has kinetic energy when rotating, and potential energy when it is located in a high position. When the motor decelerates, or when the load descends, the energy is returned to an inverter. It is known as regeneration, and the energy generated by the phenomenon is known as regenerative energy.



Preventing Breaking Resistence

The following are methods to prevent the connection of braking resistance.

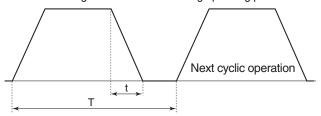
These methods will make the deceleration time increase, so check if it will not cause problems.

- Enable the deceleration stall prevention (enabled in factory settings) (It will automatically increase deceleration time not to cause an overvoltage to stop the motor).
- Set a longer deceleration time. (Cause the regenerative energy to decrease per unit of time.)
- Disable Free-Run. (Prevent the regenerative energy from returning to an inverter.)

Make a Simple Selection for Braking Resistors

It can be a simple selecting method by using the ratio of time in which regenerative energy is produced in a normal operating pattern.

Calculate the usage ratio from the following operating pattern.



Usage Rate = $t/T \times 100$ (% ED)

- t : Deceleration Time (Regenerative Time)
- T : Single Cycle Operation Time

%ED is the unit used for a usage rate.

The usage rate is used as the ratio of deceleration time (regenerative operation time) to simplify the selection of the braking options.

For Models with a Built-in Braking Circuit (3G3RX2 200 V with a capacity of 22 kW or lower, 3G3RX2 400 V with a capacity of 37 kW or lower)

Select the braking resistor based on the usage rate calculated from the operation patterns.

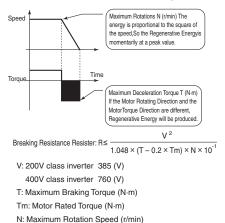
Refer to the braking resistor list described in the User's manual and catalog, and connect it according to your Inverter.

For Models without a Built-in Braking Circuit (3G3RX2 200 V with a capacity of 30 kW or higher, 3G3RX2 400 V with a capacity of 45 kW or higher)

Select the regenerative braking unit and the braking resistor. Refer to the regenerative braking unit and braking resistor lists described in the User's manual and catalog, and connect them according to your Inverter.

When the usage ratio for the braking resistor selected on the previous page exceeds 10% ED, or when an extremely large braking torque is required, use the method below to calculate a regenerative energy and make your selection.

Calculation of Required Braking Resistor

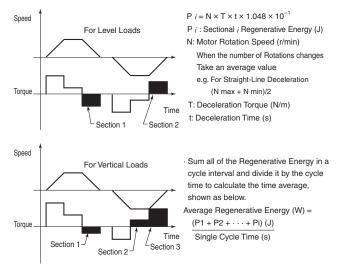


Note: Calculate a braking torque using the above "Motor Capacity Selection".

Calculation of Average Regenerative Energy

Regenerative Energy is produced when the motor rotation direction and the torque direction are opposite.

Use the following formula to calculate a regenerative energy per cycle interval.



Note: 1. Forward rotation direction is forward for the speed, and the torque in the forward rotation direction is forward for the torque.

Calculate a braking torque using the above "Motor Capacity Selection".

Braking Resistor Selection

Select a Braking Resistor from the required braking resistance and average regenerative energy on the left.

- Required Braking Resistence ≥ Resistence of Braking Resistor ≥ Minimum Connection Resistence of Invertor or Regenerative Braking Unit
- Average Regenerative Energy ≤ Permissible Power for Braking Resister

Note: 1. If a resistance that has a less then the minimum connectable value is connected on an inverter or regenerative braking resistor unit, the internal breaking transistor can be damaged. When the required braking resistance is less than the minimum connectable resistance, change the inverter or regenerative energy braking to the one having a larger capacity and a minimum connection resistance less than the required braking resistance.

- 2. Two or more regenerative braking units can be operated in parallel. Refer to the following formula to know the braking resistance value in such a case.
 Braking Resistence (Ω) = (Required Braking Resistance as calculated above) × (No. of Units in use)
- 3. Do not use the above formula to select a generative braking resistance value. 150 W does not reflect a permissible power capacity, but the maximum rated power per unit of resistance. The actual permissible power varies according to a resistance.

High-function General-purpose Inverters RX2 Series Related Manuals

Man. No.	Model	Manual
1620	3G3RX2-□□□□	3G3RX2 Series High-function General-purpose Inverter User's Manual
1663	3G3AX-RX2-ECT	3G3RX2 Series EtherCAT® Communication Unit User's Manual
1622	3G3RX2-□□□□□ CXONE-AL□□D-V□	Inverter RX2 Series DriveProgramming User's Manual
W463	CXONE-AL□□D-V□	CX-One FA Integrated Tool Package SETUP MANUAL
W453	CXONE-AL□□D-V□ WS02-DRVC01	CX-Drive OPERATION MANUAL

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Note: Do not use this document to operate the Unit.

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