Industrial PC Platform NY-series IPC Machine Controller

NY5□ □-1

CSM NY5 -1 DS F 5 5

The future will be IT driven, we make you part of it

Our IPC Machine Controller combines proven machine automation with the freedom to use PC technology: working together but independently. So you can leverage Big Data, NUI and IoT to explore manufacturing innovation with no compromise on traditional PLC reliability and robustness. It makes engineers unstoppable and machines innovative yet reliable.



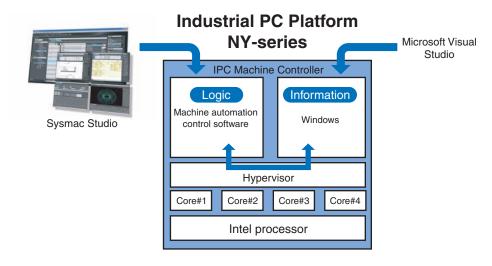


NY512

NY532

Features

- OS independency allows controller to continue to control if a Windows OS crashes
- Primary task period 500 μs/24 axes
- Retain/non-retain variables 4 MB/64 MB
- 16 to 64 axes
- 192 EtherCAT slaves
- · Secure boot and recovery methods
- Powerful 7th-generation CPU technology for optimum performance
- No internal cables in the PC part eliminates faults, maximizes uptime
- · Unique simplified thermal design to cut downtime
- Two Gbps Ethernet, one EtherCAT, one DVI, one UPS I/O connector
- Two USB2.0 and two USB3.0 for fast data-transmission

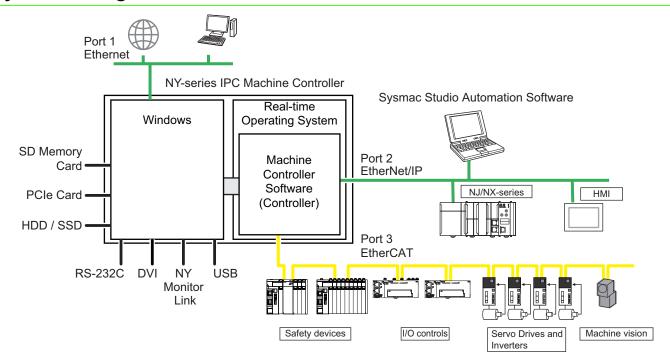


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System Configuration



Model Number Structure

The purpose of this model number structure is to provide understanding of the meaning of specifications from the model number. Models are not available for all combinations of code numbers.

NY	5			-		0	0 -									
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17

Item		Description	Option	Standard model	
1	Series name	NY	NY-series Industrial PC Platform	Yes	
2	Controller specifications	5	Large scale, high speed and high precision control application for up to 64 axes.	Yes	
3	Madeltine	1	Industrial Box PC	Yes	
3	Model type	3	Industrial Panel PC	Yes	
4	Sequential number	2 or more		Yes	
5	Function module	1	Standard	Yes	
		3	16 axes	Yes	
6	Number of axes for motion control	4	32 axes	Yes	
	motion control	5	64 axes	Yes	
7	Additional function software module	0		Yes	
8	Reserved	0		Yes	
0	Evnanciar state	0	No PCIe slot	Yes	
9	Expansion slots	1	1 PCle slots	Yes	
		1	Aluminum frame, black, and projected capacitive touch type	Yes	
10	Frame type	2	Aluminum frame, Nickel plating, and projected capacitive touch type	Yes	
		Х	No display (Industrial Box PC)	Yes	
		1	12.1 inch model	Yes	
44	Display size	2	15.4 inch model	Yes	
11		3	18.5 inch model	Yes	
		Х	No display (Industrial Box PC)	Yes	
10	2		Windows Embedded Standard 7 - 64 bit	No *2	
12	OS	4	Windows 10 IoT Enterprise 2019 LTSC - 64 bit	Yes	
40	D	1	Intel® Core™ i7-4700EQ 4th generation CPU with Fan Unit for active cooling	No *2	
13	Processor	4	Intel® Core™ i5-7440EQ 7th generation CPU with Fan Unit for active cooling	Yes	
4.4	M-i	3	8 GB, non-ECC	Yes	
14	Main memory	5	32 GB, non-ECC	Yes	
		6	128 GB, CFast MLC	Yes	
		7	256 GB, CFast MLC	Yes	
		8	32 GB, SSD SLC	No *2	
15	Storage	9	64 GB, SSD SLC	Yes	
		С	320 GB, HDD	No *2	
		К	128 GB, SSD MLC	Yes	
		Р	1 TB, SSD 3DTLC	Yes	
		0	No optional interface	Yes	
16	Ontional interface	1	RS-232C	Yes	
16	Optional interface	2	DVI-D	Yes	
		6	NY Monitor Link	Yes	
		0	OMRON	Yes	
17	Logo	2	Customized logo *1	Yes	
		Х	No display (Industrial Box PC)	Yes	

^{*1.} Customization only available in Europe.
*2. End of Life products: only available for service purpose

Ordering Information

Recommended models

The industrial PC Platform has extended configuration possibilities to meet your requirements, below an overview of the most used and recommended models. Selecting one of the models below will bring the benefit of faster delivery times.

In case your preferred model is not listed below, please contact your Omron representative to discuss the possibilities.

NY-series IPC Machine Controller

Product								
name	Operating system	CPU type	Number of motion axes	RAM memory (non-ECC type)	Storage size	Interface option	Model	
			64	32 GB	128 GB SSD MLC	RS-232C	NY512-1500-1XX445K1X	
		Intel® Core™ i5-7440EQ	04	8 GB	256 GB CFast MLC	No	NY512-1500-0XX44370X	
Industrial	Windows 10 IoT Enterprise 2019 LTSC		32	32 GB	128 GB SSD MLC	RS-232C	NY512-1400-1XX445K1X	
Box PC	64bit		32	8 GB	256 GB CFast MLC	No	NY512-1400-0XX44370X	
			16	32 GB	128 GB SSD MLC	RS-232C	NY512-1300-1XX445K1X	
			10	8 GB	256 GB CFast MLC	No	NY512-1300-0XX44370X	
			(64	32 GB	256 GB CFast MLC		NY532-1500-011445700
				04	8 GB	128 GB CFast MLC		NY532-1500-011443600
Industrial	Windows 10 IoT Enterprise 2019 LTSC	Intel® Core™	32	32 GB	256 GB CFast MLC	No	NY532-1400-011445700	
Panel PC	64bit	i5-7440EQ	32	8 GB	128 GB CFast MLC	No	NY532-1400-011443600	
			16	32 GB	256 GB CFast MLC		NY532-1300-011445700	
				8 GB	128 GB CFast MLC	1	NY532-1300-011443600	

Automation Software Sysmac Studio

Please purchase a DVD and required number of licenses the first time you purchase the Sysmac Studio. DVDs and licenses are available individually. Each model of licenses does not include any DVD.

Product name	Specifications	Number of licenses	Media	Model
Sysmac Studio Standard Edition Ver.1.	The Sysmac Studio is the software that provides an integrated environment for setting, programming, debugging and maintenance of machine automation controllers including the NJ/NX-series CPU Units, NY-series Industrial PC, EtherCAT Slave, and the HMI. The Sysmac Studio Standard Edition DVD includes Support Software to set up EtherNet/IP Units, DeviceNet slaves, Serial Communications Units, and Support Software for creating screens on HMIs (CX-Designer).	 (Media only)	Sysmac Studio (32-bit) DVD	SYSMAC-SE200D
		(Media only)	Sysmac Studio (64-bit) DVD	SYSMAC-SE200D-64
		1 license *		SYSMAC-SE201L

* Multi licenses are available for the Sysmac Studio (3, 10, 30, or 50 licenses).

Note: For details, refer to the Sysmac Studio Ver.1. □□ datasheet, visit your local OMRON website.

Collection of software functional components Sysmac Library

Please download it from following URL and install to Sysmac Studio.

http://www.ia.omron.com/sysmac_library/

Typical Models

Product	Features	Model
Vibration Suppression Library	The Vibration Suppression Library is used to suppress residual vibration caused by the operation of machines.	SYSMAC-XR006
Device Operation Monitor Library	The Device Operation Monitor Library is used to monitor the operation of devices such as air cylinders, sensors, motors, and other devices.	SYSMAC-XR008
Dimension Measurement Library	The Dimension Measurement Library is used to dimension measurement with ZW-7000/5000 Confocal Fiber Displacement Sensor, or E9NC-TA0 Contact-Type Smart Sensor.	SYSMAC-XR014

Accessories

Optional Hardware

Product name	Specifications	Model
	Book mount	NY000-AB00
	W II	NY000-AB05
	Wall mount	NY000-AB01
	VESA mount	NY000-AB06
Mounting Brackets *1	VESA mount	NY000-AB07
3	VESA mount	NY000-AB08
	VESA mount	NY000-AB09
	VESA mount	NY000-AB10
	VESA mount	NY000-AB11
	VESA mount handle	NY000-AB12
	Card type: SD Card Capacity: 2 GB Format: FAT16	HMC-SD292
SD Memory Cards	Card type: SDHC Card Capacity: 4 GB Format: FAT32	HMC-SD492
	Card type: SDHC Card Capacity: 16 GB Format: FAT32	HMC-SD1A2
	Capacity: 2 GB	FZ-MEM2G
USB Flash Drives	Capacity: 8 GB	FZ-MEM8G
	Storage type: HDD Capacity: 320 GB	NY000-AH00 *3
	Storage type: SSD SLC Capacity: 32 GB	NY000-AS00 *3
	Storage type: SSD SLC Capacity: 64 GB	NY000-AS01
Storage Devices	Storage type: SSD SLC Capacity: 64 GB	NY000-AS03
Ctorage Zevices	Storage type: SSD MLC Capacity: 128 GB	NY000-AS04
	Storage type: SSD 3DTLC Capacity: 1 TB	NY000-AS07
	Storage type: CFast MLC Capacity: 128 GB	NY000-AT01
	Storage type: CFast MLC Capacity: 256 GB	NY000-AT02
DVI Cables	Cable length: 2 m Supports DVI-D Minimum bend radius: 36 mm	NY000-AC00 2M
SVI Gubics	Cable length: 5 m Supports DVI-D Minimum bend radius: 36 mm	NY000-AC00 5M
Industrial Monitor	LCD touchscreen Multi-touch functionality Supply voltage: 24 VDC Up to 1,280 x 800 pixels at 60 Hz USB Type-A Connectors Programmable brightness control Standard and 100 m cable models are available.	NYM1□W-C1□□□
	Output voltage: 24 VDC Push-In Plus terminal blocks	S8VK-G□□□24
Power Supply	Output voltage: 24 VDC EtherNet/IP, Modbus TCP-Compatible	S8VK-X□□□24A-EIP
	Output voltage: 24 VDC Compact Output voltage: 24 VDC	S8VK-S□□24
IIDC #2	Output voltage: 24 VDC Three-phase 200-V Power Supplies Output voltage during backup operation: 24 VDC ± 5%	S8VK-WA□□□24
UPS *2	Output voltage during backup operation. 24 VDC ± 5%	JODA

Product name	Specifications	Model
UPS Communication Cable	Cable length: 2 m Signals for • Signal output (BL, TR, BU, WB) • Remote ON/OFF input • UPS Stop Signal input (BS)	S8BW-C02

Note: Orders for NY000-AS02 are no longer accepted, as of November 30, 2018.

*1. Select the required type below. Industrial Box PC type only. NY000-AB00: for NY51□-1□00-1□ NY000-AB05: for NY51□-1□00-0□

Select the required type below. Industrial Panel PC and Industrial Monitor type only.

NY000-AB06: for NYM12W NY000-AB07: for NYM15W NY000-AB08: for NYM19W

NY000-AB09: for NY53\[-1\[00-0\[1\] 4 NY000-AB10: for NY53\[-1\[00-0\[2\] 4 NY000-AB11: for NY53 -1 00-0 3 4 NY000-AB12 Handle for AB06 to AB11

*2. Revision number 04 or higher.

The revision number of the UPS can be retrieved from the serial number label on the product and the product packaging.

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1	2	3	4

Item	Description
1	Product code
2	Product period and sequential number
3	Revision number
4	RoHS status

*3. End of Life: only available for support purpose

Spare Parts

The following spare parts for the Industrial PC are available.

Product name	Specifications	Model
Battery	One battery is supplied with the Industrial PC. The battery supplies power to the real-time clock. The battery is located inside the Industrial PC. Service life: 5 years at 25°C	CJ1W-BAT01
Fan Unit	The Fan Unit is available for the Industrial PC that has active cooling. Service life: 70,000 hours of continuous operation at 40°C with 15% to 65% relative humidity. Shelf life: 6 months This is the storage limitation with no power supplied.	NY000-AF00
Accessory Kit	Replacement kit containing all accesories supplied with Industrial PC. • Power connector • I/O connector • Drive bracket for drive installation • 4 mounting screws for drive installation • PCIe Card support for PCIe Card installation • PCIe Card clip for PCIe Card installation	NY000-AK00
	Power connectors (10 pcs) for Industrial Box PC and Industrial Panel PC	NY000-AK01

Installed Support Software

Item	Specifications
Industrial PC Support Utility	The Industrial PC Support Utility is a software utility to assist in diagnosing and resolving problems of the Industrial PC. It is pre-installed on the Industrial Box PC and the Industrial Panel PC.
Industrial PC Tray Utility	The Industrial PC Tray Utility is a software utility that provides information about the current state of the Industrial PC, its related devices, and associated software. It is pre-installed on the Industrial Box PC and the Industrial Panel PC.
Industrial PC System API	The Industrial PC System API allows programmers to create programs that can retrieve information or set an indicator status of the Industrial PC. The API makes use of the included IPC System Service to manage the hardware. It is pre-installed on the Industrial Box PC and the Industrial Panel PC.
Industrial Monitor Utility	The Industrial Monitor Utility provides a user interface to control settings and display details of connected Industrial Monitors. It is pre-installed on the Industrial Box PC and the Industrial Panel PC.
Industrial Monitor Brightness Utility	The Industrial Monitor Brightness Utility is a small software utility that allows you to control the brightness of the screen backlight of all connected Industrial Monitors. It is pre-installed on the Industrial Box PC and the Industrial Panel PC.
Industrial Monitor API	The Industrial Monitor API allows programmers to create applications that can control the hardware features and retrieve information from connected Industrial Monitors. It is pre-installed on the Industrial Box PC and the Industrial Panel PC.
Industrial PC Rescue Disk Creator	The Industrial PC Rescue Disk Creator creates a USB Rescue Disk which can be used to back-up and restore the Omron IPC Operating System. It is pre-installed on the Industrial Box PC and the Industrial Panel PC.

Recommended EtherCAT and EtherNet/IP Communications Cables

Use a straight STP (shielded twisted-pair) cable of category 5 or higher with double shielding (aluminum tape and braiding) for EtherCAT. For EtherNet/IP, required specification for the communications cables varies depending on the baud rate.

For 100BASE-TX/10BASE-T, use a straight or cross STP (shielded twisted-pair) cable of category 5 or higher.

For 1000BASE-T, use a straight or cross STP cable of category 5e or higher with double shielding (aluminum tape and braiding).

Cabel with Connectors

Item	Appearance	Recommended manufacturer	Cable length (m)	Model
			0.3	XS6W-6PUR8SS30CM-YF
Cable with Connectors on Both Ends (RJ45/RJ45)			0.5	XS6W-6PUR8SS50CM-YF
Standard RJ45 plugs type *1		OMRON	1	XS6W-6PUR8SS100CM-YF
Wire Gauge and Number of Pairs: AWG26, 4-pair Cable Cable Sheath material: PUR		OWRON	2	XS6W-6PUR8SS200CM-YF
Cable color: Yellow *2	4		3	XS6W-6PUR8SS300CM-YF
			5	XS6W-6PUR8SS500CM-YF
			0.3	XS5W-T421-AMD-K
Cable with Connectors on Both Ends (RJ45/RJ45)	7771860	OMRON	0.5	XS5W-T421-BMD-K
Rugged RJ45 plugs type *1	*6		1	XS5W-T421-CMD-K
Wire Gauge and Number of Pairs: AWG22, 2-pair Cable			2	XS5W-T421-DMD-K
Cable color: Right blue			5	XS5W-T421-GMD-K
			10	XS5W-T421-JMD-K
	7000	OMRON	0.5	XS5W-T421-BM2-SS
Cable with Connectors on Both Ends (M12 Straight/M12 Straight)			1	XS5W-T421-CM2-SS
Shield Strengthening Connector cable *3 M12/Smartclick Connectors			2	XS5W-T421-DM2-SS
Wire Gauge and Number of Pairs: AWG22, 2-pair Cable			3	XS5W-T421-EM2-SS
Cable color: Black			5	XS5W-T421-GM2-SS
			10	XS5W-T421-JM2-SS
			0.5	XS5W-T421-BMC-SS
Cable with Connectors on Both Ends (M12 Straight/RJ45) Shield Strengthening Connector cable *3			1	XS5W-T421-CMC-SS
M12/Smartclick Connectors	15	OMRON	2	XS5W-T421-DMC-SS
Rugged RJ45 plugs type	00	OWINON	3	XS5W-T421-EMC-SS
Wire Gauge and Number of Pairs: AWG22, 2-pair Cable Cable color: Black			5	XS5W-T421-GMC-SS
			10	XS5W-T421-JMC-SS

^{*1.} Cables with standard RJ45 plugs are available in the following lengths: 0.2 m, 0.3 m, 0.5 m, 1 m, 1.5 m, 2 m, 3 m, 5 m, 7.5 m, 10 m, 15 m, 20 m. Cables with rugged RJ45 plugs are available in the following lengths: 0.3 m, 0.5 m, 1 m, 2 m, 3 m, 5 m, 10 m, 15 m. For details, refer to the *Industrial Ethernet Connectors Catalog* (Cat. No. G019).

Cables / Connectors

	Item	Recommended manufacturer	Model	
Products for EtherCAT or EtherNet/IP	Wire Gauge and Number of	Cables	Hitachi Metals, Ltd.	NETSTAR-C5E SAB 0.5 × 4P CP *1
(1000BASE-T *3/ 100BASE-TX)	Pairs: AWG24, 4-pair Cable		Kuramo Electric Co.	KETH-SB *1
		RJ45 Connectors	Panduit Corporation	MPS588-C *1
	Wire Gauge and Number of Pairs: AWG22, 2-pair Cable	Cables	Kuramo Electric Co.	KETH-PSB-OMR *2
		Cables	JMACS Japan Co., Ltd.	PNET/B *2
Products for EtherCAT or EtherNet/IP (100BASE-TX/10BASE-T)		RJ45 Assembly Connector	OMRON	XS6G-T421-1 *2

^{*1.} We recommend you to use above Cable, and RJ45 Connector together.

Note: Connect both ends of cable shielded wires to the connector hoods.

^{*2.} Cable colors are available in yellow, green, and blue.

^{*3.} For details, contact your OMRON representative.

^{*2.} We recommend you to use above Cable, and RJ45 Assembly Connector together.

^{*3.} The products can be used only with thes NX701.

Specifications

Performance Specifications Supported by NY5□□-1

ltem -			NY5□□-			
		item		15□□	14□□	13□□
Processing	Instruction	LD instruction		0.33 ns		
time	execution times	Math instructions	Math instructions (for Long Real Data)			
		Size		40 MB		
	Program capacity	Number	POU definition	3,000		
		Number	POU instance	24,000		
Programming		No retain	Size	64 MB		
Frogramming	Variables capacity	attribute	Number	180,000		
	variables capacity	Retain attribute	Size	4 MB		
		Retain attribute	Number	40,000		
	Data type	Number		4,000		
Unit configuration	Maximum number of connectable units	Maximum numbe	r of NX unit on the system	4,096 (on NX series I	EtherCAT slave term	nal)
		Maximum number of controlled axes		Maximum number of The number of contro + The number of sing	lled axes = The numb	er of motion control axes
				64 axes	32 axes	16 axes
	Number of controlled axes		Motion control axes		Maximum number of motion control axes which can be defined. Al motion control function is available.	
					32 axes	16 axes
		Maximum number of used real axes		Maximum number of The Number of used encoder axes.		llowing servo axes and
Motion control			Used motion control servo axes	Maximum number of servo axes which all motion control fun available. The number of used motion control servo axes = The numb motion control axes whose axis type is set to servo axis and a is set to used axis.		axes = The number of
oona o				64 axes	32 axes	16 axes
		Maximum numbe axis control	Maximum number of axes for linear interpolation axis control		4 axes per axes group	
		Number of axes for	circular interpolation axis control	2 axes per axes group		
	Maximum number o	f axes groups		32 axes groups		
	Motion control perio	od		The same control per communications cycle		r the process data
		Number of cam	Maximum points per cam table	65,535 points		
	Cams	data points	Maximum points for all cam tables	1,048,560 points		
		Maximum numbe	r of cam tables	640 tables		
	Position units			Pulses, millimeters, n	nicrometers, nanome	ters, degrees and inches
	Override factors			0.00% or 0.01% to 50	00.00%	

^{*1.} This is the capacity for the execution objects and variable tables (including variable names).

					NY5□□-	
		Item		15□□	14□□	13□□
	Number of port			1		
	Physical layer			10BASE-T/100BASE	-TX/1000BASE-T	
	Frame length			1,514 max.		
	Media access metho	od		CSMA/CD		
	Modulation			Baseband		
	Topology			Star		
	Baud rate			1Gbps (1000BASE-T)	
	Transmission media	а		' `	-pair) cable of Ethernet c	ategory 5. 5e or higher
	Maximum transmiss	sion distance betwe	en Ethernet switch and node	100 m	1 /	3 7 - 7 - 3
	Maximum number o	of cascade connecti	ons	There are no restriction	ons if Ethernet switch is	used.
		Maximum number	r of connections	128		
		Packet interval *2		1 to 10,000 ms in 1.0 Can be set for each of		
		Permissible comr	nunications band *3	20,000 pps including		
Built-in		Maximum number		128		
EtherNet/IP		Tag types		Network variables		
Port	CIP service: Tag		r connection (i.e., per tag set)		status is included in the	tag set)
	data links (Cyclic communications)		Number of tags per connection (i.e., per tag set) Maximum link data size per node		otatao io moladod in tric	rag 55i.)
	,	Maximum number of tag		256		
		Maximum data size per connection		1,444 bytes		
		Maximum number of registrable tag sets		1,444 bytes 128 (1 connection = 1 tag set)		
		Maximum tag set		1,444 bytes	if Controller status is inc	luded in the tag set)
		Multi-cast packet filter *4		Supported.	ii Controller status is inte	nadea in the tag set.)
		•		64 (clients plus serve	r)	
	Cip Message	Class 3 (number of connections) Maximum number of clients that				
	Service: explicit messages	UCMM (non-connection	can communicate at one time Maximum number of servers that	32		
		type)	can communicate at one time	32		
	Maximum number of TCP socket service			30		
	Number of port			1		
	Communications st			IEC 61158 Type12		
	EtherCAT master sp	pecifications		`	k Motion Control compli	ant)
	Physical layer			100BASE-TX		
	Modulation			Baseband		
	Baud rate			100 Mbps (100Base-TX)		
	Duplex mode			Auto		
	Topology			Line, daisy chain, and		
Built-in EtherCAT port	Transmission media			Twisted-pair cable of (double-shielded stra	category 5 or higher ight cable with aluminur	n tape and braiding)
poit	Maximum transmiss		en nodes	100 m		
	Maximum number o			192		
	Range of node addr	ress		1-512		
	Maximum process data size			Inputs: 5,736 bytes Outputs: 5,736 bytes (However, the maxim	um number of process	data frames is 4.)
	Maximum process of	data size per slave		Inputs: 1,434 bytes Outputs: 1,434 bytes		-
	Communications cy	ycle		500 μs to 8 ms (in 25	0-μs increments)	
	Sync jitter			1 μs max.	,	
Unit configuration	Maximum number of connectable Units	Maximum number		4,096 (On EtherCAT	Slave Terminals)	
g	Maximum number o	of Expansion Racks		0		
Internal clock		, , , , , , , , , , , , , , , , , , , ,		At ambient temperatu At ambient temperatu	re of 55°C: -3.5 to +0.5 re of 25°C: -1.5 to +1.5 re of 0°C: -3 to +1 min e	min error per month

^{*2.} Data will be refreshed at the set interval, regardless of the number of nodes.
*3. "pps" means packets per second, i.e., the number of communications packets that can be sent or received in one second.
*4. As the EtherNet/IP port implements the IGMP client, unnecessary multi-cast packets can be filtered by using a switching hub that supports IGMP Snooping.

Some function specifications are common with the NJ/NX-series Machine Automation Controller.

Function Specifications Supported by NY5□□-1

		Item		NY5□□-1
	Function			I/O refreshing and the user program are executed in units that are called tasks. Tasks are used to specify execution conditions and execution priority.
Tasks		Periodically	Maximum number of primary periodic tasks	1
Tasks		executed tasks	Maximum number of periodic tasks	3
			Maximum number of event tasks	32
		Conditionally executed tasks	Execution conditions	When Activate Event Task instruction is executed or when condition expression for variable is met.
		Programs		POUs that are assigned to tasks.
	POU (program	Function blocks		POUs that are used to create objects with specific conditions.
	organization units)	Functions		POUs that are used to create an object that determine unique outputs for the inputs, such as for data processing.
	Programming languages	Types		Ladder diagrams ★1 and structured text (ST)
	Namespaces			A concept that is used to group identifiers for POU definitions.
	Variables	External access of variables	Network variables	The function which allows access from the HMI, host computers, or other Controllers
			Boolean	BOOL
			Bit strings	BYTE, WORD, DWORD, LWORD
			Integers	INT, SINT, DINT,LINT, UINT, USINT, UDINT, ULINT
			Real numbers	REAL, LREAL
		Basic data	Durations	TIME
		types	Dates	DATE
			Times of day	TIME_OF_DAY
			Date and time	DATE_AND_TIME
			Text strings	STRING
	Data types	Derivative data ty	ypes	Structures, unions, enumerations
_			Function	A derivative data type that groups together data with different variable types.
Programming			Maximum number of members	2048
		Structures	Nesting maximum levels	8
			Member data types	Basic data types, structures, unions, enumerations, array variables
			Specifying member offsets	You can use member offsets to place structure members at any memory locations.
			Function	A derivative data type that groups together data with different variable types.
		Unions	Maximum number of members	4
			Member data types	BOOL, BYTE, WORD, DWORD, LWORD
		Enumerations	Function	A derivative data type that uses text strings called enumerators to express variable values.
			Function	An array is a group of elements with the same data type. You specify the number (subscript) of the element from the first element to specify the element.
	5.4.4	Array	Maximum number of dimensions	3
	Data type attributes	specifications	Maximum number of elements	65535
			Array specifications for FB instances	Supported.
		Range specificat	ions	You can specify a range for a data type in advance. The data type can take only values that are in the specified range.
	Libraries			User libraries
	Control modes			position control, velocity control, torque control
	Axis types			Servo axes, virtual servo axes, encoder axes, and virtual encoder axes
	Positions that ca	an be managed		Command positions and actual positions
			Absolute positioning	Positioning is performed for a target position that is specified with an absolute value.
Motion		Single-axis position control	Relative positioning	Positioning is performed for a specified travel distance from the command current position.
control	Single avia	position control	Interrupt feeding	Positioning is performed for a specified travel distance from the position where an interrupt input was received from an external input.
	Single-axis		Cyclic synchronous absolute positioning	A positioning command is output each control period in Position Control Mode.
		Single-axis velocity control	Velocity control Cyclic synchronous velocity control	Velocity control is performed in Position Control Mode. A velocity command is output each control period in Velocity Control Mode.
		Single-axis torque control	Torque control	The torque of the motor is controlled.
		OT: OT!! ::		

^{*1.} Inline ST is supported. (Inline ST is ST that is written as an element in a ladder diagram.)

[&]quot;CPU Unit" described in the Function Specifications Supported by NY5 ——1 means "Controller" in the NY Series.

		Item		NY5□□-1
			Starting cam operation	A cam motion is performed using the specified cam table.
			Ending cam operation	The cam motion for the axis that is specified with the input parameter is ended.
			Starting gear operation	A gear motion with the specified gear ratio is performed between a master axis and slave axis.
		Single-axis synchronized	Positioning gear operation	A gear motion with the specified gear ratio and sync position is performed between a master axis and slave axis.
		control	Ending gear operation	The specified gear motion or positioning gear motion is ended.
			Synchronous positioning	Positioning is performed in sync with a specified master axis.
			Master axis phase shift	The phase of a master axis in synchronized control is shifted.
			Combining axes	The command positions of two axes are added or subtracted and the result is output as the command position.
		Single-axis	Powering the servo	The Servo in the Servo Drive is turned ON to enable axis motion.
		manual operation	Jogging	An axis is jogged at a specified target velocity.
			Resetting axis errors	Axes errors are cleared.
			Homing	A motor is operated and the limit signals, home proximity signal, and home signal are used to define home.
			Homing with parameter	Specifying the parameter, a motor is operated and the limit signals, home proximity signal, and home signal are used to define home.
			High-speed homing	Positioning is performed for an absolute target position of 0 to return to home.
	Single-axis		Stopping	An axis is decelerated to a stop at the specified rate.
			Immediately stopping	An axis is stopped immediately.
			Setting override factors	The target velocity of an axis can be changed.
			Changing the current position	The command current position or actual current position of an axis can be changed to any position.
		Auxiliary	Enabling external latches	The position of an axis is recorded when a trigger occurs.
		functions for single-axis control	Disabling external latches	The current latch is disabled.
			Zone monitoring	You can monitor the command position or actual position of an axis to see when it is within a specified range (zone).
			Enabling digital cam switches	You can turn a digital output ON and OFF according to the position of an axis.
			Monitoring axis following error	You can monitor whether the difference between the command positions or actual positions of two specified axes exceeds a threshold value.
Motion control			Resetting the following error	The error between the command current position and actual current position is set to 0.
			Torque limit	The torque control function of the Servo Drive can be enabled or disabled and the torque limits can be set to control the output torque.
			Slave Axis Position Compensation	This function compensates the position of the slave axis currently in synchronized control.
			Cam monitor	Outputs the specified offset position for the slave axis in synchronous control.
			Start velocity	You can set the initial velocity when axis motion starts.
		Multi-axes coordinated control	Absolute linear interpolation	Linear interpolation is performed to a specified absolute position.
			Relative linear interpolation	Linear interpolation is performed to a specified relative position.
			Circular 2D interpolation	Circular interpolation is performed for two axes.
			Axes group cyclic synchronous absolute positioning	A positioning command is output each control period in Position Control Mode.
			Resetting axes group errors	Axes group errors and axis errors are cleared.
			Enabling axes groups	Motion of an axes group is enabled.
			Disabling axes groups	Motion of an axes group is disabled.
	Axes groups		Stopping axes groups	All axes in interpolated motion are decelerated to a stop.
		Auxiliary functions for multi-axes	Immediately stopping axes groups	All axes in interpolated motion are stopped immediately.
		coordinated control	Setting axes group override factors	The blended target velocity is changed during interpolated motion.
			Reading axes group positions	The command current positions and actual current positions of an axes group can be read.
			Changing the axes in an axes group	The Composition Axes parameter in the axes group parameters can be overwritten temporarily.
			Setting cam table properties	The end point index of the cam table that is specified in the input parameter is changed.
		Cams	Saving cam tables	The cam table that is specified with the input parameter is saved in non-volatile memory in the CPU Unit.
	Common items		Generating cam tables	The cam table that is specified with the input parameter is generated from the cam property and cam node.
		Parameters	Writing MC settings	Some of the axis parameters or axes group parameters are overwritten temporarily.
		Parameters	Changing axis parameters	You can access and change the axis parameters from the user program.

		Item		NY5□□-1
				1—
		Count modes		You can select either Linear Mode (finite length) or Rotary Mode (infinite length).
		Unit conversions		You can set the display unit for each axis according to the machine.
		Acceleration/ deceleration	Automatic acceleration/ deceleration control	Jerk is set for the acceleration/deceleration curve for an axis motion or axes group motion.
		control	Changing the acceleration and deceleration rates	You can change the acceleration or deceleration rate even during acceleration or deceleration.
		In-position check	(You can set an in-position range and in-position check time to confirm when positioning is completed.
		Stop method		You can set the stop method to the immediate stop input signal or limit input signal.
		Re-execution of I	motion control instructions	You can change the input variables for a motion control instruction during execution and execute the instruction again to change the target values during operation.
Motion	Auxiliary functions	Multi-execution of (Buffer mode)	of motion control instructions	You can specify when to start execution and how to connect the velocities between operations when another motion control instruction is executed during operation.
control		Continuous axes (Transition mode		You can specify the Transition Mode for multi-execution of instructions for axes group operation.
			Software limits	Software limits are set for each axis.
			Following error	The error between the command current value and the actual current value is monitored for an axis.
		Monitoring	Velocity, acceleration rate,	
		functions	deceleration rate, torque, interpolation velocity, interpolation acceleration rate, and interpolation deceleration rate	You can set and monitor warning values for each axis and each axes group.
		Absolute encoder support		You can use an OMRON 1S-series Servomotor or G5-Series Servomotor with an Absolute Encoder to eliminate the need to perform homing at startup.
		Input signal logic inversion		You can inverse the logic of immediate stop input signal, positive limit input signal, negative limit input signal, or home proximity input signal.
	External interface signals		The Servo Drive input signals listed on the right are used.	Home signal, home proximity signal, positive limit signal, negative limit signal, immediate stop signal, and interrupt input signal.
Unit (I/O) management	EtherCAT slaves	Maximum number of slaves		192
		Communications protocol		TCP/IP, UDP/IP
	Built-in	nerNet/IP port communications	CIDR	The function which performs IP address allocations without using a class (class A to C) of IP address.
			IP Forwarding	The function which forward IP packets between interfaces.
			Packet Filter *2	Check the IP packet, the function to determine whether to receive the source IP address and TCP port number.
			NAT	Function for transfer by converting the two IP address.
			Tag data links	Programless cyclic data exchange is performed with the devices on the EtherNet/IP network.
	EtherNet/IP port		Message communications	CIP commands are sent to or received from the devices on the EtherNet/IP network.
	Internal Port	TCP/IP		Data is sent to and received from any node on Ethernet using the UDP or TCP protocol.
			Socket services	Socket communications instructions are used. File can be read from or written to computers at other Ethernet nodes from
			FTP client	the CPU Unit. FTP client communications instructions are used.
		applications	FTP server	Files can be read from or written to the SD Memory Card in the CPU Unit from computers at other Ethernet nodes.
			SNMP agent	Built-in EtherNet/IP port internal status information is provided to network management software that uses an SNMP manager.
Communications		Supported	Process data communications	A communications method to exchange control information in cyclic communications between the EtherCAT master and slaves. This communications method is defined by CoE.
		services	SDO communications	A communications method to exchange control information in noncyclic event communications between EtherCAT master and slaves. This communications method is defined by CoE.
		Network scannin	g	Information is read from connected slave devices and the slave configuration is automatically generated.
	EtherCAT port	DC (distributed c	lock)	Time is synchronized by sharing the EtherCAT system time among all EtherCAT devices (including the master).
		Packet monitorin	g	The frames that are sent by the master and the frames that are received by the master can be saved. The data that is saved can be viewed with WireShark or other applications.
		Enable/disable se	ettings for slaves	The slaves can be enabled or disabled as communications targets.
		Disconnecting/co		Temporarily disconnects a slave from the EtherCAT network for maintenance, such as for replacement of the slave, and then connects the slave again.
		Supported application protocol	CoE	SDO messages of the CAN application can be sent to slaves via EtherCAT.
	Communications			The following instructions are supported. CIP communications instructions, socket communications instructions, SDO message instructions, FTP client instructions, and Modbus RTU protool instructions.

^{*2.} Internal Port only.

		Item		NY5□□-1
		Function		Events are recorded in the logs.
System	Event logs	Maximum	System event log	2,048
management	Event logs	number of	Access event log	1,024
		events	User-defined event log	1,024
	Online editing	Single		Programs, function blocks, functions, and global variables can be changed
				online. Different operators can change different POUs across a network.
	Forced refreshing		1	The user can force specific variables to TRUE or FALSE.
		Maximum Device variables for EtherCAT		64
		number of forced variables	slaves	04
	MC test run			Motor operation and wiring can be checked from the Sysmac Studio.
	Comphyspining			The project file in the Sysmac Studio and the data in the CPU Unit can I
	Synchronizing			made the same when online.
	Differentiation m	onitoring		Rising/falling edge of contacts can be monitored.
		Maximum numbe	er of contacts	8
		Types	Single triggered trace	When the trigger condition is met, the specified number of samples are taken and then tracing stops automatically.
Debugging		1,500	Continuous trace	Data tracing is executed continuously and the trace data is collected be the Sysmac Studio.
		Maximum number	er of simultaneous data trace	4
		Maximum number	er of records	10,000
		Sampling	Maximum number of sampled variables	192 variables
	Data tracing	Timing of sampli	ina	Sampling is performed for the specified task period, at the specified time
				or when a sampling instruction is executed.
		Triggered traces		Trigger conditions are set to record data before and after an event.
				When BOOL variable changes to TRUE or FALSE Comparison of non BOOL variable with a constant
			Trigger conditions	Comparison Method: Equals (=), Greater than (>), Greater than or equals (≥),
				Less Than (<), Less than or equals (≤), Not equal (≠)
			Delay	Trigger position setting: A slider is used to set the percentage of sampling the force and office the trigger position is made
	Simulation			before and after the trigger condition is met.
	Simulation			The operation of the CPU Unit is emulated in the Sysmac Studio.
		Controller	Levels	Major fault, partial fault, minor fault, observation, and information
	Self-diagnosis	errors i-diagnosis User-defined errors	Maximum number of message languages	9 (Sysmac Studio) 2 (NS-series PT) *3
Reliability				User-defined errors are registered in advance and then records are
functions			Function	created by executing instructions.
			Levels	8 levels
			Maximum number of message languages	9
	Protecting	CPU unit names		When going online to a CPU Unit from the Sysmac Studio, the CPU Ur name in the project is compared to the name of the CPU Unit being connected to.
		tware assets Protection preventing	User program transfer with no restoration information	You can prevent reading data in the CPU Unit from the Sysmac Studio
			CPU unit write protection	You can prevent writing data to the CPU Unit from the Sysmac Studio of SD Memory Card.
Security	software assets and preventing		Overall project file protection	You can use passwords to protect .smc files from unauthorized openin on the Sysmac Studio.
	operating mistakes		Data protection	You can use passwords to protect POUs on the Sysmac Studio.
		Verification of o	peration authority	Online operations can be restricted by operation rights to prevent damage to equipment or injuries that may be caused by operating mistakes.
			Number of groups	5
		V		The user program cannot be executed without entering a user program
		verification of us	ser program execution ID	execution ID from the Sysmac Studio for the specific hardware (CPU Unit
	Location to store			
	Location to store			running.
Memory card	Location to store		eration instructions	running. You can access Memory Cards from instructions in the user program.
		Memory card op	eration instructions	running. You can access Memory Cards from instructions in the user program. You can perform file operations for Controller files in the Memory Card
	Location to store Application	Memory card op	rom the Sysmac Studio	running. You can access Memory Cards from instructions in the user program. You can perform file operations for Controller files in the Memory Card and read/write general-purpose document files on the computer.
		Memory card op		running. You can access Memory Cards from instructions in the user program. You can perform file operations for Controller files in the Memory Card and read/write general-purpose document files on the computer.
		Memory card op	rom the Sysmac Studio	running. You can access Memory Cards from instructions in the user program. You can perform file operations for Controller files in the Memory Card and read/write general-purpose document files on the computer. You can store and read files by the FTP client function and FTP serve
	Application	Memory card op	rom the Sysmac Studio rom FTP Client/Server Using system-defined	running. You can access Memory Cards from instructions in the user program. You can perform file operations for Controller files in the Memory Card and read/write general-purpose document files on the computer. You can store and read files by the FTP client function and FTP serve function.
functions	Application SD memory card backup	Memory card op File operations f	rom the Sysmac Studio rom FTP Client/Server Using system-defined variables	running. You can access Memory Cards from instructions in the user program. You can perform file operations for Controller files in the Memory Card and read/write general-purpose document files on the computer. You can store and read files by the FTP client function and FTP serve function. You can use system-defined variables to backup or compare data.
Memory card functions	Application SD memory	Memory card op File operations f	rom the Sysmac Studio rom FTP Client/Server Using system-defined variables Memory card operations dialog box on Sysmac Studio Using instruction	You can access Memory Cards from instructions in the user program. You can perform file operations for Controller files in the Memory Card and read/write general-purpose document files on the computer. You can store and read files by the FTP client function and FTP server function. You can use system-defined variables to backup or compare data. Backup and verification operations can be performed from the SD
functions Backup	Application SD memory card backup	Memory card op File operations f	rom the Sysmac Studio rom FTP Client/Server Using system-defined variables Memory card operations dialog box on Sysmac Studio	running. You can access Memory Cards from instructions in the user program. You can perform file operations for Controller files in the Memory Card and read/write general-purpose document files on the computer. You can store and read files by the FTP client function and FTP serve function. You can use system-defined variables to backup or compare data. Backup and verification operations can be performed from the SD Memory Card Operations Dialog Box on the Sysmac Studio.

^{*3.} NS-series PT is no longer available to order.

Performance Specifications

	Iter	n		NY5□□-1□00-0□□□4	NY5□□-1□00-1□□□4		
		CPU type		Intel [®] Core [™] i5-7440EQ			
		Cores / Threa	ids	4 / 4			
	CPU base free		quency	2.9 GHz			
	CPU	Cache		6 MB			
		Cooling detail	ils	Requires active cooling (fan)			
	Intel CPU category		Industrial (100% operation minimal 10y	rr)			
lain system	Memory size *1		8 or 32 GB	,			
	Memory type		DDR4 (non ECC)				
	Trusted platfori			Available			
		(-/	Intel® HD Graphics. Up to two independ	dent screens		
	Graphics contro	oller		Intel® HD Graphics 630			
	Watchdog			Yes			
Operating system	Windows OS			Windows 10 IoT Enterprise 2019 LTSC	- 64 hit		
perating system	Williaows O3	Hard disk dri		Willdows 10 101 Effetphise 2019 E13C	- 04 Dit		
		riaiu uisk uii	ve		64 GB		
			SLC type		Serial ATA 3.1		
	Drives *1	Solid state		128 GB, 256 GB	128 GB		
Storage devices		drive	MLC type	Serial ATA 3.1 CFast	Serial ATA 3.1		
			3DTLC type		1 TB		
			ob i Lo type		Serial ATA 3.1		
	Drive bay (HDD	Drive bay (HDD/SSD) *2		CFast slot	2		
	Power connector			24 VDC			
	I/O connector			2 inputs (Power ON/OFF Input and UPS Mode Input) and 1 output (Power Status Output			
	USB 2.0 Type-A Maximum curr		orts	2			
			rrent	500 mA			
	31	Maximum cable length		5 m			
		ISB 3.0 Yppe-A Maximum current Maximum cable length		2			
Connectors				900 mA			
	.,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,			3 m			
	Ethernet	rnet Number of available ports		3			
	connectors	nnectors Physical layer		10BASE-T, 100BASE-TX or 1000BASE-T			
		Video interface		Digital or analog			
	DVI-I Resolution			Up to 1,920 x 1,200 pixels at 60 Hz			
	Connector	Maximum DV	I cable length	Dependent upon connected monitor type and resolution			
	RS-232C				Standard SUBD9 connector (Non-Isolated		
		Video interfa	ce		Digital only		
	D)// D	Resolution			Up to 1,920 x 1,200 pixels at 60 Hz		
Optional	DVI-D	Maximum DV	I cable length		Dependent upon connected monitor type and resolution		
connector (select		Video interfa	ce	Digital only			
one per system)		Resolution		1,280 x 800 pixels at 60 Hz			
	NY Monitor	Connector ty	pe	RJ45			
	Link	Cable shieldi max. length	•	S/FTP, Cat.6A, 100m			
		USB data thre	oughput	280 Mbps max.			
	Configuration				X4 (4 lanes) up to Gen 3		
PCIe Card Slot	Card height				Standard height cards, 4.20 inches (106.7 mm) *3		
	Card length				Half length cards, 6.6 inches (167.65 mm		
	Model			CJ1W-BAT01			
Battery	Service life			5 years at 25°C			
				NY000-AF00			
	Model		NY000-AF00 70,000 hours of continuous operation at 40°C with 15% to 65% relative humidity				
an unit	Service life				t 40°C with 15% to 65% relative humidity		

^{*1.} Not all combinations are possible or standard available. Please contact your Omron representative to dicuss the possibilities.

^{*2.} Depending on the model one or two drives are supported. ***3.** Low profile cards, 2.536 inches (64.4 mm) are not supported.

Display Specifications

	ltem -			Specifications			
			12.1 Inch models	15.4 Inch models	18.5 inch models		
		Display device	TFT LCD				
	Screen size	12.1 inches	15.4 inches	18.5 inches			
	Surface treatment	Anti glare treatment					
		Surface hardness	Mohs scale: 5 - 6				
		Resolution	1,280 × 800 pixels at 60 Hz (horizontal × vertical)		1,920 × 1,080 pixels at 60 Hz (horizontal × vertical)		
		Ratio	16 × 10		16 × 9		
Display panel *1		Colors	16,770,000 colors		·		
	*1	Effective display area	261 × 163 mm (horizontal × vertical)	331 × 207 mm (horizontal × vertical)	409 × 230 mm (horizontal × vertical)		
		View angles	Left: 60°, Right: 60°, Top: 60°, Bottom: 60°		Left: 89°, Right: 89°, Top: 89°, Bottom: 89°		
Display		Typical LCD Brightness (initial)	1500 cd/m ²	400 cd/m ²	500 cd/m ²		
		Life	50,000 hours min. * 2				
		Brightness adjustment	200 levels *3				
		Technology	Projected capacitive				
		Touch resolution	Touch accuracy 1.5% (4-5 m	m)			
	Touch	Multitouch	Up to 5 simultaneous touches	s			
	Touch	Features	Water detection *4, hand pa	lm rejection * 5, gloves * 6			
		Life	50,000,000 operations min.				
		EMC	Correct touchscreen operation	n is possible within allowable EMC im	nmunity conditions		
	Front	Material	Aluminium				
	housing	Finish *7	Black paint		Black paint or Nickel plating		

Note: Industrial Panel PC type only.

The life expectancy is drastically shortened if used at high temperatures.

- *3. If the brightness is set to very dark, it causes flickering or the screen will be too dark to use.
- ***4.** If water is detected the touch functionality will not be available.
- ***5.** If a palm is detected that specific area is neglected.
- *6. The touchscreen can be operated when wearing gloves. Check correct usage of the gloves before using them.
- *7. Black paint:

Industrial paint based on durable polyester resin with very high weathering resistance characteristics. Matt black - matching RAL9005. Nickel Plating:

A product with 'Material Finish' being 'Aluminium, Nickel Plated' conforms to ASTM B733-15, SC2.

The nature of nickel plating on our frames can show light disturbance on the surface.

^{*1.} There may be some defective pixels in the display. This is not a fault as long as the numbers of defective light and dark pixels fall within the following standard range: light and dark pixels 10 or less. (There must not be 3 consecutive light/dark pixels.)

*2. This is the estimated time before brightness is reduced by half at room temperature and humidity.

Electrical Specifications

			NY51□- 1□00-0□□□4	NY51 - 1 00-1 4	NY53□- 1□00-0□1□4 NY53□- 1□00-0□2□4	NY53□- 1□00-0□3□4	
			Intel [®] Core™ i5-7440EQ				
Rated power supply voltage			24 VDC, non-isolated				
Allowable power supply voltage range			20.4 to 28.8 VDC				
Grounding me	thod		Ground to less than 100 g	Ω			
Inrush current			At 24 VDC: 12 A / 6 ms m	nax. for cold start at room to	emperature		
Overvoltage ca	ategory		JIS B3502 and IEC 6113	1-2: Category II		_	
EMC immunity	/ level		IEC 61131-2: Zone B				
RTC accuracy			At ambient temperature of 55°C: -3.5 to +0.5 min error per month At ambient temperature of 25°C: -1.5 to +1.5 min error per month At ambient temperature of 0°C: -3 to +1 min error per month				
Power button	life		100,000 operations				
Battery life			5 years at 25°C (for battery CJ1W-BAT01)				
Fan life			8 years of continuous operation at 40°C				
		wer consumption ves and expansions	85 W	106 W	101 W	123 W	
	Maximum power consumption excluding drives and expansions		70 W	73W	86 W	108 W	
		SSD SLC 32 GB	_	-		_	
Power		SSD SLC 64 GB	_	2 W		_	
consumption *	Daire	SSD MLC 128 GB	_	2 W		_	
*	Drives	SSD 3DTLC 1 TB	-	3 W		_	
		CFast MLC 128 GB	1 W	-	1 W	-	
		CFast MLC 256 GB	1 W	-	1 W		
	F	USB	14 W max. ((2 x 500 mA	at 5 V) + (2 x 900 mA at 5 \	V))		
	Expansions	PCle	-	15 W max.		_	

Note: Refer to the NY-series IPC Machine Controller Industrial Panel PC Hardware User's Manual (W557) or the NY-series IPC Machine Controller Industrial Box PC Hardware User's Manual (W556) for detail.

* The total power consumption is the sum of the power consumption of all items that are installed in your Industrial PC.
To guarantee S8BA UPS operation in combination with our IPC, the specified combination of UPS and power-supply must be used.

Item	Minimum power requirements			
Power supply	240 W	240 W	240 W	240 W
UPS	120 W	120 W	120 W	240 W

Environmental Specifications

	Item	Specifi	cations		
	item	Industrial Box PC	Industrial Panel PC		
	Ambient operating temperature *1	0 to 55°C			
	Ambient storage temperature *1	-20 to 70°C			
	Ambient operating humidity *1	10% to 90% with no condensation			
	Ambient storage humidity *1	10% to 90% with no condensation			
	Operating atmosphere	No corrosive gases			
	Altitude	2,000 m max.			
	Noise resistance (during operation)	Conforms to IEC61000-4-4, 2 kV (power lines)			
Operation environment	Vibration resistance (during operation)	Conforms to IEC 60068-2-6. • For a Box PC with an SSD: 5 to 8.4 Hz with 3.5 mm single amplitude and 8.4 to 150 Hz with 9.8 m/s² for 10 times each in X, Y and Z directions. • For a Box PC with a HDD the vibration resistance depends on the mounting orientation *2.	The vibration resistance depends on the storage device(s): • For a Panel PC with only SSD storage devices: 5 to 8.4Hz with 3.5 mm single amplitude and 8.4 to 150 Hz with 9.8 m/s² for 10 times each in X, Y and Z directions. Conforms to IEC 60068-2-6. • For a Panel PC with one or more HDD storage devices the Panel PC must be installed in a vibration free environment. *3		
	Shock resistance (during operation)	Conforms to IEC 60068-2-27. 147 m/s², 3 times in each X, Y and Z directions			
	Installation method	Book mount, Wall mount	Mount on panel		
	Degree of protection *4	_	Front of Monitor: IP65		
	Pollution degree	2 or less: Meets IEC 61010-2-201.			
Applicable sta	ndards *5	EU Directives: EMC Directive 2014/30/EU (EN 61131-2) and RoHS Directive KC Registration, RCM, cULus, EAC			

^{*1.} The allowed ambient operating temperature and ambient humidity depend on product type, CPU type, mounting orientation, and storage device type. ***2.** Vibration resistance depends on the Box PC's mounting orientation and storage device type.

Mounting Orientation	SSD	HDD	
Book	9.8 m/s ²	2.5 m/s ²	
Wall	9.0 11// 5	4.9 m/s ²	

***3.** A Panel PC with one or more HDD storage devices should not be used in applications subject to vibration.

Examples of applications subject to vibration:

AGV (Automated Guided Vehicles)

Tableting machine

· Rail vehicle

· Connector pin assembling machine

· Stacker crane

· Bending machine

Elevator

Ensure your Panel PC with HDD does not vibrate. When in doubt use a Panel PC with SSD storage devices.

*4. The Panel PC may not operate properly in locations subjected to oil splashes for extended periods of time. (Industrial Panel PC type only)

*5. Refer to the OMRON website (www.ia.omron.com) or contact your OMRON representative for the most recent applicable standards for each model.

Storage Device Specifications

Item		Specifications							
Model	NY000-AS00 *4	NY000-AS01	NY000-AS03	NY000-AS04	NY000-AS07	NY000-AH00 *1*4	NY000-AT01	NY000-AT02	
Capacity	32 GB	64 GB	64 GB	128 GB	1 TB	320 GB	128 GB	256 GB	
Туре	SSD (SLC)			SSD (MLC)	SSD (3DTLC)	HDD	CFast (MLC)		
S.M.A.R.T. support	Yes								
Rotation speed			-			5,400 r/min –		_	
Interface	Serial ATA 3.1					Serial ATA 3.0	Serial ATA 3.1		
Sustained standard read speed	Up to 160 MB/s		Up to 500 MB/s	Up to 530 MB/s	Up to 550 MB/s	-	Up to 530 MB	's	
Sustained standard write speed	Up to 150 MB/s		Up to 370 MB/s	Up to 190 MB/s	Up to 340 MB/s	_	Up to 190 MB/s	Up to 210 MB/s	
Operating temperature	0 to 70°C					5 to 55°C	-40 to 85°C		
Operating humidity	10% to 95% (with no		10% to 85% (with no condensation)	10% to 95% (with no condensation)		10% to 95% (with no condensation) 29°C wet-bulb temperature max.	10% to 95% (with no condensation)		
Storage temperature	-40 to 100°C		-45 to 90°C	-55 to 95°C		-40 to 65°C	-55 to 95°C		
Storage humidity	10% to 95% (with no condensation)					8% to 90% (with no condensation) 40°C wet-bulb temperature max.	10% to 95% (with no conde	ensation)	
Life	1,500 TB written	3,000 TB written	1,900 TB written	temperature max. Approximately 5 years or 20,000 powered-ON hours (whichever comes first) under the following conditions: 26°C at 101.3 kPa Less than 333 powered ON hours/month \$2 Less than 20% operation while powered-ON \$3 Less than 1.30 x 106 seeks/month		208 TB written	417 TB written		

Note: Orders for NY000-AS02 are no longer accepted, as of November 30, 2018.

*1. For a Panel PC with an HDD: this device can only be installed in a vibration free environment only.

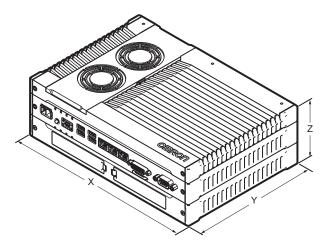
*2. Powered-ON hours include sleep and standby modes.

*3. Operation includes seeking, writing, and reading functions.

*4. End of Life: only available for support purpose

Dimensions

Industrial Box PC type

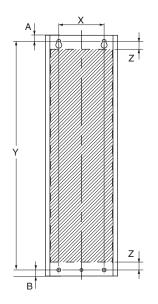


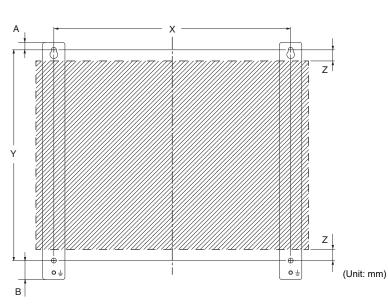
Item	NY51□-1□00-1	NY51□-1□00-0
Dimensions	Width X = 282 mm Depth Y = 195 mm. Y = 200 mm including the DVI connectors. Height Z = 88.75 mm	Width X = 282 mm Depth Y = 195 mm. Y = 200 mm including the DVI connectors. Height Z = 56 mm
Weight	3.8 kg	2.6 kg

Bracket Specifications

The metal mounting brackets mount your Industrial Box PC and they are the connection for the functional ground. Use metal screws with a diameter of 4 mm or 5 mm to mount the brackets.

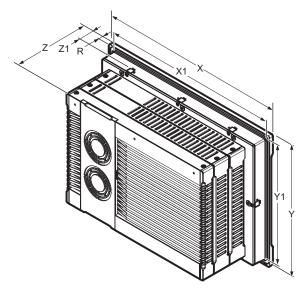
Mounting screw locations for book mount and wall mount orientation:





			Drill Specifications			Product Dimensions			
Model	Bracket type	Bracket ID	Hole Distance X	Hole Distance Y	Distance Z	Bracket Width	Bracket Height	Top to hole A	Top to hole B
All	Wall mount	NY000-AB01	245 mm	218 mm	12 mm	23 mm	245 mm	7.5 mm	19.5 mm
NY51	Book mount	NY000-AB00	60 mm	303 mm	11 mm	96 mm	319 mm	8 mm	8 mm
NY51	Book mount	NY000-AB05	25 mm	303 mm	11 mm	63 mm	339 mm	8 mm	28 mm

Industrial Panel PC type

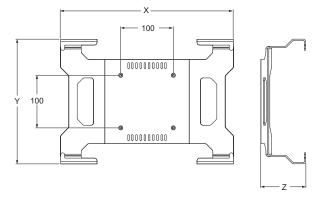


	Specifications							
Item	12.1	Inch	15.4	Inch	18.5 inch			
	NY53□-1□00-1	NY53□-1□00-0	NY53□-1□00-1	NY53□-1□00-0	NY53□-1□00-0			
Panel cutout dimensions	Cutout Width X1 = 3° Cutout Height Y1 = 2°		Cutout Width X1 = 3 Cutout Height Y1 = 2		Cutout Width X1 = 463 ⁻⁰ +1 mm Cutout Height Y1 = 285 ⁻⁰ +1 mm			
Panel thickness range *	Panel thickness rang	Panel thickness range Z1 = 1.6 to 6.0 mm						
Dimensions	Width X = 332 mm Width X = 332 mm Width X = 401 mm Depth Z = 277 mm Height Y = 277 mm Height Y = 277 mm Height Y = 277 mm Depth Z = 121				Width X = 482 mm Height Y = 304 mm Depth Z = 88 mm			
Monitor thickness in front of panel	Rim thickness R = 8.0 mm							
Weight	6.1 kg	5.1 kg	7.2 kg	6.0 kg	7.0 kg			

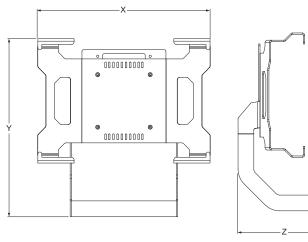
^{*}The minimum panel thickness depends on the panel material.

Bracket Specifications

Without handle



With handle NY000-AB12



	Bracket type	Bracket ID	Without handle			With handle NY000-AB12		
Model			Bracket width X	Bracket height Y	Bracket depth Z	Bracket width X	Bracket height Y	Bracket depth Z
NYM12W	Vesa mount	NY000-AB06	328 mm	237 mm	86 mm	328 mm	339 mm	164 mm
NYM15W	Vesa mount	NY000-AB07	397 mm	280 mm	86 mm	397 mm	381 mm	164 mm
NYM19W	Vesa mount	NY000-AB08	478 mm	306 mm	83 mm	478 mm	409 mm	164 mm
NY53□-1□00-0□1□4	Vesa mount	NY000-AB09	328 mm	237 mm	118 mm	328 mm	339 mm	164 mm
NY53□-1□00-0□2□4	Vesa mount	NY000-AB10	397 mm	280 mm	118 mm	397 mm	381 mm	164 mm
NY53□-1□00-0□3□4	Vesa mount	NY000-AB11	478 mm	306 mm	98 mm	478 mm	409 mm	164 mm

Version Information

Unit Versions

Units	Models	Unit Version
IDC Machine Controller	NY5□2-1□00-□□□□1	Unit version 1.12 or later
IPC Machine Controller	NY5□2-1□00-□□□44	Unit version 1.24 or later

Unit Versions and Programming Devices Supported by NY5□□-1/NY5□□-5

The following tables show the relationship between unit versions and Sysmac Studio versions.

Unit Versions and Programming Devices

Unit Version *	Corresponding version of Sysmac Studio
1.26	1.46 or higher
1.24	1.45 or higher
1.21	1.29 or higher
1.19	1.24 or higher
1.18	1.23 or higher
1.10	1.22 or higher
1.16	1.20 or higher
1.14	1.19 or higher
1.14	1.18 or higher
1.12	1.17 or higher

* There is no NY5 2-1 00- 1 with unit version 1.11 or earlier.

There is no NY5 2-1 00- 1 with unit version 1.19. There is no NY5 2-1 00- 44 with unit version 1.24 or earlier.

Note: If you use a lower version of the Sysmac Studio, you can use only the functions of the unit version of the unit that corresponds to the Sysmac

Studio version.

If you use a unit with an earlier version, select the unit version of the connected unit or an earlier unit version in the Select Device Area of the Project Properties Dialog Box on the Sysmac Studio. You can use only the functions that are supported by the unit version of the connected unit.

Functions That Were Added or Changed for Each Unit Version

- · Additions and Changes to Basic Instructions and Motion Control Instructions For details, refer to the NY-series Instructions Reference Manual (Cat. No. W560) and NY-series Motion Control Instructions Reference Manual (Cat. No. W561).
- · Additions and Changes to Controller Events For details, refer to the NY-series Troubleshooting Manual (Cat. No. W564).
- · Additions and Changes to System-defined Variables For details, refer to the NY-series IPC Machine Controller Industrial Panel PC / Industrial Box PC Software User's Manual (Cat. No. W558).

Related Manuals

Refer to the *Related Manuals* in the data sheet of the NY-series Industrial Box PC or NY-series Industrial Panel PC for the Related Manuals.

Manual name	Cat. No.	Model numbers	Application	Description
Industrial Panel PC User's Manual	W555	NYP27	Learning all basic information about the Industrial Panel PC. This includes introductory information with features, hardware overview, software overview, specifications, mounting, wiring, connecting, operating and maintaining the Industrial Panel PC.	An introduction to the Industrial Panel PC is provided along with the following information: Overview Hardware Software Specifications Installation Operating Procedures Maintenance
NY-series IPC Machine Controller Industrial Panel PC Hardware User's Manual	W557	NY532-□□□□	Learning the basic specifications of the NY-series Industrial Panel PCs, including introductory information, designing, installation, and maintenance. Mainly hardware information is provided.	An introduction to the entire NY-series system is provided along with the following information on the Industrial Panel PC. • Features and system configuration • Introduction • Part names and functions • General specifications • Installation and wiring • Maintenance and inspection
NY-series IPC Machine Controller Industrial Box PC Hardware User's Manual	W556	NY512-000	Learning the basic specifications of the NY-series Industrial Box PCs, including introductory information, designing, installation, and maintenance. Mainly hardware information is provided.	An introduction to the entire NY-series system is provided along with the following information on the Industrial Box PC. • Features and system configuration • Introduction • Part names and functions • General specifications • Installation and wiring • Maintenance and inspection
NY-series IPC Machine Controller Industrial Panel PC / Industrial Box PC Setup User's Manual	W568	NY532-000 NY512-000	Learning the initial settings of the NY-series Industrial PCs and preparations to use Controllers.	The following information is provided on an introduction to the entire NY-series system. • Two OS systems • Initial settings • Industrial PC Support Utility • NYCompolet • Industrial PC API • Backup and recovery
NY-series IPC Machine Controller Industrial Panel PC / Industrial Box PC Software User's Manual	W558	NY532-000 NY512-000	Learning how to program and set up the Controller functions of an NY- series Industrial PC.	The following information is provided on NY- series Machine Automation Control Software. • Controller operation • Controller features • Controller settings • Programming based on IEC 61131-3 language specifications
NY-series Instructions Reference Manual	W560	NY532-000 NY512-000	Learning detailed specifications on the basic instructions of an NY- series Industrial PC.	The instructions in the instruction set (IEC 61131-3 specifications) are described.
NY-series IPC Machine Controller Industrial Panel PC / Industrial Box PC Motion Control User's Manual	W559	NY532 NY512	Learning about motion control settings and programming concepts of an NY-series Industrial PC.	The settings and operation of the Controller and programming concepts for motion control are described.
NY-series Motion Control Instructions Reference Manual	W561	NY532-000 NY512-000	Learning about the specifications of the motion control instructions of an NY-series Industrial PC.	The motion control instructions are described.
NY-series IPC Machine Controller Industrial Panel PC / Industrial Box PC Built-in EtherCAT® Port User's Manual	W562	NY532-000 NY512-000	Using the built-in EtherCAT port in an NY-series Industrial PC	Information on the built-in EtherCAT port is provided. This manual provides an introduction and provides information on the configuration, features, and setup.
NY-series IPC Machine Controller Industrial Panel PC / Industrial Box PC Built-in EtherNet/IP TM Port User's Manual	W563	NY532-000 NY512-000	Using the built-in EtherNet/ IP port in an NY-series Industrial PC.	Information on the built-in EtherNet/IP port is provided. Information is provided on the basic setup, tag data links, and other features.
NY-series Troubleshooting Manual	W564	NY532 NY512	Learning about the errors that may be detected in an NY-series Industrial PC.	Concepts on managing errors that may be detected in an NY-series Controller and information on individual errors are described.
Sysmac Studio Version 1 Operation Manual	W504	SYSMAC-SE2	Learning about the operating procedures and functions of the Sysmac Studio.	Describes the operating procedures of the Sysmac Studio.
UPS S8BA User's Manual	U702	S8BA	Learning the information that is necessary to use the Uninterruptible Power Supply (UPS) Unit.	An introduction to the UPS is provided along with the following information: Overview Preparation Installation and Connection Check and Start Operation Maintenance and Inspection Shutdown Processing I/O Signal Functions Troubleshooting

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